

A EM-algorithm to fit LDFA-H (Section 2)

Initialization Let $\hat{\theta}^{(0)} = \{\hat{\Sigma}_1^{(0)}, \dots, \hat{\Sigma}_q^{(0)}, \hat{\Phi}_S^{1,(0)}, \hat{\Phi}_S^{2,(0)}, \hat{\Phi}_T^{1,(0)}, \hat{\Phi}_T^{2,(0)}, \hat{\beta}_1^{1,(0)}, \hat{\beta}_1^{2,(0)}, \hat{\mu}^{1,(0)}, \hat{\mu}^{2,(0)}\}$ be the initial parameter value. Since the MPLLE objective function for LDFA-H given in Eq. (9) is not guaranteed convex, an EM-algorithm may find a local minimum according to a choice of the initial value. Hence a good initialization is crucial to a successful estimation. Here we suggest an initialization by a canonical correlation analysis (CCA).

Let $\{X^1[n], X^2[n]\}_{n=1, \dots, N}$ be N simultaneously recorded pairs of neural time series. We can view them as NT recorded pairs of multivariate random vectors $\{X_{:,t}^1[n], X_{:,t}^2[n]\}_{(n,t) \in [N] \times [T]}$. We obtain $\hat{\beta}_1^{1,(0)}$ and $\hat{\beta}_1^{2,(0)}$ by CCA as follows:

$$\hat{\beta}_1^{1,(0)}, \hat{\beta}_1^{2,(0)} = \underset{\beta_1^1 \in \mathbb{R}^{p_1}, \beta_1^2 \in \mathbb{R}^{p_2}}{\operatorname{argmax}} \frac{\beta_1^{1\top} S^{12} \beta_1^2}{\sqrt{\beta_1^{1\top} S^{11} \beta_1^1} \sqrt{\beta_1^{2\top} S^{22} \beta_1^2}} \quad (\text{A.1})$$

where

$$\begin{aligned} S^{11} &= \frac{1}{NT} \sum_{n,t} (X_{:,t}^1[n] - \frac{1}{NT} \sum_{n,t} X_{:,t}^1[n]) (X_{:,t}^1[n] - \frac{1}{NT} \sum_{n,t} X_{:,t}^1[n])^\top \\ S^{22} &= \frac{1}{NT} \sum_{n,t} (X_{:,t}^2[n] - \frac{1}{NT} \sum_{n,t} X_{:,t}^2[n]) (X_{:,t}^2[n] - \frac{1}{NT} \sum_{n,t} X_{:,t}^2[n])^\top \\ S^{12} &= \frac{1}{NT} \sum_{n,t} (X_{:,t}^1[n] - \frac{1}{NT} \sum_{n,t} X_{:,t}^1[n]) (X_{:,t}^2[n] - \frac{1}{NT} \sum_{n,t} X_{:,t}^2[n])^\top. \end{aligned} \quad (\text{A.2})$$

According to the equivalence between CCA and probabilistic CCA shown by A. Anonymous, it gives an estimate of the first latent factors

$$\hat{Z}_{1,:}^{k,(0)}[n] = \hat{\beta}_1^{k,(0)} X^k[n] \quad (\text{A.3})$$

for $n = 1, \dots, N$ and $k = 1, 2$. The initial second latent factors $\hat{Z}_2^{k,(0)}$ and the corresponding factor loading $\hat{\beta}_2^{k,(0)}$ is similarly set by the second pair of canonical variables, and so on. Then we assign the empirical covariance matrix of $\{\hat{Z}_f^{1,(0)}[n], \hat{Z}_f^{2,(0)}[n]\}_{n \in [N]}$ to the initial latent covariance matrix $\hat{\Sigma}_f^{(0)}$ for $f = 1, \dots, q$ and the matrix-variate normal estimate (Zhou, 2014) on $\{\hat{\epsilon}^{k,(0)}[n] := X^k[n] - \hat{\beta}_1^{k,(0)} \hat{Z}_{1,:}^{k,(0)}[n]\}_{n \in [N]}$ to $\hat{\Phi}_T^{k,(0)}$ and $\hat{\Phi}_S^{k,(0)}$ for $k = 1, 2$. Along $\hat{\mu}^{k,(0)} := \frac{1}{N} \sum_{n=1}^N X^k[n]$, the above parameters comprises the initial parameter set $\hat{\theta}^{(0)}$.

However, we cannot run an E-step on the above parameter set because $\hat{\Phi}^{k,(0)}$ is not invertible. We instead pick one of its unidentifiable parameter sets $\hat{\theta}^{(0), \{\alpha^1, \alpha^2\}}$, defined in Eq. (8), with all $\hat{\Phi}^{k,(0)}$'s and $\hat{\Sigma}_f^{(0)}$'s invertible. Specifically, we take

$$\alpha_f^k = \frac{1}{2} \lambda_{\min} \left(\Sigma_f^{1/2} \begin{bmatrix} \Phi_T^1 & 0 \\ 0 & \Phi_T^2 \end{bmatrix}^{-1} \Sigma_f^{1/2} \right) \quad (\text{A.4})$$

for $f = 1, \dots, q$ and $k = 1, 2$ where $\lambda_{\min}(A)$ is the smallest eigenvalue of symmetric matrix A . Henceforth, we notate $\hat{\theta}^{(0), \{\alpha^1, \alpha^2\}}$ by $\hat{\theta}^{(0)}$. For $t = 1, 2, \dots$, we iterate the following E-step and M-step until convergence.

Another promising initialization is by finding time (t, s) on which the canonical correlation between $X_{:,t}^1$ and $X_{:,s}^2$ maximizes. i.e., we initialize $\hat{\beta}_1^{1,(0)}$ and $\hat{\beta}_1^{2,(0)}$ by

$$\hat{\beta}_1^{1,(0)}, \hat{\beta}_1^{2,(0)} = \underset{\beta_1^1 \in \mathbb{R}^{p_1}, \beta_1^2 \in \mathbb{R}^{p_2}}{\operatorname{argmax}} \frac{\beta_1^{1\top} S_{(t,s)}^{12} \beta_1^2}{\sqrt{\beta_1^{1\top} S_{(t,t)}^{11} \beta_1^1} \sqrt{\beta_1^{2\top} S_{(s,s)}^{22} \beta_1^2}} \text{ such that } |t - s| < h_{\text{cross}}. \quad (\text{A.5})$$

where

$$\begin{aligned}
S_{(t,t)}^{11} &= \frac{1}{N} \sum_{n,t} (X_{:,t}^1[n] - \frac{1}{N} \sum_n X_{:,t}^1[n]) (X_{:,t}^1[n] - \frac{1}{N} \sum_n X_{:,t}^1[n])^\top \\
S_{(s,s)}^{22} &= \frac{1}{N} \sum_{n,s} (X_{:,s}^2[n] - \frac{1}{N} \sum_n X_{:,s}^2[n]) (X_{:,s}^2[n] - \frac{1}{N} \sum_n X_{:,s}^2[n])^\top \\
S_{(t,s)}^{12} &= \frac{1}{N} \sum_{n,t} (X_{:,t}^1[n] - \frac{1}{N} \sum_n X_{:,t}^1[n]) (X_{:,s}^2[n] - \frac{1}{N} \sum_n X_{:,s}^2[n])^\top.
\end{aligned} \tag{A.6}$$

for $(t, s) \in [T] \times [T]$. Then the other parameters are initialized as above. We can even take an ensemble approach in which we fit LDFA-H on different initialized values and pick the estimate with the minimum cost function (Eq. (9)).

Now, for $r = 1, 2, \dots$, we alternate an E-step and an M-step until the target parameter Π_f converges.

E-step Given $\hat{\theta} := \hat{\theta}^{(r-1)}$ from the previous iteration, the conditional distribution of latent factors $Z^1[n]$ and $Z^2[n]$ with respect to observed data $X^1[n]$ and $X^2[n]$ on trial $n = 1, \dots, N$ follows

$$(Z_{1,:}^1[n]; Z_{1,:}^2[n]; \dots; Z_{q,:}^2[n]) \mid X^1[n], X^2[n] \sim \text{MVN} \left(m_{Z|X}^{(r)}[n], V_{Z|X}^{(r)} \right), \tag{A.7}$$

where

$$V_{Z|X}^{(r)} = \begin{pmatrix} V_{Z_1, Z_1|X}^{(r)} & \cdots & V_{Z_1, Z_q|X}^{(r)} \\ \vdots & \ddots & \vdots \\ V_{Z_q, Z_1|X}^{(r)} & \cdots & V_{Z_q, Z_q|X}^{(r)} \end{pmatrix} = \begin{pmatrix} W_{Z_1, Z_1|X}^{(r)} & \cdots & W_{Z_1, Z_q|X}^{(r)} \\ \vdots & \ddots & \vdots \\ W_{Z_q, Z_1|X}^{(r)} & \cdots & W_{Z_q, Z_q|X}^{(r)} \end{pmatrix}^{-1} \tag{A.8}$$

and

$$\begin{aligned}
m_{Z|X}^{(r)}[n] &= \left(m_{Z_1^1|X}^{(r)}; m_{Z_2^1|X}^{(r)}; \dots; m_{Z_q^2|X}^{(r)} \right) \\
&= V_{Z|X}^{(r)} \left(\hat{\beta}_1^\top \hat{\Gamma}_S^1 X^1[n] \hat{\Gamma}_T^1; \hat{\beta}_1^{2\top} \hat{\Gamma}_S^2 X^2[n] \hat{\Gamma}_T^2; \dots; \hat{\beta}_q^{2\top} \hat{\Gamma}_S^2 X^2[n] \hat{\Gamma}_T^2 \right)
\end{aligned} \tag{A.9}$$

given

$$W_{Z_f, Z_g|X}^{(r)} = \begin{pmatrix} (\hat{\beta}_f^{1\top} \hat{\Gamma}_S^1 \hat{\beta}_g^1) \hat{\Gamma}_T^1 & 0 \\ 0 & (\hat{\beta}_f^{2\top} \hat{\Gamma}_S^2 \hat{\beta}_g^2) \hat{\Gamma}_T^2 \end{pmatrix} + \mathbb{I}_{\{f=g\}} \hat{\Omega}_f, \quad \mathbb{I}_{\{f=g\}} = \begin{cases} 1, & f = g \\ 0, & \text{o.w.} \end{cases} \tag{A.10}$$

for $f, g = 1, \dots, q$.

M-step We find $\hat{\theta}^{(r)}$ which maximize the conditional expectation of the penalized likelihood under the same constraints in Eq. (9), i.e.

$$\begin{aligned}
\hat{\theta}^{(r)} &= \underset{\theta}{\text{argmin}} \frac{1}{N} \sum_{n=1}^N \mathbb{E}_{Z[n]|X[n], \hat{\theta}^{(r-1)}} \left[\log p(X^1[n], X^2[n], Z^1[n], Z^2[n]; \hat{\theta}^{(r-1)}) \right] \\
&\quad + \sum_{f=1}^q \sum_{k,l=1}^2 \|\Lambda_f^{kl} \odot \Pi_f^{kl}\|_1 \quad \text{s.t.} \quad \hat{\Gamma}_T^k \text{ is } (2h_\epsilon^k + 1)\text{-diagonal}
\end{aligned} \tag{A.11}$$

where p is the probability density function of our model in Eqs. (1), (4) and (5) and the expectation $\mathbb{E}_{Z[n]|X[n], \hat{\theta}^{(r-1)}}$ follows the conditional distribution in Eq. (A.7). Taking a block coordinate descent approach, we solve the optimization problem by alternating M1 - M4.

M1: With respect to latent precision matrices Ω_f , Eq. (A.11) reduces to a graphical Lasso problem,

$$\hat{\Omega}_f^{(r)} = \underset{\Omega_f}{\text{argmin}} \left\{ -\log \det(\Omega_f) + \text{tr} \left(\Omega_f \left(V_{Z_f|X}^{(r)} + \hat{\mathbb{E}}[m_{Z_f|X}^{(r)} m_{Z_f|X}^{(r)\top}] \right) \right) + \sum_{k,l=1}^2 \|\Lambda_f^{kl} \odot \Pi_f^{kl}\|_1 \right\} \tag{A.12}$$

for each $f = 1, \dots, q$ where $\widehat{\mathbb{E}}[m_{Z_f|X}^{(r)} m_{Z_f|X}^{(r)\top}] = \frac{1}{N} \sum_{n=1}^N m_{Z_f|X}^{(r)}[n] m_{Z_f|X}^{(r)\top}[n]$. The graphical Lasso problem is solved by the P-GLASSO algorithm by Mazumder et al. (2010).

M2: With respect to Γ^k , Eq. (A.11) reduces to an estimation of matrix-variate normal model (Zhou, 2014). The estimation problem can be formulated as

$$\widehat{\Gamma}_{\mathcal{S}}^{k(r)} = \frac{1}{T} \left(\widehat{\mathbb{E}} \left[m_{\epsilon^k|X}^{(r)} m_{\epsilon^k|X}^{(r)\top} \right] + \sum_{f,g=1}^q \text{tr}(V_{Z_f^k, Z_g^k|X}^{(r)}) \beta_f^k \beta_g^{k\top} \right) \quad (\text{A.13})$$

and

$$\widehat{\Gamma}_{\mathcal{T}}^{k(r)} = \underset{\Gamma_{\mathcal{T}}^k}{\text{argmin}} \left\{ \begin{array}{l} -\log \det(\Gamma_{\mathcal{T}}^k) \\ + \frac{1}{p_k} \text{tr} \left(\Gamma_{\mathcal{T}}^k \left(\sum_{f,g=1}^q (\beta_f^{k\top} \Gamma_{\mathcal{S}}^k \beta_g^k) V_{Z_f^k, Z_g^k|X}^{(r)} + \widehat{\mathbb{E}} \left[m_{\epsilon^k|X}^{(r)\top} \Gamma_{\mathcal{S}}^k m_{\epsilon^k|X}^{(r)} \right] \right) \right) \end{array} \right\} \quad (\text{A.14})$$

s.t. $\widehat{\Gamma}_{\mathcal{T}}^k$ is $(2h_{\epsilon}^k + 1)$ -diagonal

for each $k = 1, 2$ where $m_{\epsilon^k|X}^{(r)} = X^k - \beta^k m_{Z^k|X}^{(r)} - \mu^k$ and $\widehat{\mathbb{E}}[A]$ is the empirical mean of a random matrix A . The estimation of $\Gamma_{\mathcal{T}}^k$ under the bandedness constraint is tractable with modified Cholesky factor decomposition approach with bandwidth h_{ϵ}^k using the procedure by Bickel and Levina (2008).

M3: With respect to β^k , Eq. (A.11) reduces to a quadratic program

$$\widehat{\beta}^{k(r)} = \underset{\beta^k}{\text{arg max}} \left\{ \begin{array}{l} \sum_{t,s} \Gamma_{\mathcal{T},(t,s)}^k \text{tr} \left(\beta^{k\top} \Gamma_{\mathcal{S}}^k \beta^k (V_{Z_{:,t}^k, Z_{:,s}^k|X}^{(r)} + \widehat{\text{Cov}}[m_{Z_{:,t}^k|X}^{(r)}, m_{Z_{:,s}^k|X}^{(r)}]) \right) \\ - 2 \sum_{t,s} \Gamma_{\mathcal{T},(t,s)}^k \text{tr} \left(\Gamma_{\mathcal{S}}^k \beta^k \widehat{\text{Cov}}[X_{:,t}^k, m_{Z_{:,s}^k|X}^{(r)}] \right) \end{array} \right\} \quad (\text{A.15})$$

where $\Gamma_{\mathcal{T},(t,s)}^k$ is the (t, s) entry in $\Gamma_{\mathcal{T}}^k$ and $\widehat{\text{Cov}}(A, B)$ is the empirical covariance matrix between random vectors A and B . The analytic form of the solution is given by

$$\beta^k = \left(\sum_{t,s} \Gamma_{\mathcal{T},(t,s)}^k (V_{Z_{:,t}^k, Z_{:,s}^k|X}^{(r)} + \widehat{\text{Cov}}[m_{Z_{:,t}^k|X}^{(r)}, m_{Z_{:,s}^k|X}^{(r)}]) \right)^{-1} \left(\sum_{t,s} \Gamma_{\mathcal{T},(t,s)}^k \widehat{\text{Cov}}[m_{Z_{:,s}^k|X}^{(r)}, X_{:,t}^k] \right) \quad (\text{A.16})$$

M4: With respect to μ^k , it is straight-forward that Eq. (A.11) yields

$$\widehat{\mu}^{k(r)} = \widehat{\mathbb{E}} \left[X^k - \sum_{f=1}^q \beta_f^k m_{Z_f^k|X}^{(r)\top} \right].$$

B Simulation details (Section 3)

We simulated realistic data with known cross-region connectivity as follows. Simulating $q = 1$ pair of latent time-series Z^k from Equation (2), we introduced an exact ground-truth for the inverse cross-correlation matrix Π_1^{12} by setting:

$$\Pi_1 = \begin{bmatrix} (P_{1,0}^{11})^{-1} & 0 \\ 0 & (P_{1,0}^{22})^{-1} \end{bmatrix} + \begin{bmatrix} D^1 & \Pi_1^{12} \\ \Pi_1^{12\top} & D^2 \end{bmatrix} \quad (\text{B.1})$$

where D^1 and D^2 are diagonal matrices with elements $D_{(t,t)}^1 = \sum_s \Pi_{1,(t,s)}^{12}$ and $D_{(s,s)}^2 = \sum_t \Pi_{1,(t,s)}^{12}$, which ensures that the matrix on the right hand side is positive definite. The matrix on the left hand side contains the auto-precision matrices of the two latent time series, with elements simulated from the squared exponential function:

$$P_{1,0}^{kk} = [\exp(-c^k(t-s)^2)]_{t,s} + \lambda I_T, \quad (\text{B.2})$$

with $c^1 = 0.105$ and $c^2 = 0.142$, chosen to match the observed LFPs auto-correlations in the experimental dataset (Section 3.2). We added the regularizer λI_T , $\lambda = 1$, to render P^{kk} invertible.

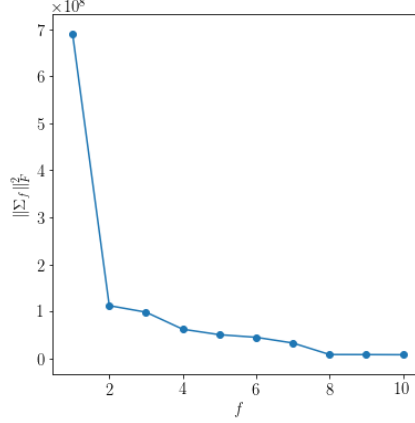


Figure C.1: Squared Frobenius norms of covariance matrix estimates, $\widehat{\Sigma}_f$, for all factors $f = 1, \dots, 10$. Notice that the amplitudes of the top four factors dominate the others.

We designed the true inverse cross-correlation matrix Π^{12} to induce lead-lag relationship between Z^1 and Z^2 in two epochs as depicted in the right-most panel of Fig. 2a. Specifically, the elements of Π^{12} were set:

$$\Pi_{(t,s)}^{12} = \begin{cases} -r, & \text{where } Z_{1,t}^1 \text{ and } Z_{1,s}^2 \text{ partially correlate,} \\ 0, & \text{elsewhere,} \end{cases} \quad (\text{B.3})$$

where the association intensity $r = 0.6$ was chosen to match our cross-correlation estimate in the experimental data (Section 3.2). Finally, we rescaled $P_1 = \Pi_1^{-1}$ to have diagonal elements equal to one. The corresponding factor loading vector β_1^k was randomly generated from standard multivariate normal distribution and then scaled to have $\|\beta_1^k\|_2 = 1$.

We generated the noise ϵ^k from the $N = 1000$ trials of the experimental data analyzed in Section 3.2. First, we permuted the trials in one region to remove cross-region correlations. Let $\{Y^1[n], Y^2[n]\}_{n=1, \dots, N}$ be the permuted dataset. Then we contaminated the dataset with white noise to modulate the strength of noise correlation relative to cross-region correlations. i.e.

$$\epsilon_{:,t}^k = Y_{:,t}^k - \mu_{:,t}^k + \eta_{:,t}^k, \quad \eta_{:,t}^k \stackrel{\text{indep}}{\sim} \text{MVN}\left(0, \lambda_\epsilon \widehat{\text{Cov}}[Y_{:,t}^k]\right), \quad \text{and } \mu_{:,t}^k = \widehat{\mathbb{E}}[Y_{:,t}^k] \quad (\text{B.4})$$

where $\widehat{\mathbb{E}}[Y_{:,t}^k]$ and $\widehat{\text{Cov}}[Y_{:,t}^k]$ were the empirical mean and covariance matrix of $Y_{:,t}^k$, respectively, for $k = 1, 2, t = 1, \dots, T$. The noise auto-correlation level was modulated by $\lambda_\epsilon \in \{2.78, 1.78, 0.44, 0.11\}$. We also obtained Σ_1 by scaling P_1 so that $\Sigma_{1,(t,s)}^{kk} = \beta_1^{k\top} S_t^k \beta_1^k$. Putting all the pieces together, we generated observed time series by Eq. (1).

C Experimental data analysis details (Section 3.2)

The strength of each factor, which is characterized by Σ_f , is shown in Fig. C.1.

We also examined an alternative definition of information flow, using non-stationary regression in the spirit of Granger causality. For the latent factor f in V4 at time t , we use partial R^2 , effectively comparing the full regression model using the full history of latent variables in both area,

$$Z_{f,t}^1 \sim Z_{f,1:t-1}^1 + Z_{f,1:t-1}^2$$

with the reduced model using history of latent variables in V4 only,

$$Z_{f,t}^1 \sim Z_{f,1:t-1}^1.$$

The partial R^2 for $Z_{f,t}^1$ on $Z_{f,1:t-1}^2$ given $Z_{f,1:t-1}^1$ summarizes the contribution of PFC history to V4, after taking account of the autocorrelation in V4, and thus can be viewed as information flow from V4 to PFC at time t . Dynamic information flow from V4 to PFC is defined similarly. The results shown in Fig. C.2 are consistent with those in Fig. 5d.

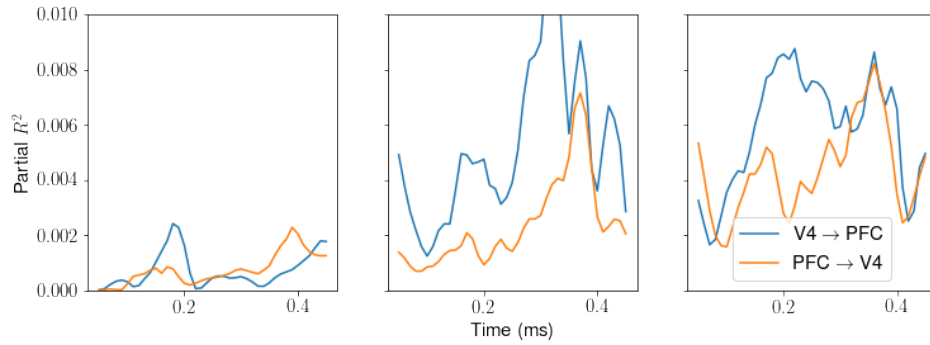


Figure C.2: **Information flow by partial R^2 for the top three factors.** In this figure, we characterize dynamic information flow in terms of partial R^2 . We show dynamic information flow from $V4 \rightarrow PFC$ (blue) and $PFC \rightarrow V4$ (orange). The results in the first panel are consistent with those in the first panel of Fig. 5d.