
Asymptotic Behaviors of Projected Stochastic Approximation: A Jump Diffusion Perspective

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Abstract

In this paper we consider linearly constrained stochastic approximation problems with federated learning as a special case. We propose a loopless projection stochastic approximation algorithm (LPSA) to ensure feasibility by performing the projection with probability p_n at the n -th iteration. Considering a specific family of the probability p_n and step size η_n , we analyze our algorithm from an asymptotic and continuous perspective. Using a novel jump diffusion approximation, we show that the trajectories connecting those properly rescaled last iterates weakly converge to the solution of specific stochastic differential equations (SDEs). By analyzing SDEs, we identify the asymptotic behaviors of LPSA for different choices of (p_n, η_n) . We find the algorithm presents an intriguing asymptotic bias-variance trade-off according to the relative magnitude of p_n w.r.t. η_n . It brings insights on how to choose appropriate $\{(p_n, \eta_n)\}_{n \geq 1}$ to minimize the projection complexity.

1 Introduction

Recently, a novel distributed computing paradigm that called *Federated Learning* (FL) has been proposed for collaboratively training a global model from data that remote *clients* hold [31]. As a standard optimization algorithm in FL, *Local SGD* alternates between running stochastic gradient descent (SGD) independently in parallel on different clients and averaging the sequences only once in a while. Put simply, it learns a shared global model via infrequent communication. Empirical investigation finds its superior performance in communication efficiency [30] and theoretical analysis toward it has already provided a complete picture [26, 1, 15, 42, 43, 15]. Among them, Li et al. [27] establishes a functional CLT that Local SGD with Polyak-Ruppert averaging simultaneously achieves the optimal asymptotic variance and diminishing average communication frequency. However, they are all derived from a discrete perspective.

The use of a continuous-time stochastic process to characterize the entire trajectory of a discrete stochastic algorithm has been witnessed progresses in recent years, and we call it diffusion approximation. The continuous approach has advantages in its rich toolbox and can provide intuitive explanation for uncanny phenomena that are intractable to analyze in discrete cases. It can also motivate new optimization algorithms and statistical inference methods. Current works applying diffusion approximation to stochastic optimization algorithms can be roughly divided into two classes. The first one is to interest the optimization algorithm as a numerical discretization of a specific stochastic differential equation (SDE) [14] in a finite time interval $[0, T]$. When the step size η is

sufficiently small and the length $T(= n\eta)$ of the interval is fixed (n is the total iterations), such approximation is of high accuracy, and it is easy to analyze the geometric properties of our target algorithms [41, 23, 13, 7, 38, 34, 8]. However, this avenue is difficult to capture the convergence behaviors around the optimal point due to the fixed T .¹ The second class comes up to solve the issue. It instead considers the iterates divided by a proper power function of step sizes. Under certain conditions, as n goes to infinity, the rescaled iterates would weakly converge to the stationary solution of corresponding SDEs [21, 35, 6, 9, 10]. In FL, to the best of our knowledge, no work considers analyzing Local SGD via the aspect, which is our focus here.

However, it is not easy to serialize Local SGD iterates due to its double-loop nature. Recent researchers developed a new technique named as ‘loopless’ to simplify the two-loop structure for SVRG and Katyusha [16]. The key is to replace the hard loop with a probabilistic loop. Specifically, we will independently toss a (possibly biased) coin ω_n with head probability p_n at iteration n . When getting the head $\omega_n = 1$, we start a new loop and update the outer-loop intermediate variables; when getting the tail $\omega_n = 0$, we stay in the same loop and keep the intermediate variables. In this way, we obtain a loopless counterpart algorithm and do not need to distinguish inner and outer loops anymore. It facilitates theoretical analysis and typically does not deteriorate the convergence rate [12, 29, 28, 11]. It is worth mentioning that Hanzely and Richtárik [12] first introduced the loopless technique to FL and obtained many efficient FL algorithms. Li [28] used a dynamic p_n (which varies with n) to generalize the scope of original methods. We are then motivated to analyze a loopless version of Local SGD with decreasing p_n , but from an asymptotic and continuous perspective.

1.1 Contribution

Our work is motivated by Local SGD but beyond it. In particular, for a general optimization problems with linear constrains (of which FL is a special case), we develop a loopless projection stochastic approximation method (LPSA) as a generalization of Local SGD (see Appendix A for more details). Such generality renders us the possibility to transfer our techniques and results to other linearly constrained problems. LPSA is affected by two important hyperparameters, namely the step size $\{\eta_n\}$ and the projection probability $\{p_n\}$. For the choices of $\eta_n \propto n^{-\alpha}$ and $p_n \propto \min\{\eta_n^\beta, 1\}$, we derive a non-asymptotic convergence rate for different $\alpha \in (0, 1]$ and $\beta \in (0, 1)$ in Theorem 3.1. We observe a phase transition for the convergence rate $\mathcal{O}(n^{-\alpha \min\{1, 2-2\beta\}})$ when β crosses 0.5.

To derive asymptotic results, we obtain two sequences $\{\mathbf{u}_n\}$ and $\{\mathbf{v}_n\}$ by orthogonal decomposition for the optimized sequence of LPSA. We then construct two sequences of processes which pass through the appropriately rescaled \mathbf{u}_n and \mathbf{v}_n , respectively. We show rigorously, when the iteration goes to infinity, these two sequences of stochastic processes weakly converge to the solutions of specific SDEs that are driven by either a Brownian motion or a Poisson process. As a corollary, the rescaled last iterate of \mathbf{u}_n (which we mainly care about) has a known asymptotic distribution (either Gaussian distribution in Theorem 3.3 or Dirac in Corollary 1). And the phase transition we mentioned above evolves into a trade-off between the bias caused by the low frequency projection and the fluctuation resulting from the gradient noise (see Section 3.2.3).

Moreover, according to different convergence rate for every $\{(\eta_n, p_n)\}$ pair, we consider a selection scheme at the end of Section 3.2.3, which makes the algorithm have the same nonasymptotic convergence order as the conventional stochastic approximation and spend as little as possible on the projection operation which is usually expensive in practice. At the end, we conduct numerical experiments to confirm the theoretical results.

From a technical level, we propose a novel proof technique to analyze the discontinuity brought by probabilistic projection. In particular, we borrow tools from jump diffusion and verify necessary conditions (e.g., stochastic tightness) to apply it. See the paragraph after Theorem 3.4 for a main idea. We believe our technique can extend to and help analyze other stochastic approximation algorithms which can be approximated by a jump diffusion.

¹A finite T implies not only the algorithm but also its corresponding SDE do not converge to the optimum.

2 Problem Formulation

2.1 Loopless Projected Stochastic Approximation

Notice that distributed optimization such as FL can be formulated as a global consensus problem which is a linearly constrained problem [5]. For the sake of simplicity and generality, we aim to solve the following problem

$$\min_{\mathbf{x}} \mathbb{E}_{\zeta \sim \mathcal{D}} f(\mathbf{x}, \zeta) \quad \text{subject to } \mathbf{A}^\top \mathbf{x} = \mathbf{0} \quad (1)$$

via a randomly (and infrequently) projected stochastic approximation algorithm. In particular, at iteration n , we first perform one step of SGD via

$$\mathbf{x}_{n+\frac{1}{2}} = \mathbf{x}_n - \eta_n \nabla f(\mathbf{x}_n) + \eta_n \xi_n, \quad (2)$$

where $f(\mathbf{x}) = \mathbb{E}_{\zeta \sim \mathcal{D}} f(\mathbf{x}, \zeta)$ and $\xi_n = \nabla f(\mathbf{x}_n) - \nabla f(\mathbf{x}_n, \zeta_n)$. Here $\{\xi_n\}$ is a martingale difference sequence (m.d.s.) under the natural filtration $\mathcal{F}_{n+1} := \sigma(\zeta_k, \omega_k; k \leq n+1)$. We then use the loopless trick introduced in the introduction, i.e., we independently cast a coin with the head probability p_n and obtain the result $\omega_n \sim \text{Bernoulli}(p_n)$. If $\omega_n = 1$, we perform one step of projection to ensure \mathbf{x}_{n+1} fall into the feasible region: $\mathbf{x}_{n+1} = \mathcal{P}_{\mathbf{A}^\perp}(\mathbf{x}_{n+\frac{1}{2}})$ where $\mathcal{P}_{\mathbf{A}^\perp}$ denotes the projection onto the null space of \mathbf{A}^\top . If $\omega_n = 0$, we assign \mathbf{x}_{n+1} as the same value of $\mathbf{x}_{n+\frac{1}{2}}$, i.e., $\mathbf{x}_{n+1} = \mathbf{x}_{n+\frac{1}{2}}$. It is clear this algorithm (2) mimics the behavior of Local SGD in FL settings (see Appendix A for the equivalence).

2.2 Assumptions

For the linearly constrained convex optimization problem (1), we make the following assumptions which are quite common in the literature. Without special clarification, $\|\cdot\|$ denotes the Euclidean norm for vectors and the spectral norm for matrices.

Assumption 1 (Smoothness). *We assume that $f: \mathbb{R}^d \rightarrow \mathbb{R}$ is L -smooth, that is,*

$$\|\nabla f(\mathbf{x}) - \nabla f(\mathbf{y})\| \leq L\|\mathbf{x} - \mathbf{y}\|, \quad \forall \mathbf{x}, \mathbf{y} \in \mathbb{R}^d.$$

Assumption 2 (Strong convexity). *We assume that $f: \mathbb{R}^d \rightarrow \mathbb{R}$ is μ -strongly convex, that is,*

$$f(\mathbf{x}) - f(\mathbf{y}) \geq \langle \nabla f(\mathbf{y}), \mathbf{x} - \mathbf{y} \rangle + \frac{\mu}{2} \|\mathbf{x} - \mathbf{y}\|^2, \quad \forall \mathbf{x}, \mathbf{y} \in \mathbb{R}^d.$$

Assumption 3 (Continuous Hessian matrix). *We assume that $f: \mathbb{R}^d \rightarrow \mathbb{R}$ is Hessian Lipschitz, that is, there is a constant \tilde{L} such that*

$$\|\nabla^2 f(\mathbf{x}) - \nabla^2 f(\mathbf{y})\| \leq \tilde{L}\|\mathbf{x} - \mathbf{y}\|, \quad \forall \mathbf{x}, \mathbf{y} \in \mathbb{R}^d.$$

Assumption 4 (Continuous covariance matrix). *Given an m.d.s. $\{\xi_t\}$, we denote the conditional covariance as $\mathbb{E}[\xi_t \xi_t^\top | \mathcal{F}_t] = \Sigma(\mathbf{x}_t)$ and assume it is L -Lipschitz continuous in the sense that*

$$\|\Sigma(\mathbf{x}) - \Sigma(\mathbf{y})\|_2 \leq L\|\mathbf{x} - \mathbf{y}\|, \quad \forall \mathbf{x}, \mathbf{y} \in \mathbb{R}^d.$$

Assumption 5. *For the m.d.s. $\{\xi_n\}$, we assume there exists a $p > 2$ such that the p -th moment of every element in $\{\xi_n\}$ is uniformly bounded, that is,*

$$\sup_{n \geq 0} \mathbb{E} \|\xi_n\|^p < \infty.$$

The first three assumptions imply we consider the strongly convex case. The last two assumptions help us identify the asymptotic variance. Especially, the assumption of uniformly bounded p ($p > 2$) moments is typically required to establish central limit theorems [9, 10, 27]. Finally, we want to emphasize that the stationary condition for the problem (1) is different from unconstrained ones; $\nabla f(\mathbf{x}^*)$ is not necessarily zero, however, its projection into the null space of \mathbf{A}^\top must be zero.

Proposition 1 ([25], Corollary 2.1). *Let $\mathcal{P}_{\mathbf{A}}$ be the projection onto the column space of \mathbf{A} and $\mathcal{P}_{\mathbf{A}^\perp}$ the projection onto the null space of \mathbf{A}^\top . Under Assumption 2, the solution of (1) is unique (denoted \mathbf{x}^*). Moreover, we have $\mathcal{P}_{\mathbf{A}^\perp}(\nabla f(\mathbf{x}^*)) = \mathbf{0}$.*

2.3 Jump Diffusion

Jump diffusion is a stochastic Lévy process that involves jumps and diffusion. Typically, the former is modeled by a Poisson process, while the latter is modeled as a Brownian motion. It has wide and important applications in physics, finance[36], and computer vision.

We say a function f defined on \mathbb{R} is càdlàg when f is right-continuous and has left limits everywhere. For a càdlàg process $(\mathbf{V}_s)_{s \geq 0}$, we denote \mathbf{V}_{t-} as the left limit of \mathbf{V} at time t . Let $\mathbf{N}_\gamma(t)$ denote the Poisson process with γ the intensity, which quantifies the number of jumps up to the time t and is clearly càdlàg. We use $\mathbf{N}_\gamma(dt) = \mathbf{N}_\gamma(t) - \mathbf{N}_\gamma(t-) \in \{0, 1\}$ to indicate whether \mathbf{N}_γ jumps at time t and $\int_0^T g(t-) \mathbf{N}(dt) = \sum_{\{t: \mathbf{N}_\gamma(t) \neq \mathbf{N}_\gamma(t-)\}} g(t-)$ to denote the integral that drives for a measurable function $g(\cdot)$. We will consider a special class of jump diffusion in the following form

$$d\mathbf{X}_t = \alpha(t, \mathbf{X}_t)dt + \beta(t, \mathbf{X}_t)d\mathbf{W}_t + \varphi(t, \mathbf{X}_{t-})\mathbf{N}_\gamma(dt). \quad (3)$$

When the coefficient functions $\alpha(t, \mathbf{X}_t)$ and $\beta(t, \mathbf{X}_t)$ satisfy conditions like linear growth and Lipschitz continuity, there exists a solution for the jump diffusion (3) (e.g., Theorem 1.19 in [33]).

3 Main Results

In the section, we are going to capture the convergence behaviors of our projected stochastic approximation method (2) from both non-asymptotic and asymptotic perspectives. We consider a specific family of step size η_n and projection probability p_n , namely, $\eta_n = \eta_0 n^{-\alpha}$ and $p_n = \min\{\eta_n^\beta, 1\}$ indexed by $0 < \alpha \leq 1$ and $0 \leq \beta < 1$, respectively. The choice of step sizes η_n has been used to establish CLTs [37, 27], while the choice of p_n is quite novel. To provide a complete picture of convergence, we will consider almost all combinations of α and β .

3.1 Non-asymptotic Analysis

To provide the convergence rate, it is natural to focus on the projection of \mathbf{x}_n into the column space of \mathbf{A} (since it is the easiest feasible solution one can obtain from \mathbf{x}_n). Hence, we decompose the iterated \mathbf{x}_n into two orthogonal components $\mathbf{x}_n := \mathbf{u}_n + \mathbf{v}_n$ where $\mathbf{u}_n = \mathcal{P}_{\mathbf{A}^\perp}(\mathbf{x}_n)$ and $\mathbf{v}_n = \mathcal{P}_{\mathbf{A}}(\mathbf{x}_n)$.² We specify the convergence rate of $\mathbb{E} \|\mathbf{u}_n - \mathbf{x}^*\|^2$ in terms of α, β and n in the following theorem.

Theorem 3.1. *Suppose that Assumptions 1, 2 and 4 hold. Let $\eta_n = \eta_0 n^{-\alpha}$ and $p_n = \min\{\eta_n^\beta, 1\}$ with $0 \leq \beta < 1$. Then for (i) $0 < \alpha < 1$ or (ii) $\alpha = 1$ with $\eta_0 > 2/\mu$ (μ is the strong convexity parameter of the objective function f), we have*

$$\mathbb{E} \|\mathbf{u}_n - \mathbf{x}^*\|^2 = \mathcal{O}(n^{-\alpha \min\{1, 2-2\beta\}}).$$

From Theorem 3.1, as β decreases, that is, the projection happens more frequently, $\mathbb{E} \|\mathbf{u}_n - \mathbf{x}^*\|^2$ converges faster. The rate is $\mathcal{O}(n^{-\alpha})$ when $\beta < 0.5$, while the rate is $\mathcal{O}(n^{-2\alpha(1-\beta)})$ when $\beta > 0.5$. Thus there exists a phase transition when β goes across 0.5, which implies we should analyze asymptotic performances for these two phases respectively. As an extreme, when $\beta = 1$, the algorithm is possible to disconverge in an artifact quadratic loss with a specific \mathbf{A} (see Theorem 3.2). Though for a specific \mathbf{A} , it could apply to FL (see Corollary 2 in Appendix A.2.1 for the detail).

Theorem 3.2. *If $\eta_n = \eta_0 n^{-\alpha}$ and $p_n = \min\{p_0 \eta_n, 1\}$ with $0 < \alpha \leq 1$, for a specific \mathbf{A} , there exists a quadratic function $f(\mathbf{x})$ so that $\nabla^2 f(\mathbf{x}) \succeq \mathbf{I}_d$ and $\mathbb{E} \|\mathbf{u}_n - \mathbf{x}^*\|^2$ does not converge to 0. Here $\mathbf{I}_d \in \mathbb{R}^{d \times d}$ is the identity matrix, and $\nabla^2 f(\mathbf{x}) \succeq \mathbf{I}_d$ means $\nabla^2 f(\mathbf{x}) - \mathbf{I}_d$ is positive semidefinite.*

3.2 Asymptotic Behavior of the Rescaled Trajectory

In this section, we want to derive an asymptotic convergence for (2). Recall that there exists a phase transition for the convergence rate of $\mathbb{E} \|\mathbf{u}_t - \mathbf{x}^*\|^2$ when β crosses 0.5, when the projection probability is set as $p_n = \eta_n^\beta$. In the following, we will analyze the asymptotic behaviors of LSPA for the two cases $\beta \in [0, 1/2)$ and $\beta \in (1/2, 1)$.

²One can check Proposition 4 in Appendix B to see why \mathbf{u}_n is orthogonal to \mathbf{v}_n .

3.2.1 Case 1: Frequent Projection where $\beta \in [0, 1/2)$

From an asymptotic perspective, the typical central limit theorem (CLT) claims $\check{\mathbf{u}}_n := \frac{\mathbf{u}_n - \mathbf{x}^*}{\sqrt{\eta_{n-1}}}$ would weakly converge to a rescaled standard distribution [21]. It helps us capture the large-sample convergence behaviors and provide ways for future statistical inference. However, we can provide a stronger result that captures the asymptotic behavior of the whole trajectory. In particular, we serialize the sequence $\{\check{\mathbf{u}}_n\}$ by constructing a continuous random function (denoted $\bar{\mathbf{u}}_t^{(n)}$) such that it starts from $\bar{\mathbf{u}}_0^{(n)} = \check{\mathbf{u}}_n$, and as t increases it will pass through $\check{\mathbf{u}}_{n+1}$, $\check{\mathbf{u}}_{n+2}$ and so on. We will show that such a random function $\bar{\mathbf{u}}_t^{(n)}$ will weakly converge to the solution of a specific SDE. From the SDE, we can derive asymptotic variance of $\check{\mathbf{u}}_n$ and the whole trajectory evolution.

Since $\bar{\mathbf{u}}_t^{(n)}$ should pass all $\{\check{\mathbf{u}}_k\}_{k \geq n}$, we can connect these discrete points by piecewise linear functions. To that end, we first derive the one-step relation between $\check{\mathbf{u}}_n$ and $\check{\mathbf{u}}_{n+1}$. In particular,

$$\check{\mathbf{u}}_{n+1} = \check{\mathbf{u}}_n - \eta_n \mathbf{b}_n + \sqrt{\eta_n} \xi_n^{(1)}, \quad (4)$$

$$\mathbf{b}_n := \mathcal{P}_{\mathbf{A}^\perp} \left(\nabla^2 f(\mathbf{x}^*) - \frac{1}{2\eta_0} \mathbb{1}_{\{\alpha=1\}} \mathbf{I}_d \right) \check{\mathbf{u}}_n + \frac{1}{\eta_n} \mathcal{R}_n, \quad (5)$$

where \mathcal{R}_n stands for a high-order residual error, and $\xi_n^{(1)}$ denotes the component of noise ξ_n on the null space of \mathbf{A} . One can find the derivation of (4) in Appendix C.1. Roughly speaking, (4) can be viewed as a one-step Euler Maruyama discretization with timescale η_n for an SDE, which starts at $\check{\mathbf{u}}_n$ with local drift coefficient \mathbf{b}_n and local diffusion coefficient $\text{var}(\xi_n^{(1)})$.

Definition 1 (Time interpolation). Let a positive sequence $\gamma = \{\gamma_n\}_n^\infty$ decrease to zero. For $n \in \mathbb{N}$, $t \geq 0$, define

$$N(n, t, \gamma) = \min_{m \in \mathbb{N}} \left\{ m \geq n : \sum_{k=n}^m \gamma_k > t \right\}, \Gamma_n(\gamma) = \sum_{k=1}^{n-1} \gamma_k, \text{ and } \underline{t}_n(\gamma) = \Gamma_{N(n, t, \gamma)} - \Gamma_n.$$

We introduce a time interpolation for the formal description of the continuous function and further analysis. Intuitively, $N(n, t, \gamma)$ is the number of iterations m at which the sum of step sizes $\sum_{k=n+1}^{m+1} \eta_k$ is just larger than t and $\underline{t}_n(\gamma)$ is the approximation of t when we only use step sizes $\{\gamma_k\}_{k \geq n}$. Since $\gamma_n \rightarrow 0$, $\underline{t}_n(\gamma) \rightarrow t$ as n goes to infinity. A property of Definition 1 is that $N(n, \Gamma_m(\gamma) - \Gamma_n(\gamma), \gamma) = m$ for any $m \geq n$. By now, we are ready to construct $\bar{\mathbf{u}}_t^{(n)}$. For a given $n \in \mathbb{N}$, let $\bar{\mathbf{u}}_0^{(n)} = \check{\mathbf{u}}_n$ and define for $t \geq 0$,

$$\begin{aligned} \bar{\mathbf{u}}_t^{(n)} = & \check{\mathbf{u}}_n + \left\{ \sum_{k=n}^{N(n, t, \eta)-1} \eta_k \mathbf{b}_k + (t - \underline{t}_n(\eta)) \mathbf{b}_{N(n, t, \eta)} \right\} \\ & + \left\{ \sum_{k=n}^{N(n, t, \eta)-1} \sqrt{\eta_k} \xi_k^{(1)} + \sqrt{t - \underline{t}_n(\eta)} \xi_{N(n, t, \eta)}^{(1)} \right\}. \end{aligned} \quad (6)$$

From the construction, we can see that $\bar{\mathbf{u}}_{\underline{t}_k(\eta)}^{(n)} = \check{\mathbf{u}}_{n+k}$.

Theorem 3.3 (Diffusion Approximation). Let Assumptions 1-5 hold. The following family of continuous stochastic processes $\{\bar{\mathbf{u}}_t^{(n)} : t \geq 0\}_{n=1}^\infty$ weakly converges to the stationary weak solution of the following SDE:

$$d\mathbf{X}_t = -\mathcal{P}_{\mathbf{A}^\perp} \left(\nabla^2 f(\mathbf{x}^*) - \frac{1}{2\eta_0} \mathbb{1}_{\{\alpha=1\}} \mathbf{I}_d \right) \mathbf{X}_t dt + \mathcal{P}_{\mathbf{A}^\perp} \Sigma(\mathbf{x}^*)^{\frac{1}{2}} d\mathbf{W}_t. \quad (7)$$

Further, the rescaled sequence $\{\check{\mathbf{u}}_n\}_{n=1}^\infty$ converges weakly to the invariant distribution of the dynamics (7), i.e., $\mathcal{N}(\mathbf{0}, \tilde{\Sigma})$. Here the variance $\tilde{\Sigma}$ satisfies the Lyapunov equation

$$\mathcal{P}_{\mathbf{A}^\perp} \left(\nabla^2 f(\mathbf{x}^*) - \frac{1}{2\eta_0} \mathbb{1}_{\{\alpha=1\}} \mathbf{I}_d \right) \tilde{\Sigma} + \tilde{\Sigma} \left(\nabla^2 f(\mathbf{x}^*) - \frac{1}{2\eta_0} \mathbb{1}_{\{\alpha=1\}} \mathbf{I}_d \right) \mathcal{P}_{\mathbf{A}^\perp} = \mathcal{P}_{\mathbf{A}^\perp} \Sigma(\mathbf{x}^*) \mathcal{P}_{\mathbf{A}^\perp}.$$

Remark 1. By using the continuous time version of the Lyapunov theorem (Lemma 1 in [40]), the Lyapunov equation has a unique positive semidefinite solution (denoted $\tilde{\Sigma}$). From Theorem 3.3 and Theorem 4.1.1 in [9], we can tell that when $\beta \in [0, \frac{1}{2})$ our algorithm LPSA achieves the same asymptotic variance as SGD that also uses the same step size. The typical projected SGD corresponds to the case $\beta = 0$, while LPSA allows β to vary in $[0, \frac{1}{2})$. One can reduce the projection frequency by increasing β (equivalently decreasing the probability p_n). Hence, when projection is expensive, LPSA is more efficient in performing projections due to its flexible and moderate projection frequency.

Proof Idea of Theorem 3.3. We shed light on the proof idea of Theorem 3.3. From a high level, we leverage the general theory for operator semigroups, which are developed by Trotter and Kurtz [39, 17–19] and are used to analyze stochastic optimization algorithms in [9]. Our diffusion approximation results are built on it, but generalize it in the sense that we use the celebrated Prokhorov’s theorem to extend to the whole trajectory. One difficulty is to prove the stochastic tightness of $\{\mathbf{u}_t^{(n)}\}$. To that end, we make use of a classic result (e.g. Theorem 7.3 of [4]).

3.2.2 Case 2: Occasional Projection where $\beta \in (1/2, 1)$

When we step into the low-frequency regime where $\beta \in (\frac{1}{2}, 1)$, the situation totally changes. Intuitively, when LPSA performs much less frequent projection, we will frequently use infeasible \mathbf{x}_t to update parameters, which accumulates residual errors. These errors would not only dominate and slow down the non-asymptotic convergence rate (see Theorem 3.1), but also change the asymptotic behavior. In this case, we should not only find the right timescale, but also need to figure out how these errors are accumulated. To solve the issue, we develop a new analysis routine. In the following, we consider $p_t = \gamma\eta_t^\beta$ with $\gamma > 0$.

Our solution is to monitor another random process that is related with $\{\mathbf{v}_n\}$, which serves as a bridge to derive the asymptotic behavior of $\{\mathbf{u}_n\}$. The right scale should make the scaled sequence have non-vanishing expected L_2 norm. From Theorem 3.1, it should be $\tilde{\mathbf{v}}_n = \eta_{n-1}^{\beta-1} \mathbf{v}_n$. In addition, given $\tilde{\mathbf{v}}_n$, the candidate value of $\tilde{\mathbf{v}}_{n+1}$ before tossing the coin ω_n , can be derived from LPSA’s Algorithm 1 in Appendix A, and we denote this candidate as $\tilde{\mathbf{v}}_{(n+1)-}$.

$$\tilde{\mathbf{v}}_{(n+1)-} := \tilde{\mathbf{v}}_n - \eta_n^\beta \mathbf{d}_n + \eta_n^\beta \xi_n^{(2)}, \quad (8)$$

where $\mathbf{d}_n = \nabla f(\mathbf{x}^*) + \eta_n^{-\beta} \mathcal{S}_n$ with \mathcal{S}_n a residual error which satisfies $\eta_n^{-\beta} \mathcal{S}_n = o_{\mathbb{P}}(1)$ (see Appendix C.2 for more details) and $\xi_n^{(2)}$ stands for the component of noise ξ_n on the orthogonal complementary space A^\perp . Due to the probabilistic projection, $\tilde{\mathbf{v}}_{n+1}$ takes value $\tilde{\mathbf{v}}_{(n+1)-}$ with probability $1 - \gamma\eta_n^\beta$ and takes value zero with probability $\gamma\eta_n^\beta$. Similar to the previous section, we then construct a càdlàg random process $\bar{\mathbf{v}}_t^{(n)}$ which starts from $\tilde{\mathbf{v}}_n$ and will pass through $\{\tilde{\mathbf{v}}_{(k)-}\}_{k \geq n}$. We can connect these discrete points with a step function. It results in the following construction

$$\begin{aligned} \bar{\mathbf{v}}_t^{(n)} &= \bar{\mathbf{v}}_{\underline{t}_n(\eta^\beta)}^{(n)} - (t - \underline{t}_n(\eta^\beta)) (\mathbf{d}_{N(n,t,\eta^\beta)} - \xi_{N(n,t,\eta^\beta)}^{(2)}) \text{ if } t \in (\underline{t}_n(\eta^\beta), \underline{t}_n(\eta^\beta) + \eta_{\underline{t}_n(\eta^\beta)}^\beta), \\ \bar{\mathbf{v}}_{\underline{t}_n(\eta^\beta)}^{(n)} &= \tilde{\mathbf{v}}_{N(n,t,\eta^\beta)}. \end{aligned} \quad (9)$$

From (9), we can claim that $\bar{\mathbf{v}}_{\underline{t}_n(\eta^\beta)-}^{(n)} = \tilde{\mathbf{v}}_{N(n,t,\eta^\beta)-}$ for any $t \geq 0$. With probability $p_{N(n,t,\eta^\beta)}$, $\tilde{\mathbf{v}}_{N(n,t,\eta^\beta)}$ takes value zero, which causes the process $\bar{\mathbf{v}}_t^{(n)}$ to change abruptly at the time $\underline{t}_n(\eta^\beta)$. These discontinuities about $\bar{\mathbf{v}}_t^{(n)}$ prevent the diffusion process from working on $\bar{\mathbf{v}}_t^{(n)}$ as the result of Theorem 3.3. Even so, the following theorem shows that we can still find a suitable process in the broader jump diffusion class to approximate $\bar{\mathbf{v}}_t^{(n)}$.

Theorem 3.4 (Jump Approximation). Let Assumptions 1, 2, 4 and 5 hold. The following family of càdlàg stochastic processes $\{\bar{\mathbf{v}}_t^{(n)} : t \geq 0\}_{n=1}^\infty$ weakly converges to the stationary weak solution of the following SDE

$$d\mathbf{Y}_t = -\nabla f(\mathbf{x}^*)dt - \mathbf{Y}_{t-} \cdot \mathbf{N}_\gamma(dt). \quad (10)$$

Here $\mathbf{N}_\gamma(t)$ represents Poisson process with intensity γ , and $\mathbf{N}_\gamma(dt) = \mathbf{N}_\gamma(t) - \mathbf{N}_\gamma(t-)$. Further, the rescaled sequence $\{\tilde{\mathbf{v}}_n\}_{n=1}^\infty$ weakly converges to the invariant distribution of the dynamics (10), i.e., $-\frac{\nabla f(\mathbf{x}^*)}{\|\nabla f(\mathbf{x}^*)\|} \cdot \mathcal{E}\left(\frac{\|\nabla f(\mathbf{x}^*)\|}{\gamma}\right)$. Here $\mathcal{E}(\theta)$ represents the exponential distribution with intensity $\frac{1}{\theta}$.

Theorem 3.4 shows that the sequence $\{\bar{\mathbf{v}}_t^{(n)}\}$ constructed by shifting initial points will finally approximate a jump process with a constant drift as n goes to infinity. The SDE (10) sheds light on how $\bar{\mathbf{v}}_t^{(n)}$ (equivalently a rescaled version of \mathbf{v}_n) move as t increases. As the error incurred by infrequent projections, $\bar{\mathbf{v}}_t^{(n)}$ will move towards the direction of $\nabla f(\mathbf{x}^*)$ (due to the drift term $-\nabla f(\mathbf{x}^*)dt$) and be periodically forced to set as zero vector (due to the correcting term $-\mathbf{Y}_{t-} \cdot \mathbf{N}_\gamma(dt)$). From a qualitative perspective, the SDE (10) captures the periodical behavior of \mathbf{v}_n , hence it shows without projection the residual error will accumulate along the direction of $\nabla f(\mathbf{x}^*)$. As argued in Proposition 1, $\nabla f(\mathbf{x}^*)$ is unlikely to be zero in our constrained problems.

The remaining issue is how to link $\{\bar{\mathbf{v}}_t^{(n)}\}$ to our target $\{\mathbf{u}_n\}$. Similarly, we should consider a rescaled \mathbf{u}_n , that is, $\hat{\mathbf{u}}_n := (\mathbf{u}_n - \mathbf{x}^*)/\eta_{n-1}^{1-\beta}$. The following corollary, which is based on Theorem 3.4, shows when $\beta \in (\frac{1}{2}, 1)$, $\hat{\mathbf{u}}_n$ converges to a non-zero vector. Recall that $\check{\mathbf{u}}_n = \frac{\mathbf{u}_n - \mathbf{x}^*}{\sqrt{\eta_{n-1}}} = \eta_{n-1}^{0.5-\beta} \hat{\mathbf{u}}_n$. The equation together with Corollary 1 implies $\|\mathbb{E}\check{\mathbf{u}}_n\| = \eta_{n-1}^{0.5-\beta} \|\mathbb{E}\hat{\mathbf{u}}_n\| \rightarrow \infty$. As a result, the bias in Corollary 1 instead of the Gaussian fluctuation in Theorem 3.3 becomes the leading term hindering the convergence.

Corollary 1. *Let Assumptions 1- 3 hold. Then $\hat{\mathbf{u}}_n := \frac{1}{\eta_{n-1}^{1-\beta}}(\mathbf{u}_n - \mathbf{x}^*)$ converges to a non-zero vector $\frac{1}{\gamma} \left\{ \mathcal{P}_{A^\perp} \left(\nabla^2 f(\mathbf{x}^*) - \frac{1-\beta}{\eta_0} \mathbb{1}_{\{\alpha=1\}} \mathbf{I} \right) \mathcal{P}_{A^\perp} \right\}^\dagger (\mathcal{P}_{A^\perp} \nabla^2 f(\mathbf{x}^*) \nabla f(\mathbf{x}^*))$ in the L_2 as $n \rightarrow \infty$. Where \mathbf{G}^\dagger denotes the pseudoinverse of the symmetric matrix \mathbf{G} .*

Proof Idea of Theorem 3.4 The main proof idea is similar to that of Theorem 3.4 except that we need to handle the jump diffusion which introduces additional discontinuity. As a result, for each $n \geq 0$, $\{\bar{\mathbf{v}}_t^{(n)}\}_{t \geq n}$ is càdlàg rather than continuous. We then use the approximation result for jump diffusions developed by Kushner [20] instead of Trotter and Kurtz’s theories. Furthermore, the tool for proving tightness also needs to change. We replace the classic tool in [4] with a generalized determination method, the latter used to establish the stochastic tightness for càdlàg processes (e.g., Theorem 4.1 in [19]). The remaining issue is to figure out properties (e.g., the mixing nature) of (10). To that end, we establish the geometric ergodicity of Eq. (10) by combining the coupling method with the Itô’s formula for jump diffusions, and show that its invariant distribution exists uniquely.

3.2.3 Summary and Discussion

From Sections 3.2.1 and 3.2.2, for the choice $p_n \propto \eta_n^\beta$, when β varies, our algorithm has an interesting bias-variance tradeoff. In fact, Theorems 3.3 and 3.4 reveal that the fluctuation of \mathbf{u}_n is of order $\mathcal{O}(\eta_n^{\frac{1}{2}})$ and the bias is of order $\mathcal{O}(\eta_n^{1-\beta})$. When $\beta \in [0, 1/2)$ the fluctuation caused by the randomness of gradient queries in every iteration dominates the optimization accuracy. And when $\beta \in (1/2, 1)$, this indicator is manipulated by the biases formed by the accumulation of skewed updates in the unconstrained state within each ‘inner loop’.

In practice, projection is expensive to perform. Hence, it is important to tune α and β so that the projection complexity is minimized as much as possible. We use the average projection complexity (APC) to quantify the projection efficiency. For a target accuracy $\epsilon > 0$, APC is defined as the number of projections required to obtain an ϵ -accuracy feasible solution. We summarize the derived results and the corresponding APC in Table 1. We can see that APC is minimized when $\alpha \rightarrow 1$ and $\beta \rightarrow 0.5$. In this case, APC is approaching $\frac{1}{\sqrt{\epsilon}}$.

We find an interesting parallelism between LPSA and Local SGD. In the case of FL, projection complexity corresponds to communication complexity, because a synchronization in FL is essentially a projection in linearly constrained problems (see Appendix A for the equivalence). In [27], the authors analyzed the averaged communication complexity (ACC) for Local SGD with Polyak-Ruppert averaging.³ They considered a general case where the length of the m -th inner loop could be up to $E_m := m^\nu$ with $\nu \in [0, 1)$. After E_m steps of inner loop, communication would perform to synchronize local models. Hence, E_m plays a role similar to p_n in our paper. Li et al. [27] found that when $\nu \in [0, 1)$, the averaged Local SGD iterates enjoy an optimal asymptotic normality up

³For a target accuracy $\epsilon > 0$, ACC is defined as the number of communication required to obtain a ϵ -accuracy global parameter.

Table 1: (Non-)Asymptotic results and projection complexity under different choice of η_n and p_n . The first two columns list the non-asymptotic and asymptotic results respectively, and the last column characterizes projection complexity.

(α, β)	$\mathbb{E}\ \mathbf{u}_n - \mathbf{x}^*\ ^2$	Asymptotic behavior	APC
$(0, 1) \times [0, 1/2)$	$\mathcal{O}\left(\frac{1}{n^\alpha}\right)$ 3.1	Normal 3.3	$\mathcal{O}\left(\epsilon^{\beta - \frac{1}{\alpha}}\right)$
$(0, 1) \times (1/2, 1)$	$\mathcal{O}\left(\frac{1}{n^{2\alpha(1-\beta)}}\right)$ 3.1	Biased 1	$\mathcal{O}\left(\epsilon^{\frac{\alpha\beta-1}{2\alpha(1-\beta)}}\right)$

to a known constant scale and its ACC is $\left(\frac{1}{\epsilon}\right)^{\frac{1}{1+\nu}}$. When $\nu \rightarrow 1$, ACC is approaching $\frac{1}{\sqrt{\epsilon}}$, similar to our case where APC converges to $\frac{1}{\sqrt{\epsilon}}$ when $\alpha \rightarrow 1$ and $\beta \rightarrow 0.5$. Actually, the $\frac{1}{\sqrt{\epsilon}}$ average communication complexity is actually optimal for any first-order oracle distributed algorithms, as shown in [43]. Hence, it implies our LSPA is efficient and near optimal in projection, because we can always reduce FL as a special of (1).

4 Experiments

In this section, we validate our theoretical results through comprehensive experiments. Due to space limitations, we only show some representative results on synthetic datasets under FL settings. For the results on general linearly constrained problems, please refer to Appendix D.

Experimental Setup We focus on classification problems with cross entropy loss, and ℓ_2^2 regularization is imposed to ensure the strong convexity of the objective function. The synthetic datasets are generated by following [24]. There are K clients and the sample (\mathbf{x}_k, z_k) on the k -th client is modeled as $\mathbf{x}_k \sim \mathcal{N}(\nu_k, \Lambda)$ and $z_k = \text{argmax}(\text{softmax}(\mathbf{W}_k \mathbf{x}_k + \mathbf{b}_k))$ where $\Lambda \in \mathbb{R}^{d \times d}$ is diagonal with the entry (j, j) equal to $j^{-1.2}$, $\mathbf{W}_k \in \mathbb{R}^{C \times d}$ and $\mathbf{b}_k \in \mathbb{R}^C$. We consider two specific datasets. The first one is denoted by IID, where all the clients share the same \mathbf{W}_k and \mathbf{b}_k , and $\nu_k \sim \mathcal{N}(\mathbf{0}, \mathbf{I}_d)$. For this one, we set $K = 100$, $d = 60$ and $C = 10$. The second one is denoted by Synthetic (a, b) , where a and b control the heterogeneity across clients. Specifically, each entry of \mathbf{W}_k and \mathbf{b}_k is modeled as $\mathcal{N}(\mu_k, 1)$ with $\mu_k \sim \mathcal{N}(0, a)$ and $\nu_k \sim \mathcal{N}(\zeta_k, \mathbf{I})$ with $\zeta_k \sim \mathcal{N}(\mathbf{0}, b\mathbf{I}_d)$. For this dataset, we set $K = 20$, $d = 10$ and $C = 5$.

We find that the results on IID are intuitive enough to demonstrate the convergence rates of the mean squared error (MSE) $\mathbb{E}\|\mathbf{u}_n - \mathbf{x}^*\|^2$ and the asymptotic behavior of $\tilde{\mathbf{u}}_n$ for $\beta \in [0, 1/2)$. The results on Synthetic (a, b) , a dataset with fewer parameters and more heterogeneity, are more appropriate to illustrate the asymptotic biased of $\hat{\mathbf{u}}_n$ for $\beta \in (1/2, 1)$. The full results on both the datasets are deferred to Appendix D.

Convergence Rate We plot the log-log scale graphs of averaged MSEs over 5 repetitions on IID vs iterations in Figure 1. The value of α is set as $\{1, 0.8, 0.6\}$ and the value of β is from $\{0, 0.2, 0.4, 0.6, 0.8\}$. For each repetition, we run 2000 steps of LPSA. By Theorem 3.1, the slope of the line in the log-log scale graph should be $-\alpha \min\{1, 2 - 2\beta\}$. This is in accordance with Figure 1 when the iteration is larger than 100. For $\beta \in [0, 1/2)$, the value of β does not affect the slope, while for $\beta \in (1/2, 1)$, larger β and smaller α both lead to smoother lines.

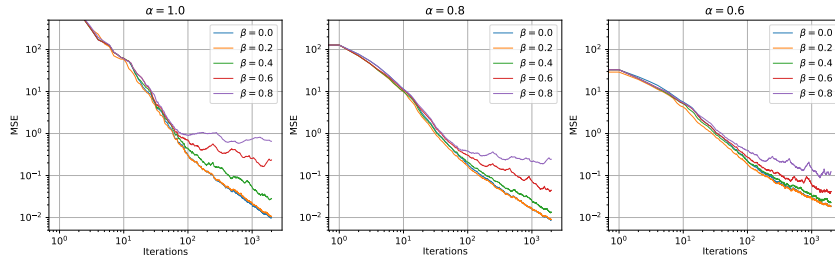


Figure 1: The log-log scale graphs of averaged MSE on IID over 5 repetition vs iterations.

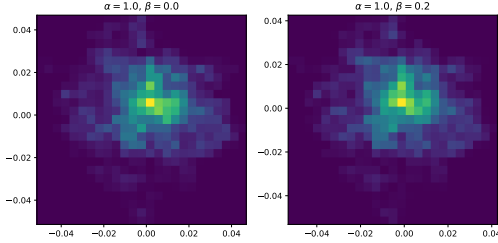


Figure 2: The heatmaps of $\tilde{\mathbf{u}}_n$ across two orthogonal directions over 100 repetitions on IID.

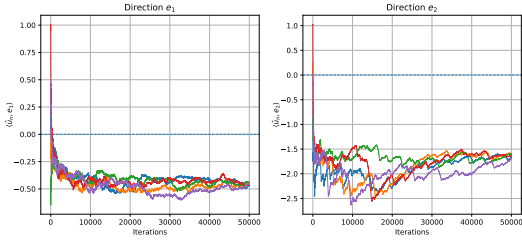


Figure 3: Trajectories of $\hat{\mathbf{u}}_n$ along two random directions over 5 repetitions on Synthetic (1, 1).

Frequent Projection For $\alpha = 1$ and $\beta \in \{0, 0.2\}$, we run 2000 steps of LPSA over 100 repetitions on IID and pick up the last 200 iterates. For these iterates, we compute the rescaled vectors $\tilde{\mathbf{u}}_n$ and project them into a two-dimensional random subspace. Then we plot the heatmaps across the two dimensions in Figure 2. We observe that the cells near the origin have the lightest colors, and as we move away from the origin the cell color becomes darker. Since the cells with lighter colors imply more frequencies, these phenomena agree with Theorem 3.3, where the limiting distribution of $\tilde{\mathbf{u}}_n$ is Gaussian. The results with other values of α and β are deferred to Appendix D.4.

Occasional Projection For $\alpha = 0.8$ and $\beta = 0.6$, we run 50000 steps of LPSA over 5 repetition on Synthetic (1, 1). Then we compute the rescaled sequence $\hat{\mathbf{u}}_n$ and project them along two random directions \mathbf{e}_1 and \mathbf{e}_2 . The trajectories depicted in Figure 3 show that the limits of $\langle \hat{\mathbf{u}}_n, \mathbf{e}_1 \rangle$ and $\langle \hat{\mathbf{u}}_n, \mathbf{e}_2 \rangle$ are nonzero and verify the asymptotic biased of $\hat{\mathbf{u}}_n$ mentioned in Corollary 1. The results with other values of α and β are deferred to Appendix D.6.

5 Concluding Remarks

In this paper we study the linearly constrained optimization problem. We propose the LPSA algorithm that is inspired by Local SGD. The probabilistic projection in LPSA follows the spirit of loopless methods [16, 12, 28] and simplifies the double-loop structure of original Local SGD, facilitating theoretical analysis. We thoroughly analyze the (non-)asymptotic properties of properly scaled trajectories obtained from $\{\mathbf{u}_n\}$ and discover an interesting phase transition where $\{\mathbf{u}_n\}$ changes from asymptotically normal to asymptotically biased as the projection frequency decreases. From a technical level, we generalize jump diffusion approximations to accommodate the particularity and discontinuity of LPSA.

There are also some open problems. It is unclear about the asymptotic behavior of \mathbf{u}_n when $\beta = 0.5$, i.e., $p_n = \Theta(\sqrt{\eta_n})$. The jump diffusion approach fails because we can't analyze $\{\mathbf{u}_n\}$ via the length of $\{\mathbf{v}_n\}$ anymore. It accounts for failure that $\{\tilde{\mathbf{u}}_n\}$ and $\{\tilde{\mathbf{v}}_n\}$ are incompatible in the sense that they use different time scales and the time interpolation. However, we speculate $\tilde{\mathbf{u}}_n$ would finally converge weakly to a non-centred Gaussian distribution. In addition, it is also interesting to analyze the performance of projection complexity of LPSA. From Corollary 1, to achieve a better convergence rate at lower projection frequencies, we must overcome the asymptotically biased nature of \mathbf{u}_n . One feasible approach is to build a 'de-biasing' algorithm which attenuates the effect of \mathbf{v}_n during the update of \mathbf{u}_n . We leave them as future work.

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Checklist

1. For all authors...
 - (a) Do the main claims made in the abstract and introduction accurately reflect the paper's contributions and scope? **[Yes]** See the Introduction part and the comparison with previous works in Appendix A.
 - (b) Did you describe the limitations of your work? **[Yes]** See Section 5.
 - (c) Did you discuss any potential negative societal impacts of your work? **[N/A]** Our work is purely theoretical.
 - (d) Have you read the ethics review guidelines and ensured that your paper conforms to them? **[Yes]**
2. If you are including theoretical results...
 - (a) Did you state the full set of assumptions of all theoretical results? **[Yes]**
 - (b) Did you include complete proofs of all theoretical results? **[Yes]** They are all deferred in the appendix.
3. If you ran experiments...
 - (a) Did you include the code, data, and instructions needed to reproduce the main experimental results (either in the supplemental material or as a URL)? **[Yes]** We describe the experimental details in Appendix D.
 - (b) Did you specify all the training details (e.g., data splits, hyperparameters, how they were chosen)? **[Yes]** See Appendix D.
 - (c) Did you report error bars (e.g., with respect to the random seed after running experiments multiple times)? **[No]**
 - (d) Did you include the total amount of compute and the type of resources used (e.g., type of GPUs, internal cluster, or cloud provider)? **[No]** Our experiments use synthetic datasets to validate the theoretical results. It is easy to reproduce the experiments on an average computer using only CPUs.
4. If you are using existing assets (e.g., code, data, models) or curating/releasing new assets...
 - (a) If your work uses existing assets, did you cite the creators? **[N/A]**
 - (b) Did you mention the license of the assets? **[N/A]**
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5. If you used crowdsourcing or conducted research with human subjects...
 - (a) Did you include the full text of instructions given to participants and screenshots, if applicable? **[N/A]**
 - (b) Did you describe any potential participant risks, with links to Institutional Review Board (IRB) approvals, if applicable? **[N/A]**
 - (c) Did you include the estimated hourly wage paid to participants and the total amount spent on participant compensation? **[N/A]**

A Special Condition: Federated Learning

In this section, we focus on the specific case of Federated Learning (FL). We first present the FL problem and establish the equivalence between LPSA and local SGD. Then we restate our main results under the context of FL. We also discuss related works on distributed optimization.

A.1 The Problem and Reduction

In this subsection, we formulate our algorithm in federated settings and show that it is equivalent to local SGD. Before we proceed, we first give the formal statement of our algorithm

Algorithm 1: Loopless Projected Stochastic Approximation (LPSA)

Input: function f , data distribution \mathcal{D} , initial point \mathbf{x}_0 , step size η_n , projection probability p_n .
Initialization: let $\mathbf{x}_0^{(k)} = \mathbf{x}_0$ for all k .
for $n = 0$ **to** $T - 1$ **do**
 Sample $\zeta_n \sim \mathcal{D}$ and $\omega_n \sim \text{Bernoulli}(p_n)$
 $\mathbf{x}_{n+\frac{1}{2}} = \mathbf{x}_n - \eta_n \nabla f(\mathbf{x}_n, \zeta_n)$
 if $\omega_n = 1$ **then**
 $\mathbf{x}_{n+1} = \mathcal{P}_{\mathbf{A}^\perp} \mathbf{x}_{n+\frac{1}{2}}$
 else
 $\mathbf{x}_{n+1} = \mathbf{x}_{n+\frac{1}{2}}$
 end if
end for
Return: $\mathcal{P}_{\mathbf{A}^\perp} \mathbf{x}_T$.

For typical distributed optimization problems, we can rewrite them as a global consensus problem,

$$\min_{\mathbf{x}^{(1)}, \mathbf{x}^{(2)}, \dots, \mathbf{x}^{(N)}} \frac{1}{N} \sum_{k=1}^N \mathbb{E}_{\zeta^{(k)} \sim \mathcal{D}_k} g(\mathbf{x}^{(k)}, \zeta^{(k)}) \quad \text{s.t. } \mathbf{x}^{(1)} = \dots = \mathbf{x}^{(N)}, \quad (11)$$

where there are N clients, $\mathbf{x}^{(k)}$ is the local parameter at the k -th client and $\zeta^{(k)}$ represents the randomness from this client. If we concatenate all the local parameters as $\mathbf{x} = [(\mathbf{x}^{(1)})^\top, (\mathbf{x}^{(2)})^\top, \dots, (\mathbf{x}^{(N)})^\top]^\top \in \mathbb{R}^{Nd}$ and $\zeta = (\zeta^{(1)}, \zeta^{(2)}, \dots, \zeta^{(N)})^\top$, we can rewrite the equation (11) as the form of equation (1), where $f(\mathbf{x}, \zeta) = \frac{1}{N} \sum_{k=1}^N g(\mathbf{x}^{(k)}, \zeta^{(k)})$, $\mathcal{D} = \mathcal{D}_1 \times \mathcal{D}_2 \times \dots \times \mathcal{D}_N$ and \mathbf{A}^\top is equipped with a particular structure

$$\mathbf{A}^\top = \begin{bmatrix} \mathbf{I}_d & -\mathbf{I}_d & \mathbf{0}_d & \dots & \mathbf{0}_d & \mathbf{0}_d \\ \mathbf{0}_d & \mathbf{I}_d & -\mathbf{I}_d & \dots & \mathbf{0}_d & \mathbf{0}_d \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\ \mathbf{0}_d & \mathbf{0}_d & \mathbf{0}_d & \dots & \mathbf{I}_d & -\mathbf{I}_d \end{bmatrix} \in \mathbb{R}^{(N-1)d \times Nd}. \quad (12)$$

In the expression of \mathbf{A}^\top , $\mathbf{I}_d \in \mathbb{R}^{d \times d}$ is the identity matrix and $\mathbf{0}_d \in \mathbb{R}^{d \times d}$ is the zero matrix. For such an \mathbf{A} , the operators $\mathcal{P}_{\mathbf{A}^\perp}$ and $\mathcal{P}_{\mathbf{A}}$ are easy to compute. One can check that

$$\mathcal{P}_{\mathbf{A}^\perp}(\mathbf{x}) = [\bar{\mathbf{x}}^\top, \bar{\mathbf{x}}^\top, \dots, \bar{\mathbf{x}}^\top]^\top \quad (13)$$

and

$$\mathcal{P}_{\mathbf{A}}(\mathbf{x}) = [(\mathbf{x}^{(1)} - \bar{\mathbf{x}})^\top, (\mathbf{x}^{(2)} - \bar{\mathbf{x}})^\top, \dots, (\mathbf{x}^{(N)} - \bar{\mathbf{x}})^\top]^\top,$$

where $\bar{\mathbf{x}} = \frac{1}{N} \sum_{i=1}^N \mathbf{x}^{(i)}$. Then we can establish the equivalent between LPSA and local SGD. At iteration n , the step $\mathbf{x}_{n+\frac{1}{2}} = \mathbf{x}_n - \eta_n \nabla f(\mathbf{x}_n, \zeta_n)$ represents a step of local update, that is $\mathbf{x}_{n+\frac{1}{2}}^{(k)} = \mathbf{x}_n^{(k)} - \eta_n \nabla g(\mathbf{x}_n^{(k)}, \zeta_n^{(k)})$ for each k . If $\omega_n = 1$, the projection step $\mathbf{x}_{n+1} = \mathcal{P}_{\mathbf{A}^\perp}(\mathbf{x}_{n+\frac{1}{2}})$ becomes a round of communication such that all the local parameters share the same value, i.e.,

$\mathbf{x}_{n+1}^{(k)} = \frac{1}{N} \sum_{i=1}^N \mathbf{x}_{n+\frac{1}{2}}^{(i)}$ for each k ; if $\omega = 0$, no communication happens and $\mathbf{x}_{n+1}^{(k)} = \mathbf{x}_{n+\frac{1}{2}}^{(k)}$. Finally, Algorithm 1 returns the average of all local parameters $\mathcal{P}_{\mathbf{A}^\perp} \mathbf{x}_T = \frac{1}{N} \sum_{k=1}^N \mathbf{x}_T^{(k)}$.

The above reduction analysis implies that under the context of FL, Algorithm 1 becomes a loopless version of local SGD. The main difference between LPSA and original Local SGD is that LPSA has a stochastic length of local updates, which is determined by how frequent we observe $\omega_n = 1$. Since p_n gradually decreases, the expectation of local updates would gradually increase. Such a difference does not deteriorate the convergence under certain conditions, as shown in Theorem 3.1. Moreover, the probabilistic loop also facilitates theoretical analysis.

A.2 Restatement of Theoretical Results

In this subsection, we examine the theoretical results and give a revision of Theorem 3.2 under the FL condition.

For simplicity, we define the population loss function on client k as $g_k(\mathbf{x}^{(k)}) := \mathbb{E}_{\zeta^{(k)} \sim \mathcal{D}_k} g(\mathbf{x}^{(k)}, \zeta^{(k)})$. Then we have $f(\mathbf{x}) = \mathbb{E}_{\zeta \sim \mathcal{D}} f(\mathbf{x}, \zeta) = \frac{1}{N} \sum_{k=1}^N g_k(\mathbf{x}^{(k)})$,

$$\nabla f(\mathbf{x}) = \frac{1}{N} \begin{bmatrix} \nabla g_1(\mathbf{x}^{(1)}) \\ \nabla g_2(\mathbf{x}^{(2)}) \\ \vdots \\ \nabla g_N(\mathbf{x}^{(N)}) \end{bmatrix}$$

and

$$\nabla^2 f(\mathbf{x}) = \frac{1}{N} \begin{bmatrix} \nabla^2 g_1(\mathbf{x}^{(1)}) & \mathbf{0}_d & \cdots & \mathbf{0}_d \\ \mathbf{0}_d & \nabla^2 g_2(\mathbf{x}^{(2)}) & \cdots & \mathbf{0}_d \\ \vdots & \vdots & \ddots & \vdots \\ \mathbf{0}_d & \mathbf{0}_d & \cdots & \nabla^2 g_N(\mathbf{x}^{(N)}) \end{bmatrix}.$$

We first focus on Proposition 1. Note that the solution to (11) must be of the form

$$\mathbf{x}^* = [(\mathbf{x}^{(*)})^\top, (\mathbf{x}^{(*)})^\top, \dots, (\mathbf{x}^{(*)})^\top]^\top \in \mathbb{R}^{Nd}.$$

Proposition 1 implies that the solution satisfies $\frac{1}{N} \sum_{k=1}^N \nabla g_k(\mathbf{x}^{(*)}) = \mathbf{0}$. This equation does not imply that the $\nabla g_k(\mathbf{x}^{(*)})$ are all equal to zero. In fact, under the heterogeneous setting, where the g_k are different due to the diversity across the clients, we typically have $\nabla f(\mathbf{x}^{(*)}) \neq \mathbf{0}$. This is crucial for the validity of Theorem 3.4 and Corollary 1. As for the homogeneous setting where the g_k share the same form, $\frac{1}{N} \sum_{k=1}^N \nabla g_k(\mathbf{x}^{(*)}) = \mathbf{0}$ does imply $\nabla g_k(\mathbf{x}^{(*)}) = \mathbf{0}$ and consequently $\nabla f(\mathbf{x}^{(*)}) = \mathbf{0}$. In this case, Theorem 3.4 and Corollary 1 do not hold any more. However, the homogeneous setting is beyond the scope of our paper and is left for future work. Thus, we assume $\nabla f(\mathbf{x}^*) \neq \mathbf{0}$ from now on.

Now we turn to the results in Section 3.1. With $\mathcal{P}_{\mathbf{A}^\perp}$ described in (13), we have

$$\mathbf{u}_n = [(\bar{\mathbf{x}}_n)^\top, (\bar{\mathbf{x}}_n)^\top, \dots, (\bar{\mathbf{x}}_n)^\top]^\top,$$

where $\bar{\mathbf{x}}_n = \frac{1}{N} \sum_{k=1}^N \mathbf{x}_n^{(k)}$. As a result, $\mathbb{E} \|\mathbf{u}_n - \mathbf{x}^*\|^2 = N \mathbb{E} \|\bar{\mathbf{x}}_n - \mathbf{x}^{(*)}\|^2$. Then Theorem 3.1 guarantees that $\mathbb{E} \|\bar{\mathbf{x}}_n - \mathbf{x}^{(*)}\|^2 = \mathcal{O}(n^{-\alpha \min\{1, 2-2\beta\}})$, which is what we desire. The revision of Theorem 3.2 is deferred to the last part of this subsection.

As for the results in Section 3.2, we first take a glance at Theorem 3.3. Since the expression of $\mathcal{P}_{\mathbf{A}^\perp}$ implies we can just focus on the first d dimensions of (7), Theorem 3.3 actually characterizes the asymptotic behavior of $\frac{\bar{\mathbf{x}}_n - \mathbf{x}^{(*)}}{\sqrt{\eta_{n-1}}}$ when $\beta \in [0, \frac{1}{2})$. Then we consider the bias vector mentioned in Corollary 1. Direct computation shows

$$\mathcal{P}_{\mathbf{A}^\perp} \nabla^2 f(\mathbf{x}^*) \nabla f(\mathbf{x}^*) = \frac{1}{N^2} \mathcal{P}_{\mathbf{A}^\perp} \begin{bmatrix} \nabla^2 g_1(\mathbf{x}^{(*)}) \nabla g_1(\mathbf{x}^{(*)}) \\ \nabla^2 g_2(\mathbf{x}^{(*)}) \nabla g_2(\mathbf{x}^{(*)}) \\ \vdots \\ \nabla^2 g_N(\mathbf{x}^{(*)}) \nabla g_N(\mathbf{x}^{(*)}) \end{bmatrix}$$

$$= \frac{1}{N^3} \begin{bmatrix} \mathbf{I}_d \\ \mathbf{I}_d \\ \vdots \\ \mathbf{I}_d \end{bmatrix} \sum_{k=1}^N \nabla^2 g_k(\mathbf{x}^{(*)}) \nabla g_k(\mathbf{x}^{(*)})$$

Even if $\nabla g_k(\mathbf{x}^{(*)}) \neq 0$ for any k , the bias vector could still be equal to the zero vector. For example, $\nabla^2 g_k(\mathbf{x}^{(*)})$ are all the same and $\sum_{k=1}^N \nabla g_k(\mathbf{x}^{(*)}) = \mathbf{0}$. For such a special case, the convergence of $\mathbb{E} \|\bar{\mathbf{x}}_n - \mathbf{x}^{(*)}\|_2^2$ could be faster, since the leading term hindering the convergence vanishes.

A.2.1 Revision of the Lower Bound

Finally, we present a revised version of Theorem 3.2. Recall that the Hessian matrix $\nabla^2 f(\mathbf{x})$ is a block diagonal matrix. Although Theorem 3.1 provides a counter example for the general case, it does not specify the form of $\nabla^2 f(\mathbf{x})$. Fortunately, with \mathbf{A} defined in (12), we can find a counter example such that $\nabla^2 f(\mathbf{x})$ is a diagonal matrix.

Corollary 2. *Consider the problem (11). If $\eta_n = \eta_0 n^{-\alpha}$ and $p_n = \min\{p_0 \eta_n, 1\}$ with $0 < \alpha \leq 1$, then there exists a quadratic function $f(\mathbf{x})$ such that $\nabla^2 f(\mathbf{x})$ is a diagonal matrix, $\nabla^2 f(\mathbf{x}) \succeq \mathbf{I}_d$ and $\mathbb{E} \|\mathbf{u}_n - \mathbf{x}^*\|^2$ does not converge to 0.*

The proof of Corollary 2 is deferred to Appendix B.3.

A.3 Related Work

In this section, we focus on several works that investigate the asymptotic and dynamical nature of distributed optimization. We can trace this line of research back from the classical work [22] by Kushner et al. Unlike the prevailing federated learning algorithm (multi-step local computation between adjacent communications), Kushner et al. [22] consider a random, incomplete decentralized communication within each iteration. And the randomness of these communications are characterized by a sequence of random gossip matrices $\{\mathbf{W}_n\}$. In particular, the algorithm has the following form,

$$\begin{aligned} \text{Local step: } \mathbf{x}_{n+\frac{1}{2},i} &= \mathbf{x}_{n,i} + \epsilon \mathbf{Y}_{n,i} \\ \text{Gossip step: } \mathbf{x}_{n+1,i} &= \sum_{j=1}^N \omega_{n+1}(i,j) \mathbf{x}_{n+\frac{1}{2},j} \end{aligned} \quad (14)$$

where $\mathbf{W}_n = [\omega_n(i,j)]_{i,j=1}^N$ and N is the number of nodes.

For the algorithm, Kushner et al. [22] proved that the trajectories of the final iteration converge weakly to the solution of the particular ODE as the step size ϵ converges to zero, and formally discussed the weak convergence of the rescaled sequences to the solution of a specific linear SDE (i.e. the diffusion approximation result). However, there are several limitations to this work. First of all, the most critical point is that the above theoretical results are discussed in the case of fixed step sizes. As the iteration increases, the variance term of a stochastic approximation begins to dominate the rate of convergence, and the use of a constant step size at this point will make the effect of variance never fall to zero. So a fixed step size means a fixed and finite total iteration (depending on the constant step size and the required estimation accuracy). This makes all the asymptotic results in [22] less practical. In addition, the article assumes (without proof) some intermediate results such as tightness and weak convergence at the initial point, making his theoretical results incomplete.

Thereafter, Bianchi et al. [2] consider the same random gossip stochastic approximation algorithm. Unlike [22], Bianchi et al. replace the fixed step size with a decreasing step size and obtain the asymptotic normality of rescaled final iteration and Polyak-Ruppert averaging sequence. But note that Bianchi et al. [2] assume that all gossip matrices have the same distribution, implying that their asymptotic results hold only if the communication frequency does not decrease as the iteration increases. This is equivalent to the case in LPSA where the projection probability is set as a constant. In particular, they assume the step size $\gamma_n \sim \frac{1}{n^\alpha}$ satisfies that $\alpha \in (\frac{1}{2}, 1]$. In the end, neither of the above two works analyzes the effect of communication frequency on the asymptotic performance of the distributed stochastic approximation algorithm, which is explicitly reflected in our analysis in the form of bias-variance tradeoff.

B Proof of Section 3.1

In this section, we give the proof of Theorems 3.1 and 3.2.

B.1 Useful Propositions and Lemmas

In this subsection, we present some existing results and auxiliary lemmas useful for our later analysis.

Proposition 2 ([32], Theorem 2.1.9, property of strong convexity). *If $f(\mathbf{x})$ is μ -strongly convex, then we have*

$$\langle \nabla f(\mathbf{x}) - \nabla f(\mathbf{y}), \mathbf{x} - \mathbf{y} \rangle \geq \mu \|\mathbf{x} - \mathbf{y}\|^2, \forall \mathbf{x}, \mathbf{y} \in \mathbb{R}^d.$$

Proposition 3 (Cauchy–Schwarz Inequality). *For any vectors $\mathbf{a}, \mathbf{b} \in \mathbb{R}^d$ and positive number γ , it holds that*

$$2 \langle \mathbf{a}, \mathbf{b} \rangle \leq \gamma \|\mathbf{a}\|^2 + \frac{1}{\gamma} \|\mathbf{b}\|^2.$$

Moreover, for any positive integer n and any vectors $\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_n \in \mathbb{R}^d$, it holds that

$$\left\| \sum_{i=1}^n \mathbf{x}_i \right\|^2 \leq n \sum_{i=1}^n \|\mathbf{x}_i\|^2.$$

Proposition 4 ([25], Proposition 2.1 and Lemma B.1, property of projection). *Suppose that \mathbf{A} is a $p \times q$ matrix. Let $\mathcal{P}_{\mathbf{A}}$ be the projection onto the column space of \mathbf{A} and $\mathcal{P}_{\mathbf{A}^\perp}$ the projection onto the null space of \mathbf{A}^\top . Then we have*

1. *Linearity: $\mathcal{P}_{\mathbf{A}}(\alpha \mathbf{x} + \beta \mathbf{y}) = \alpha \mathcal{P}_{\mathbf{A}}(\mathbf{x}) + \beta \mathcal{P}_{\mathbf{A}}(\mathbf{y})$ for any $\mathbf{x}, \mathbf{y} \in \mathbb{R}^p$ and $\alpha, \beta \in \mathbb{R}$.*
2. *Non-expansiveness: $\max\{\|\mathcal{P}_{\mathbf{A}}(\mathbf{x}) - \mathcal{P}_{\mathbf{A}}(\mathbf{y})\|, \|\mathcal{P}_{\mathbf{A}^\perp}(\mathbf{x}) - \mathcal{P}_{\mathbf{A}^\perp}(\mathbf{y})\|\} \leq \|\mathbf{x} - \mathbf{y}\|$ for any $\mathbf{x}, \mathbf{y} \in \mathbb{R}^p$.*
3. *Orthogonality: any $\mathbf{x} \in \mathbb{R}^p$ can be decomposed uniquely into $\mathbf{x} = \mathbf{u} + \mathbf{v}$ where $\mathbf{u} = \mathcal{P}_{\mathbf{A}^\perp}(\mathbf{x})$ and $\mathbf{v} = \mathcal{P}_{\mathbf{A}}(\mathbf{x})$ satisfying $\langle \mathbf{u}, \mathbf{v} \rangle = 0$.*

More specifically, we have $\mathcal{P}_{\mathbf{A}}(\mathbf{x}) = \mathbf{A}(\mathbf{A}^\top \mathbf{A})^\dagger \mathbf{A}^\top \mathbf{x} = (\mathbf{A}^\top)^\dagger \mathbf{A}^\top \mathbf{x}$ and $\mathcal{P}_{\mathbf{A}^\perp}(\mathbf{x}) = \mathbf{I}_p - \mathcal{P}_{\mathbf{A}}(\mathbf{x}) = (\mathbf{I}_p - \mathbf{A}(\mathbf{A}^\top \mathbf{A})^\dagger \mathbf{A}^\top) \mathbf{x} = (\mathbf{I}_p - (\mathbf{A}^\top)^\dagger \mathbf{A}^\top) \mathbf{x}$ with \dagger the pseudo inverse.

Proposition 5 (Stolz–Cesàro theorem). *Let $\{a_n\}$ and $\{b_n\}$ be two sequences of real numbers such that*

1. *$0 < b_1 < b_2 < \dots < b_n < \dots$ and $\lim_{t \rightarrow \infty} b_t = \infty$.*
2. *$\lim_{n \rightarrow \infty} \frac{a_{n+1} - a_n}{b_{n+1} - b_n} = l \in \mathbb{R}$.*

Then, $\lim_{n \rightarrow \infty} \frac{a_n}{b_n}$ exists and is equal to l .

Lemma 1. *Let $\{r_n\} \subset (0, 1)$ be a sequence of positive numbers that decays to zero monotonically. If $\frac{r_n}{r_{n+1}} - 1 = o(r_n)$, for $p \geq 1$, we have that*

$$\lim_{T \rightarrow \infty} \frac{\sum_{n=1}^T r_n^p \prod_{s=n+1}^T (1 - r_s)}{r_T^{p-1}} = 1.$$

Lemma 2. *Let $\{r_n\} \subset (0, 1)$ be a sequence of positive numbers that decays to zero monotonically and a is a positive number. If $\frac{r_n}{r_{n+1}} - 1 = ar_n + o(r_n)$, for $p \geq 1$ and $1/a > p - 1$, we have*

$$\lim_{T \rightarrow \infty} \frac{\sum_{n=1}^T r_n^p \prod_{s=n+1}^T (1 - r_s)}{r_T^{p-1}} = \frac{1}{1 - a(p - 1)}.$$

Lemma 3. *Let $\{r_n\} \subset (0, 1)$ be a sequence of positive numbers that decays to zero monotonically and $\{s_n\}$ is a sequence of positive numbers. If $\frac{r_n}{r_{n+1}} - 1 = ar_n + o(r_n)$ for $a \geq 0$ and $s_{n+1} = (1 - r_n)s_n + o(r_n)$. Then we have $s_n = o(1)$.*

The proof of the three lemmas are deferred to Appendix B.4.

B.2 Proof of Theorem 3.1

In this subsection, we give the formal statement of Theorem 3.1 and its proof. Before that, we first present the one-step descent lemmas of $\mathbb{E} \|\mathbf{u}_n - \mathbf{x}^*\|^2$ and $\mathbb{E} \|\mathbf{v}_n\|^2$, whose proof is deferred to Appendix B.5.

Lemma 4 (One-step descent of $\mathbb{E} \|\mathbf{u}_n - \mathbf{x}^*\|^2$). *Suppose that Assumptions 1, 2 and 4 hold. Then there exists a n_0 such that for any $n \geq n_0$,*

$$\mathbb{E} \|\mathbf{u}_{n+1} - \mathbf{x}^*\|^2 \leq (1 - \mu\eta_n) \mathbb{E} \|\mathbf{u}_n - \mathbf{x}^*\|^2 + \frac{3L^2}{\mu} \eta_n \mathbb{E} \|\mathbf{v}_n\|^2 + 2\eta_n^2 \Sigma_\star^{(1)}, \quad (15)$$

where $\Sigma_\star^{(1)} := \mathbb{E} \|\mathcal{P}_{\mathcal{A}^\perp} \xi^\star\|^2$ with $\xi^\star = \nabla f(\mathbf{x}^*) - \nabla f(\mathbf{x}^*, \zeta)$, $\zeta \sim \mathcal{D}$.

Lemma 5 (One-step descent of $\mathbb{E} \|\mathbf{v}_n\|^2$). *Suppose that Assumptions 1, 2 and 4 hold. Then there exists a n_0 such that for any $n \geq n_0$*

$$\mathbb{E} \|\mathbf{v}_{n+1}\|^2 \leq \left(1 - \frac{p_n}{2}\right) \mathbb{E} \|\mathbf{v}_n\|^2 + \frac{7L^2\eta_n^2}{p_n} \mathbb{E} \|\mathbf{u}_n - \mathbf{x}^*\|^2 + \frac{7L^2\eta_n^2}{p_n} \|\nabla f(\mathbf{x}^*)\|^2 + 2\eta_n^2 \Sigma_\star^{(2)}, \quad (16)$$

where $\Sigma_\star^{(2)} := \mathbb{E} \|\mathcal{P}_{\mathcal{A}} \xi^\star\|^2$ with $\xi^\star = \nabla f(\mathbf{x}^*) - \nabla f(\mathbf{x}^*, \zeta)$, $\zeta \sim \mathcal{D}$.

Now we are prepared to give the formal statement of Theorem 3.1.

Theorem B.1 (Formal statement of Theorem 3.1). *Suppose that Assumptions 1, 2 and 4 hold. Let $\eta_n = \eta_0 n^{-\alpha}$ and $p_n = \min\{p_0 \eta_n^\beta, 1\}$ with $0 \leq \beta < 1$. Then for (i) $0 < \alpha < 1$ or (ii) $\alpha = 1$ with $\eta_0 > 2/\mu$, we have*

$$\begin{aligned} \mathbb{E} \|\mathbf{u}_n - \mathbf{x}^*\|^2 &= \mathcal{O}(\eta_n + \eta_n^{2-2\beta}) \\ \mathbb{E} \|\mathbf{v}_n\|^2 &= \mathcal{O}(\eta_n^{2-2\beta}) \end{aligned}$$

Proof. (Proof of Theorem B.1)

Let $z_n = \|\mathbf{u}_n - \mathbf{x}^*\|^2 + c_0 \sqrt{\frac{p_n}{\eta_n}} \|\mathbf{v}_n\|^2$ with $c_0 = \sqrt{3/(7\mu)}$. By Lemmas 4 and 5, there exists a n_0 such that for any $n \geq n_0$, we have

$$\begin{aligned} \mathbb{E} z_{n+1} &\leq \left(1 - \min\left\{\mu\eta_n, \frac{p_n}{2}\right\} + 7c_0 L^2 \frac{\eta_n^{3/2}}{p_n^{1/2}}\right) \mathbb{E} z_n + 2\eta_n^2 \Sigma_\star^{(1)} \\ &\quad + 7c_0 L^2 \frac{\eta_n^{3/2}}{p_n^{1/2}} \|\nabla f(\mathbf{x}^*)\|^2 + 2c_0 \eta_n^{3/2} p_n^{1/2} \Sigma_\star^{(2)}. \end{aligned}$$

With $p_n = \min\{p_0 \eta_n^\beta, 1\}$ for some $0 \leq \beta < 1$, there exists a $n_1 \geq n_0$ such that for any $n \geq n_1$, we have $p_n = p_0 \eta_n^\beta$ and

$$\mathbb{E} z_{n+1} \leq \left(1 - \frac{\mu\eta_n}{2}\right) \mathbb{E} z_n + 2\eta_n^2 \Sigma_\star^{(1)} + \frac{7c_0 L^2}{\sqrt{p_0}} \eta_n^{3/2-\beta/2} \|\nabla f(\mathbf{x}^*)\|^2 + 2c_0 \sqrt{p_0} \eta_n^{3/2+\beta/2} \Sigma_\star^{(2)}. \quad (17)$$

For any $T \geq n_1$, applying the recursion (17) ($T - n_1$) times yields

$$\begin{aligned} \mathbb{E} z_T &\leq \mathbb{E} z_{n_1} \prod_{n=n_1}^{T-1} \left(1 - \frac{\mu\eta_n}{2}\right) + 2\Sigma_\star^{(1)} \sum_{n=n_1}^{T-1} \eta_n^2 \prod_{s=n+1}^{T-1} \left(1 - \frac{\mu\eta_s}{2}\right) \\ &\quad + \frac{7c_0 L^2}{\sqrt{p_0}} \|\nabla f(\mathbf{x}^*)\|^2 \sum_{n=n_1}^{T-1} \eta_n^{3/2-\beta/2} \prod_{s=n+1}^{T-1} \left(1 - \frac{\mu\eta_s}{2}\right) \\ &\quad + 2c_0 \sqrt{p_0} \Sigma_\star^{(2)} \sum_{n=n_1}^{T-1} \eta_n^{3/2+\beta/2} \prod_{s=n+1}^{T-1} \left(1 - \frac{\mu\eta_s}{2}\right). \end{aligned} \quad (18)$$

For case (i) where $0 < \alpha < 1$, we have $\eta_n = \eta_0 n^{-\alpha}$. Thus, for the first term, we have

$$\begin{aligned} \mathbb{E} z_{n_1} \prod_{n=n_1}^{T-1} \left(1 - \frac{\mu \eta_n}{2}\right) &\leq \mathbb{E} z_{n_1} \exp\left(-\frac{\mu}{2} \sum_{n=n_1}^{T-1} \eta_n\right) \\ &\leq \mathbb{E} z_{n_1} \exp\left(-\frac{\mu \eta_0 (T^{1-\alpha} - n_1^{1-\alpha})}{2(1-\alpha)}\right). \end{aligned}$$

For other terms, one can check that $\frac{\eta_n}{\eta_{n+1}} - 1 = o(\eta_n)$. Then by Lemma 1, we have

$$\mathbb{E} \|\mathbf{u}_n - \mathbf{x}^*\|^2 \leq \mathbb{E} z_n = \mathcal{O}\left(\frac{c_0 L^2 \|\nabla f(\mathbf{x}^*)\|^2}{\sqrt{p_0} \mu} \eta_n^{1/2-\beta/2}\right) = \mathcal{O}\left(\frac{L^2 \|\nabla f(\mathbf{x}^*)\|^2}{\sqrt{p_0} \mu} \eta_n^{1/2-\beta/2}\right). \quad (19)$$

This implies that there exists a positive number c_1 such that $\mathbb{E} \|\mathbf{u}_n - \mathbf{x}^*\|^2 \leq c_1 \frac{L^2 \|\nabla f(\mathbf{x}^*)\|^2}{\sqrt{p_0} \mu} \eta_n^{1/2-\beta/2}$ for any $n \geq n_1$. Substituting this into (16) yields that

$$\begin{aligned} \mathbb{E} \|\mathbf{v}_{n+1}\|^2 &\leq \left(1 - \frac{p_0 \eta_n^\beta}{2}\right) \mathbb{E} \|\mathbf{v}_n\|^2 + \frac{7c_1 L^4 \|\nabla f(\mathbf{x}^*)\|^2}{p_0^{3/2} \sqrt{\mu}} \eta_n^{5/2-3\beta/2} \mathbb{E} \|\mathbf{u}_n - \mathbf{x}^*\|^2 \\ &\quad + \frac{7L^2}{p_0} \eta_n^{2-\beta} \|\nabla f(\mathbf{x}^*)\|^2 + 2\eta_n^2 \Sigma_\star^{(2)} \end{aligned}$$

hold for any $n \geq n_1$. Following the same argument as before, we can prove

$$\mathbb{E} \|\mathbf{v}_n\|^2 = \mathcal{O}\left(\frac{L^2 \|\nabla f(\mathbf{x}^*)\|^2}{p_0^2} \eta_n^{2-2\beta}\right). \quad (20)$$

Then there exists $c_2 > 0$ such that $\mathbb{E} \|\mathbf{v}_n\|^2 \leq \frac{c_2 L^2 \|\nabla f(\mathbf{x}^*)\|^2}{p_0^2} \eta_n^{2-2\beta}$ for any $n \geq n_1$. Substituting this into (15) yields that

$$\mathbb{E} \|\mathbf{u}_{n+1} - \mathbf{x}^*\|^2 \leq (1 - \mu \eta_n) \mathbb{E} \|\mathbf{u}_n - \mathbf{x}^*\|^2 + \frac{3c_2 L^4 \|\nabla f(\mathbf{x}^*)\|^2}{\mu p_0^2} \eta_n^{3-2\beta} + 2\eta_n^2 \Sigma_\star^{(1)}$$

hold for any $n \geq n_1$. Following the same procedure again, we can obtain

$$\mathbb{E} \|\mathbf{u}_n - \mathbf{x}^*\|^2 = \mathcal{O}\left(\frac{\Sigma_\star^{(1)}}{\mu} \eta_n + \frac{L^4 \|\nabla f(\mathbf{x}^*)\|^2}{\mu^2 p_0^2} \eta_n^{2-2\beta}\right). \quad (21)$$

For case (ii) where $\alpha = 1$ with $\eta_0 > 2/\mu$, we can still obtain (18). Since $\eta_n = \eta_0 t^{-1}$, for the first term on the right-hand side of (18), we have

$$\begin{aligned} \mathbb{E} z_{n_1} \prod_{n=n_1}^{T-1} \left(1 - \frac{\mu \eta_n}{2}\right) &\leq \mathbb{E} z_{n_1} \exp\left(-\frac{\mu}{2} \sum_{n=n_1}^{T-1} \eta_n\right) \\ &\leq \mathbb{E} z_{n_1} \exp\left(-\frac{\mu \eta_0 (\ln T - \ln n_1)}{2}\right) \\ &= \mathcal{O}\left(T^{-\mu \eta_0/2}\right). \end{aligned}$$

For other terms, one can check that $\frac{\eta_n}{\eta_{t+1}} - 1 = \frac{2}{\mu \eta_0} \cdot \frac{\mu \eta_n}{2} + o(\eta_n)$. Then by Lemma 2, we have (19) holds for $\eta_0 > 2/\mu$. Following the same procedure as before, we can also obtain (20). Substituting this into (15) yields that

$$\mathbb{E} \|\mathbf{u}_{n+1} - \mathbf{x}^*\|^2 \leq (1 - \mu \eta_n) \mathbb{E} \|\mathbf{u}_n - \mathbf{x}^*\|^2 + \frac{3c_2 L^2}{\mu} \eta_n^{3-2\beta} + 2\eta_n^2 \Sigma_\star^{(1)}$$

holds for any $n \geq n_1$. Since $\frac{\eta_n}{\eta_{t+1}} - 1 = \frac{1}{\mu \eta_0} \cdot \mu \eta_n + o(\eta_n)$, following the same procedure as before, we can obtain (21) for $\eta_0 > 2/\mu > \max\{2 - 2\beta, 1\}/\mu$. \square

B.3 Proof of Theorem 3.2

We first give a formal statement of Theorem 3.2 that can combine Theorem 3.2 and Corollary 2.

Theorem B.2. *If $\eta_n = \eta_0 n^{-\alpha}$ and $p_n = \min\{p_0 \eta_n, 1\}$ with $0 < \alpha \leq 1$, for a specific $\mathbf{A} \in \mathbb{R}^{p \times r}$ with $r < p$, there exists a quadratic function $f(\mathbf{x})$ defined on \mathbb{R}^p so that $\nabla^2 f(\mathbf{x}) \succeq \mathbf{I}_p$ and $\mathbb{E} \|\mathbf{u}_n - \mathbf{x}^*\|^2$ does not converge to 0. Here $\mathbf{I}_p \in \mathbb{R}^{p \times p}$ is the identity matrix, and $\nabla^2 f(\mathbf{x}) \succeq \mathbf{I}_p$ means $\nabla^2 f(\mathbf{x}) - \mathbf{I}_p$ is positive semidefinite. Moreover, if $\mathcal{P}_{\mathbf{A}}$ is not of the form $\mathcal{P}_{\mathbf{A}} = \sum_{i \in I} \mathbf{e}_i \mathbf{e}_i^\top$, where $I \subseteq \{1, 2, \dots, p\}$ and \mathbf{e}_i is the unit vector in \mathbb{R}^p with the i -th element equal to 1, $\nabla^2 f(\mathbf{x})$ can be chosen as a diagonal matrix such that $\nabla^2 f(\mathbf{x}) \succeq \mathbf{I}_p$.*

Before give the proof of Theorem B.2, we first give the proof of Corollary 2 based on Theorem B.1.

Proof. (Proof of Corollary 2)

With \mathbf{A} defined in (12), we have $p = Nd$ and $r = (N - 1)d$. Recall that for $\mathbf{x} = [(\mathbf{x}^{(1)})^\top, (\mathbf{x}^{(2)})^\top, \dots, (\mathbf{x}^{(N)})^\top]^\top \in \mathbb{R}^{Nd}$, we have

$$\mathcal{P}_{\mathbf{A}^\perp}(\mathbf{x}) = [\bar{\mathbf{x}}^\top, \bar{\mathbf{x}}^\top, \dots, \bar{\mathbf{x}}^\top]^\top$$

where $\bar{\mathbf{x}} = \frac{1}{N} \sum_{k=1}^N \mathbf{x}^{(k)}$. As a result, we have $\mathcal{P}_{\mathbf{A}^\perp} \mathbf{e}_1 = \frac{1}{N} \sum_{k=0}^{N-1} \mathbf{e}_{1+kd}$. This implies that $\mathcal{P}_{\mathbf{A}^\perp}$ can not be of the form $\mathcal{P}_{\mathbf{A}^\perp} = \sum_{i \in I} \mathbf{e}_i \mathbf{e}_i^\top$. Thus, $\nabla^2 f(\mathbf{x})$ can be chosen as a diagonal matrix. \square

Now we present the proof of Theorem B.2.

Proof. (Proof of Theorem B.2)

Consider the quadratic function $f(\mathbf{x}) = \frac{1}{2} \mathbf{x}^\top \mathbf{B} \mathbf{x} + \mathbf{c}^\top \mathbf{x}$ where the positive definite matrix $\mathbf{B} \in \mathbb{R}^{p \times p}$ and the vector $\mathbf{c} \in \mathbb{R}^p$ are specified later.

The exact solution to problem (1) We first compute the exact solution to problem (1), where $\mathbf{A} \in \mathbb{R}^{p \times r}$ for some positive integer $r < p$. With out loss of generalization, we assume $\text{rank}(\mathbf{A}) = r$.

Suppose that the singular value decomposition (SVD) of \mathbf{A} is $\mathbf{A} = \mathbf{U} \mathbf{D}_A \mathbf{V}^\top$ where $\mathbf{U} \in \mathbb{R}^{p \times p}$ and $\mathbf{V} \in \mathbb{R}^{r \times r}$ are orthogonal matrices and $\mathbf{D}_A \in \mathbb{R}^{p \times r}$ is a rectangular diagonal matrix with diagonal entries in descending order. One can check that the solution to $\mathbf{A}^\top \mathbf{x} = \mathbf{0}$ has the form $\mathbf{x} = (\mathbf{I}_p - (\mathbf{A}^\top)^\dagger \mathbf{A}^\top) \mathbf{w} = \mathcal{P}_{\mathbf{A}^\perp}(\mathbf{w})$ where \mathbf{w} is an arbitrary vector in \mathbb{R}^p and $(\mathbf{A}^\top)^\dagger$ is the pseudo inverse of \mathbf{A}^\top . From the SVD of \mathbf{A} , we have

$$\mathbf{I}_p - (\mathbf{A}^\top)^\dagger \mathbf{A}^\top = \mathbf{U} \begin{bmatrix} \mathbf{0}_r & \mathbf{0}_{r \times (p-r)} \\ \mathbf{0}_{(p-r) \times r} & \mathbf{I}_{p-r} \end{bmatrix} \mathbf{U}^\top,$$

where $\mathbf{0}_{m \times n} \in \mathbb{R}^{m \times n}$ denote the zero matrix and reduces to $\mathbf{0}_n \in \mathbb{R}^{n \times n}$ for $m = n$. We denote the first r columns of \mathbf{U} by \mathbf{U}_1 and last $p - r$ columns of \mathbf{U} by \mathbf{U}_2 for simplicity, Then the problem (1) becomes the following unconstrained problem

$$\begin{aligned} & \min_{\mathbf{w} \in \mathbb{R}^p} \frac{1}{2} \mathbf{w}^\top (\mathbf{I}_p - (\mathbf{A}^\top)^\dagger \mathbf{A}^\top)^\top \mathbf{B} (\mathbf{I}_p - (\mathbf{A}^\top)^\dagger \mathbf{A}^\top) \mathbf{w} + \mathbf{w}^\top (\mathbf{I}_p - (\mathbf{A}^\top)^\dagger \mathbf{A}^\top)^\top \mathbf{c}. \\ & = \min_{\mathbf{w}_2 \in \mathbb{R}^{p-r}} \frac{1}{2} \mathbf{w}_2^\top \mathbf{B}_2 \mathbf{w}_2 + \mathbf{w}_2^\top \mathbf{c}_2, \end{aligned}$$

where $\mathbf{w}_2 = \mathbf{U}_2^\top \mathbf{w}$, $\mathbf{B}_2 = \mathbf{U}_2^\top \mathbf{B} \mathbf{U}_2$ and $\mathbf{c}_2 = \mathbf{U}_2^\top \mathbf{c}$. The solution is $\mathbf{w}_2^* = -\mathbf{B}_2^{-1} \mathbf{c}_2$. From the expression of $\mathbf{I}_p - (\mathbf{A}^\top)^\dagger \mathbf{A}^\top$, we know that the first r elements of $\mathbf{U}^\top \mathbf{w}$ will not affect the value of \mathbf{x} . Thus, the solution to the original problem (1) is $\mathbf{x}^* = -\mathbf{U}_2 \mathbf{B}_2^{-1} \mathbf{c}_2$.

Moreover, one can check

$$\mathcal{P}_{\mathbf{A}} = \mathbf{U} \begin{bmatrix} \mathbf{I}_r & \mathbf{0}_{r \times (p-r)} \\ \mathbf{0}_{(p-r) \times r} & \mathbf{0}_{(p-r) \times (p-r)} \end{bmatrix} \mathbf{U}^\top = \mathbf{U}_1 \mathbf{U}_1^\top$$

and

$$\mathcal{P}_{\mathbf{A}^\perp} = \mathbf{U} \begin{bmatrix} \mathbf{0}_{r \times r} & \mathbf{0}_{r \times (p-r)} \\ \mathbf{0}_{(p-r) \times r} & \mathbf{I}_{p-r} \end{bmatrix} \mathbf{U}^\top = \mathbf{U}_2 \mathbf{U}_2^\top.$$

Recursions of $\mathbb{E}u_n$ and $\mathbb{E}v_n$ From the definition of u_n and the linearity of \mathcal{P}_{A^\perp} , we have

$$\begin{aligned} u_{n+1} - x^* &= \mathcal{P}_{A^\perp}(x_n - \eta_n B x_n - \eta_n c + \eta_n \xi_n) - x^* \\ &= u_n - x^* - \eta_n \mathcal{P}_{A^\perp}(B x_n + c) + \eta_n \mathcal{P}_{A^\perp} \xi_n \\ &= u_n - x^* - \eta_n \mathcal{P}_{A^\perp} B(u_n - x^*) - \eta_n \mathcal{P}_{A^\perp} B v_n - \eta_n \mathcal{P}_{A^\perp}(B x^* + c) + \eta_n \mathcal{P}_{A^\perp} \xi_n \\ &= u_n - x^* - \eta_n \mathcal{P}_{A^\perp} B \mathcal{P}_{A^\perp}(u_n - x^*) - \eta_n \mathcal{P}_{A^\perp} B v_n - \eta_n \mathcal{P}_{A^\perp}(B x^* + c) + \eta_n \mathcal{P}_{A^\perp} \xi_n. \end{aligned}$$

The optimality of x^* implies that $\mathcal{P}_{A^\perp}(B x^* + c) = \mathbf{0}$. Taking expectation yields

$$\mathbb{E}u_{n+1} - x^* = (\mathbf{I}_p - \eta_n \mathcal{P}_{A^\perp} B \mathcal{P}_{A^\perp})(\mathbb{E}u_n - x^*) - \eta_n \mathcal{P}_{A^\perp} B \mathbb{E}v_n. \quad (22)$$

As for the iteration of $\mathbb{E}v_t$. From the definition of v_n , with probability $1 - p_n$ we have

$$\begin{aligned} v_{t+1} &= \mathcal{P}_A(x_n - \eta_n B x_n - \eta_n c + \eta_n \xi_n) \\ &= v_n - \eta_n \mathcal{P}_A(B x_n + c) + \eta_n \mathcal{P}_A \xi_n \\ &= v_n - \eta_n \mathcal{P}_A B(u_n - x^*) - \eta_n \mathcal{P}_A B v_n - \eta_n \mathcal{P}_A(B x^* + c) + \eta_n \mathcal{P}_A \xi_n \\ &= (\mathbf{I}_p - \eta_n \mathcal{P}_A B \mathcal{P}_A)v_n - \eta_n \mathcal{P}_A B(u_n - x^*) - \eta_n \mathcal{P}_A(B x^* + c) + \eta_n \mathcal{P}_A \xi_n, \end{aligned}$$

and with probability p_n we have $v_{n+1} = \mathbf{0}$. Taking expectation yields

$$\mathbb{E}v_{n+1} = (1 - p_n)(\mathbf{I}_p - \eta_n \mathcal{P}_A B \mathcal{P}_A)\mathbb{E}v_n - (1 - p_n)\eta_n [\mathcal{P}_A B(\mathbb{E}u_n - x^*) + \mathcal{P}_A(B x^* + c)]. \quad (23)$$

Simultaneous diagonalization of $\mathcal{P}_A B \mathcal{P}_A$ and $\mathcal{P}_{A^\perp} B \mathcal{P}_{A^\perp}$ We first express the two matrices as follows:

$$\begin{aligned} \mathcal{P}_A B \mathcal{P}_A &= U \begin{bmatrix} \mathbf{I}_r & \mathbf{0}_{r \times (n-r)} \\ \mathbf{0}_{(n-r) \times r} & \mathbf{0}_{n-r} \end{bmatrix} U^\top B U \begin{bmatrix} \mathbf{I}_r & \mathbf{0}_{r \times (n-r)} \\ \mathbf{0}_{(n-r) \times r} & \mathbf{0}_{n-r} \end{bmatrix} U^\top \\ &= U \begin{bmatrix} B_1 & \mathbf{0}_{r \times (n-r)} \\ \mathbf{0}_{(n-r) \times r} & \mathbf{0}_{n-r} \end{bmatrix} U^\top, \\ \mathcal{P}_{A^\perp} B \mathcal{P}_{A^\perp} &= U \begin{bmatrix} \mathbf{0}_r & \mathbf{0}_{r \times (n-r)} \\ \mathbf{0}_{(n-r) \times r} & \mathbf{I}_{n-r} \end{bmatrix} U^\top B U \begin{bmatrix} \mathbf{0}_r & \mathbf{0}_{r \times (n-r)} \\ \mathbf{0}_{(n-r) \times r} & \mathbf{I}_{n-r} \end{bmatrix} U^\top \\ &= U \begin{bmatrix} \mathbf{0}_r & \mathbf{0}_{r \times (n-r)} \\ \mathbf{0}_{(n-r) \times r} & B_2 \end{bmatrix} U^\top, \end{aligned}$$

where $B_1 = U_1^\top B U_1$ and $B_2 = U_2^\top B U_2$ are positive definite. We suppose the eigenvalue decomposition of B_1 and B_2 is $B_1 = Q_1 D_{B_1} Q_1^\top$ and $B_2 = Q_2 D_{B_2} Q_2^\top$. With $Q := \begin{bmatrix} Q_1 & \mathbf{0}_{r \times (n-r)} \\ \mathbf{0}_{(n-r) \times r} & Q_2 \end{bmatrix}$ and $P := UQ$, we obtain the eigenvalue decomposition of $\mathcal{P}_{A^\perp} B \mathcal{P}_{A^\perp}$ and $\mathcal{P}_A B \mathcal{P}_A$ as follows

$$\mathcal{P}_A B \mathcal{P}_A = P \begin{bmatrix} D_{B_1} & \mathbf{0}_{r \times (n-r)} \\ \mathbf{0}_{(n-r) \times r} & \mathbf{0}_{n-r} \end{bmatrix} P^\top =: P \tilde{D}_{B_1} P^\top$$

and

$$\mathcal{P}_{A^\perp} B \mathcal{P}_{A^\perp} = P \begin{bmatrix} \mathbf{0}_r & \mathbf{0}_{r \times (n-r)} \\ \mathbf{0}_{(n-r) \times r} & D_{B_2} \end{bmatrix} P^\top =: P \tilde{D}_{B_2} P^\top.$$

Proof by contradiction Left multiplication of (23) by P^\top yields

$$\mathbb{E}\tilde{v}_{n+1} = (\mathbf{I}_p - \tilde{D}_n)\mathbb{E}\tilde{v}_n - \eta_n(1 - p_n)\mathbf{B}_0(\mathbb{E}u_n - x^*) - (1 - p_n)\eta_n c_0. \quad (24)$$

where $\tilde{v}_n := P^\top v_n$, $\mathbf{B}_0 := P^\top \mathcal{P}_A B$, $\tilde{D}_n := \eta_n \tilde{D}_{B_1} + p_n \mathbf{I}_p - \eta_n p_n \tilde{D}_{B_1}$ and $c_0 := P^\top \mathcal{P}_A(B x^* + c)$. Adding $(p_0 \mathbf{I}_p + \tilde{D}_{B_1})^{-1} c_0$ to both sides of (24), we obtain

$$\begin{aligned} &\mathbb{E}\tilde{v}_{n+1} + (p_0 \mathbf{I}_p + \tilde{D}_{B_1})^{-1} c_0 \\ &= (\mathbf{I}_p - \tilde{D}_n)\mathbb{E}\tilde{v}_n - \eta_n(1 - p_n)\mathbf{B}_0(\mathbb{E}u_n - x^*) - (1 - p_n)\eta_n c_0 + (p_0 \mathbf{I}_p + \tilde{D}_{B_1})^{-1} c_0 \\ &= (\mathbf{I}_p - \tilde{D}_n)[\mathbb{E}\tilde{v}_n + (p_0 \mathbf{I}_p + \tilde{D}_{B_1})^{-1} c_0] - \eta_n(1 - p_n)\mathbf{B}_0(\mathbb{E}u_n - x^*) \end{aligned}$$

$$+ [p_n - p_0\eta_n(1 - p_n)](p_0\mathbf{I}_p + \tilde{\mathbf{D}}_{B_1})^{-1}\mathbf{c}_0. \quad (25)$$

Suppose $\mathbb{E}\|\mathbf{u}_n - \mathbf{x}^*\|^2 = o(1)$, which implies $\mathbb{E}\mathbf{u}_n - \mathbf{x}^* = o(1)$. Let $\tilde{\mathbf{D}}_n = \text{diag}\{\tilde{d}_{n,1}, \tilde{d}_{n,2}, \dots, \tilde{d}_{n,p}\}$ and $\tilde{\mathbf{D}}_{B_1} = \text{diag}\{\tilde{d}_{B_1,1}, \tilde{d}_{B_1,2}, \dots, \tilde{d}_{B_1,p}\}$. Left multiplication of (25) by \mathbf{e}_i^\top gives

$$\left| \mathbb{E}\mathbf{e}_i^\top \tilde{\mathbf{v}}_{n+1} + \frac{1}{p_0 + \tilde{d}_{B_1,i}} \mathbf{e}_i^\top \mathbf{c}_0 \right| \leq (1 - \tilde{d}_{n,i}) \left| \mathbb{E}\mathbf{e}_i^\top \tilde{\mathbf{v}}_n + \frac{1}{p_0 + \tilde{d}_{B_1,i}} \mathbf{e}_i^\top \mathbf{c}_0 \right| + o(\eta_n),$$

where \mathbf{e}_i is the unit vector with the i -th element equal to 1. Since $\tilde{d}_{n,i} = \eta_n d_{B_1,i}(1 - p_n) + p_n$ and $p_n = \min\{p_0\eta_n, 1\}$, $o(\eta_n) = o(\tilde{d}_{n,i})$. Lemma 3 implies $\mathbb{E}\mathbf{e}_i^\top \tilde{\mathbf{v}}_{n+1} = -\frac{1}{p_0 + \tilde{d}_{B_1,i}} \mathbf{e}_i^\top \mathbf{c}_0 + o(1)$. It follows that $\mathbb{E}\tilde{\mathbf{v}}_n = -(p_0\mathbf{I}_p + \tilde{\mathbf{D}}_{B_1})^{-1}\mathbf{c}_0 + o(1)$. Thus we have

$$\mathbb{E}\mathbf{v}_n = -\mathbf{P}(p_0\mathbf{I}_p + \tilde{\mathbf{D}}_{B_1})^{-1}\mathbf{P}^\top \mathcal{P}_A(\mathbf{B}\mathbf{x}^* + \mathbf{c}) + o(1). \quad (26)$$

Denote the limit of $\mathbb{E}\mathbf{v}_n$ by \mathbf{v}_∞ and we come back to the iteration (22). Left multiplication of (22) by \mathbf{P}^\top yields

$$\mathbb{E}\tilde{\mathbf{u}}_{n+1} = (\mathbf{I}_p - \eta_n \tilde{\mathbf{D}}_{B_2})\mathbb{E}\tilde{\mathbf{u}}_n - \eta_n \mathbf{P}^\top \mathcal{P}_{A^\perp} \mathbf{B}\mathbf{v}_\infty + o(\eta_n),$$

where $\tilde{\mathbf{u}}_n = \mathbf{P}^\top(\mathbf{u}_n - \mathbf{x}^*)$. Similar to the above argument, adding $\mathbf{P}^\top \mathcal{P}_{A^\perp} \mathbf{B}\mathbf{v}_\infty$ to both sides and using Lemma 3, we can obtain

$$\begin{aligned} \mathbb{E}\tilde{\mathbf{u}}_n &= -\mathbf{P}^\top \mathcal{P}_{A^\perp} \mathbf{B}\mathbf{v}_\infty + o(1) \\ &= \mathbf{P}^\top \mathcal{P}_{A^\perp} \mathbf{B}\mathbf{P}(p_0\mathbf{I}_p + \tilde{\mathbf{D}}_{B_1})^{-1}\mathbf{P}^\top \mathcal{P}_A(\mathbf{B}\mathbf{x}^* + \mathbf{c}) + o(1). \end{aligned}$$

It remains to prove that there exists a positive definite matrix $\mathbf{B} \in \mathbb{R}^{p \times p}$ and a vector $\mathbf{c} \in \mathbb{R}^p$ such that the limit is nonzero.

Specification of \mathbf{B} and \mathbf{c} From the expression of \mathbf{x}^* , we have

$$\mathbf{B}\mathbf{x}^* + \mathbf{c} = \mathbf{c} - \mathbf{B}\mathbf{U}_2(\mathbf{U}_2^\top \mathbf{B}\mathbf{U}_2)^{-1}\mathbf{U}_2^\top \mathbf{c} = (\mathbf{I}_p - \mathbf{B}\mathbf{U}_2(\mathbf{U}_2^\top \mathbf{B}\mathbf{U}_2)^{-1}\mathbf{U}_2^\top)\mathbf{c}.$$

Define $\tilde{\mathbf{B}} := \mathbf{I}_p - \mathbf{B}\mathbf{U}_2(\mathbf{U}_2^\top \mathbf{B}\mathbf{U}_2)^{-1}\mathbf{U}_2^\top$ for short. We examine the column space of $\tilde{\mathbf{B}}$, which is denoted by $\mathcal{R}(\tilde{\mathbf{B}})$. We can easily find $\mathbf{U}_2^\top \tilde{\mathbf{B}} = \mathbf{0}_{(p-r) \times r}$. Thus $\mathcal{R}(\tilde{\mathbf{B}}) \subseteq \mathcal{R}(\mathbf{U}_1)$. On the other hand, we have $\tilde{\mathbf{B}}\mathbf{U}_1 = \mathbf{U}_1$, which implies $\text{rank}(\tilde{\mathbf{B}}) \geq \text{rank}(\mathbf{U}_1)$. As a result, $\mathcal{R}(\tilde{\mathbf{B}}) = \mathcal{R}(\mathbf{U}_1)$. Then for any $\mathbf{z} \in \mathbb{R}^r$, there exists a $\mathbf{c} \in \mathbb{R}^p$ such that $\tilde{\mathbf{B}}\mathbf{c} = \mathbf{U}_1\mathbf{z}$. It suffices to prove that there exists a positive definite matrix $\mathbf{B} \in \mathbb{R}^{p \times p}$ and a vector $\mathbf{z} \in \mathbb{R}^r$ such that $\mathbf{P}^\top \mathcal{P}_{A^\perp} \mathbf{B}\mathbf{P}(p_0\mathbf{I}_p + \tilde{\mathbf{D}}_{B_1})^{-1}\mathbf{P}^\top \mathcal{P}_A \mathbf{U}_1\mathbf{z}$ is nonzero.

Since $\mathbf{P} = \mathbf{U}\mathbf{Q}$, $\mathcal{P}_A = \mathbf{U}_1\mathbf{U}_1^\top$, $\mathcal{P}_{A^\perp} = \mathbf{U}_2\mathbf{U}_2^\top$, $\mathbf{Q} = \begin{bmatrix} \mathbf{Q}_1 & \mathbf{0}_{r \times (n-r)} \\ \mathbf{0}_{(n-r) \times r} & \mathbf{Q}_2 \end{bmatrix}$, $\tilde{\mathbf{D}}_{B_1} = \begin{bmatrix} \mathbf{D}_{B_1} & \mathbf{0}_{r \times (n-r)} \\ \mathbf{0}_{(n-r) \times r} & \mathbf{0}_{n-r} \end{bmatrix}$ and $\mathbf{B}_1 = \mathbf{Q}_1 \mathbf{D}_{B_1} \mathbf{Q}_1^\top$, we have

$$\begin{aligned} & \mathbf{P}^\top \mathcal{P}_{A^\perp} \mathbf{B}\mathbf{P}(p_0\mathbf{I}_p + \tilde{\mathbf{D}}_{B_1})^{-1}\mathbf{P}^\top \mathcal{P}_A \mathbf{U}_1\mathbf{z} \\ &= \mathbf{Q}^\top \mathbf{U}^\top \mathbf{U}_2 \mathbf{U}_2^\top \mathbf{B}\mathbf{U}\mathbf{Q}(p_0\mathbf{I}_p + \tilde{\mathbf{D}}_{B_1})^{-1}\mathbf{Q}^\top \mathbf{U}^\top \mathbf{U}_1\mathbf{z} \\ &= \mathbf{Q}^\top \begin{bmatrix} \mathbf{0} \\ \mathbf{U}_2^\top \end{bmatrix} \mathbf{B}[\mathbf{U}_1 \ \mathbf{U}_2] \begin{bmatrix} (p_0\mathbf{I}_r + \mathbf{B}_1)^{-1} & \mathbf{0}_{r \times (p-r)} \\ \mathbf{0}_{(p-r) \times r} & \frac{1}{p_0}\mathbf{I}_{p-r} \end{bmatrix} \begin{bmatrix} \mathbf{z} \\ \mathbf{0} \end{bmatrix} \\ &= \mathbf{Q}^\top \begin{bmatrix} \mathbf{0} \\ \mathbf{U}_2^\top \mathbf{B}\mathbf{U}_1(p_0\mathbf{I}_p + \tilde{\mathbf{D}}_{B_1})^{-1} \end{bmatrix} \mathbf{z}. \end{aligned}$$

Then it suffices to prove that there exist a positive matrix $\mathbf{B} \in \mathbb{R}^{p \times p}$ such that $\mathbf{U}_2^\top \mathbf{B}\mathbf{U}_1$ is nonzero. Suppose that $\mathbf{U}_1 = (\mathbf{p}_1, \mathbf{p}_2, \dots, \mathbf{p}_r) = (p_{ki})_{p \times r}$ and $\mathbf{U}_2 = (\mathbf{q}_1, \mathbf{q}_2, \dots, \mathbf{q}_{p-r}) = (q_{kj})_{p \times (p-r)}$. Then the column vectors of \mathbf{U}_1 and \mathbf{U}_2 form an orthonormal basis of \mathbb{R}^p .

If there exist i, j and k_0 such that $p_{k_0 i} q_{k_0 j} \neq 0$, Then we can take \mathbf{B} as a diagonal matrix $\mathbf{I}_p + \mathbf{E}_{k_0 k_0}$ where \mathbf{E}_{ij} is the $p \times p$ matrix with (i, j) entry equal to 1 and others equal to 0. The (j, i) entry of $\mathbf{U}_2^\top \mathbf{B}\mathbf{U}_1$ is $\sum_{k=1}^p p_{ki} q_{kj} + p_{k_0 i} q_{k_0 j} = p_{k_0 i} q_{k_0 j} \neq 0$. And one can check $\mathbf{B} \succeq \mathbf{I}_p$.

Otherwise, there must exist i, j, k_0 and l_0 such that $p_{k_0 i} q_{l_0 j} \neq 0$ and $k_0 \neq l_0$. Since in this case $p_{k i} q_{k j} = 0$ for any k , then we have $q_{k_0 j} = p_{l_0 i} = 0$. We take $\mathbf{B} = 2\mathbf{I}_p + \mathbf{E}_{k_0 l_0} + \mathbf{E}_{l_0 k_0}$. Then the (j, i) entry of $\mathbf{U}_2^\top \mathbf{B} \mathbf{U}_1$ is $2 \sum_{k=1}^p p_{k i} q_{k j} + p_{k_0 i} q_{l_0 j} + p_{l_0 i} q_{k_0 j} = p_{k_0 i} q_{l_0 j} \neq 0$. And one can check $\mathbf{B} \succeq \mathbf{I}_p$.

As a result, there always exists \mathbf{B} and \mathbf{c} such that the limit of $\|\mathbb{E}\tilde{\mathbf{u}}_n\|$ is nonzero. This implies $\mathbb{E}\|\mathbf{u}_n - \mathbf{x}^*\|^2 \neq o(1)$, which induces a contradiction.

In the latter case, for any $\mathbf{e}_i \in \mathbb{R}^p$, either $\mathbf{e}_i^\top \mathbf{U}_1$ or $\mathbf{e}_i^\top \mathbf{U}_2$ is zero. Note that \mathbf{U}_1 and \mathbf{U}_2 are of full column rank. Then we have $\mathbf{U}_1 = \sum_{i \in I_1} \mathbf{e}_i \tilde{\mathbf{p}}_i^\top$ and $\mathbf{U}_2 = \sum_{j \in I_2} \mathbf{e}_j \tilde{\mathbf{q}}_j^\top$ where $|I_1| = r$, $|I_2| = p - r$, $I_1 \cup I_2 = \{1, 2, \dots, p\}$, $I_1 \cap I_2 = \emptyset$, $\tilde{\mathbf{p}}_i$ ($i \in I_1$) are orthonormal basis of \mathbb{R}^r and $\tilde{\mathbf{q}}_j$ ($j \in I_2$) are orthonormal basis of \mathbb{R}^{p-r} . As a consequence, $\mathcal{P}_A = \mathbf{U}_1 \mathbf{U}_1^\top = \sum_{i \in I_1} \mathbf{e}_i \mathbf{e}_i^\top$ and $\mathcal{P}_{A^\perp} = \mathbf{U}_2 \mathbf{U}_2^\top = \sum_{j \in I_2} \mathbf{e}_j \mathbf{e}_j^\top$. This implies that if \mathcal{P}_A is not of this form there must exist i, j, k_0 such that $p_{k_0 i} q_{k_0 j} \neq 0$. Then we can choose \mathbf{B} as a diagonal matrix such that $\mathbf{B} \succeq \mathbf{I}_p$. \square

B.4 Proof of Lemmas 1, 2 and 3

Proof. (Proof of Lemma 1)

Define $a_T = \sum_{n=1}^T r_n^p \prod_{s=1}^n \frac{1}{1-r_s}$ and $b_T = r_T^{p-1} \prod_{s=1}^T \frac{1}{1-r_s}$. We first prove that $b_{T+1} > b_T$ for sufficiently large T and $\lim_{T \rightarrow \infty} b_T = \infty$. Since

$$\begin{aligned} \frac{b_{T+1}}{b_T} &= \left(\frac{r_{T+1}}{r_T} \right)^{p-1} \cdot \frac{1}{1-r_{T+1}} \\ &= \frac{1}{(1+o(r_T))^{p-1}} \cdot (1+r_{T+1}+o(r_{T+1})) \\ &= (1+o(r_{T+1}))(1+r_{T+1}+o(r_{T+1})) \\ &= 1+r_{T+1}+o(r_{T+1}), \end{aligned}$$

then we have $b_{T+1} > b_T$ for sufficiently large T . Besides, $\frac{r_n}{r_{n+1}} - 1 = o(r_n)$ implies $\frac{1}{r_n} - \frac{1}{r_{n+1}} = o(1)$. By Stolz–Cesàro theorem, we have $\lim_{n \rightarrow \infty} \frac{1}{nr_n} = 0$ and $\lim_{n \rightarrow \infty} \frac{\sum_{s=1}^n 1/s}{\sum_{s=1}^n r_s} = 0$. As a consequence,

$$\begin{aligned} b_T &\geq r_T^{p-1} \exp\left(\sum_{s=1}^T r_s\right) \\ &= r_T^{p-1} \exp\left(\frac{\sum_{s=1}^T r_s}{\sum_{s=1}^T 1/s} \sum_{s=1}^T 1/s\right) \\ &\geq r_T^{p-1} \exp\left(\frac{\sum_{s=1}^T r_s}{\sum_{s=1}^T 1/s} \log T\right) \\ &= (Tr_T)^{p-1} \exp\left[\left(\frac{\sum_{s=1}^T r_s}{\sum_{s=1}^T 1/s} - p + 1\right) \log T\right]. \end{aligned}$$

Thus $\lim_{T \rightarrow \infty} b_T = \infty$. Now we use Stolz–Cesàro theorem to prove $\lim_{T \rightarrow \infty} \frac{a_T}{b_T} = 1$. With the definition of a_T and b_T , we have

$$a_{T+1} - a_T = r_{T+1}^p \prod_{s=1}^{T+1} \frac{1}{1-r_s}$$

and

$$\begin{aligned} b_{T+1} - b_T &= r_{T+1}^{p-1} \prod_{s=1}^{T+1} \frac{1}{1-r_s} - r_T^{p-1} \prod_{s=1}^T \frac{1}{1-r_s} \\ &= (r_{T+1}^{p-1} - r_T^{p-1}) \prod_{s=1}^{T+1} \frac{1}{1-r_s} + r_T^{p-1} r_{T+1} \prod_{s=1}^{T+1} \frac{1}{1-r_s}. \end{aligned}$$

It follows that

$$\begin{aligned}
\frac{a_{T+1} - a_T}{b_{T+1} - b_T} &= \frac{r_{T+1}^p}{r_{T+1}^{p-1} - r_T^{p-1} + r_T^{p-1} r_{T+1}} \\
&= \frac{r_{T+1}}{1 - (r_T/r_{T+1})^{p-1} + r_{T+1}(r_T/r_{T+1})^{p-1}} \\
&= \frac{r_{T+1}}{1 - (1 + o(r_T))^{p-1} + r_{T+1}(1 + o(1))} \\
&= \frac{r_{T+1}}{o(r_T) + r_{T+1}(1 + o(1))} \\
&= \frac{1}{1 + o(1)},
\end{aligned}$$

which implies $\lim_{T \rightarrow \infty} \frac{a_{T+1} - a_T}{b_{T+1} - b_T} = 1$. By Stolz–Cesàro theorem, we obtain what we want. \square

Proof. (Proof of Lemma 2)

Define $a_T = \sum_{n=1}^T r_t^p \prod_{s=1}^n \frac{1}{1-r_s}$ and $b_T = r_T^{p-1} \prod_{s=1}^T \frac{1}{1-r_s}$. We first prove that $b_{T+1} > b_T$ for sufficiently large T and $\lim_{T \rightarrow \infty} b_T = \infty$. Since

$$\begin{aligned}
\frac{b_{T+1}}{b_T} &= \left(\frac{r_{T+1}}{r_T} \right)^{p-1} \cdot \frac{1}{1 - r_{T+1}} \\
&= \frac{1}{(1 + ar_T + o(r_T))^{p-1}} (1 + r_{T+1} + o(r_{T+1})) \\
&= (1 - a(p-1)r_T + o(r_T)) \left(1 + \frac{r_T}{1 + ar_T + o(r_T)} + o(r_T) \right) \\
&= (1 - a(p-1)r_T + o(r_T)) (1 + r_T + o(r_T)) \\
&= 1 + [1 - a(p-1)]r_T + o(r_T),
\end{aligned}$$

then we have $b_{T+1} > b_T$ for sufficiently large T . Besides, $\frac{r_n}{r_{n+1}} - 1 = ar_n + o(r_n)$ implies $\frac{1}{r_n} - \frac{1}{r_{n+1}} = a + o(1)$. By Stolz–Cesàro theorem, we have $\lim_{t \rightarrow \infty} \frac{1}{nr_n} = a$ and $\lim_{n \rightarrow \infty} \frac{\sum_{s=1}^n 1/s}{\sum_{s=1}^n r_s} = a$. As a consequence,

$$\begin{aligned}
b_T &\geq r_T^{p-1} \exp \left(\sum_{s=1}^T r_s \right) \\
&= r_T^{p-1} \exp \left(\frac{\sum_{s=1}^T r_s}{\sum_{s=1}^T 1/s} \sum_{s=1}^T 1/s \right) \\
&\geq r_T^{p-1} \exp \left(\frac{\sum_{s=1}^T r_s}{\sum_{s=1}^T 1/s} \log T \right) \\
&= (Tr_T)^{p-1} \exp \left[\left(\frac{\sum_{s=1}^T r_s}{\sum_{s=1}^T 1/s} - p + 1 \right) \log T \right] \\
&= (1/a + o(1))^{p-1} \exp [(1/a + o(1) - p + 1) \log T].
\end{aligned}$$

Thus $\lim_{T \rightarrow \infty} b_T = \infty$.

Now we use Stolz–Cesàro theorem to prove $\lim_{T \rightarrow \infty} \frac{a_T}{b_T} = \frac{1}{1-a(p-1)}$. With the definition of a_T and b_T , we have

$$a_{T+1} - a_T = r_{T+1}^p \prod_{s=1}^{T+1} \frac{1}{1-r_s}$$

and

$$b_{T+1} - b_T = r_{T+1}^{p-1} \prod_{s=1}^{T+1} \frac{1}{1-r_s} - r_T^{p-1} \prod_{s=1}^T \frac{1}{1-r_s}$$

$$= (r_{T+1}^{p-1} - r_T^{p-1}) \prod_{s=1}^{T+1} \frac{1}{1-r_s} + r_T^{p-1} r_{T+1} \prod_{s=1}^{T+1} \frac{1}{1-r_s}.$$

It follows that

$$\begin{aligned} \frac{a_{T+1} - a_T}{b_{T+1} - b_T} &= \frac{r_{T+1}^p}{r_{T+1}^{p-1} - r_T^{p-1} + r_T^{p-1} r_{T+1}} \\ &= \frac{r_{T+1}}{1 - (r_T/r_{T+1})^{p-1} + r_{T+1}(r_T/r_{T+1})^{p-1}} \\ &= \frac{r_{T+1}}{1 - (1 + ar_T + o(r_T))^{p-1} + r_{T+1}(1 + ar_T + o(r_T))^{p-1}} \\ &= \frac{r_{T+1}}{1 - 1 - a(p-1)r_T + o(r_T) + r_{T+1}(1 + o(1))} \\ &= \frac{1}{-a(p-1)r_T/r_{T+1} + o(1) + 1 + o(1)} \\ &= \frac{1}{1 - a(p-1) + o(1)}, \end{aligned}$$

which implies $\lim_{T \rightarrow \infty} \frac{a_{T+1} - a_T}{b_{T+1} - b_T} = \frac{1}{1 - a(p-1)}$. By Stolz–Cesàro theorem, we obtain what we want. \square

Proof. (Proof of Lemma 3)

Suppose that $s_n = o(1)$ does not hold. Then for any positive number $\varepsilon > 0$, there exists a sequence of positive integers $\{n_i\}$ that increases to ∞ such that $s_{n_i} \geq \varepsilon$. From the recursion of s_n , there exists a positive integer T such that

$$s_{n+1} \leq (1 - r_n)s_n + \frac{\varepsilon}{2}r_n \quad (27)$$

for any $n \geq T$. For $n_i > T$, we have

$$\varepsilon \leq s_{n_i} \leq (1 - r_{n_i-1})s_{n_i-1} + \frac{\varepsilon}{2}r_{n_i-1} \leq (1 - r_{n_i-1})s_{n_i-1} + \varepsilon r_{n_i-1}.$$

It follows that $s_{n_i-1} \geq \varepsilon$. Since n_i increases to ∞ , we have $s_n \geq \varepsilon$ for any $n \geq T$ by induction. For any $T_1 > T$, summing (27) from T to $T_1 - 1$, we have

$$\sum_{n=T+1}^{T_1} s_n \leq \sum_{n=T}^{T_1-1} s_n - \sum_{n=T}^{T_1-1} s_n r_n + \frac{\varepsilon}{2} \sum_{n=T}^{T_1-1} r_n.$$

Rearranging the terms yields

$$s_{T_1} \geq s_T + \sum_{n=T}^{T_1-1} s_n r_n - \frac{\varepsilon}{2} \sum_{n=T}^{T_1-1} r_n \geq s_T + \frac{\varepsilon}{2} \sum_{n=T}^{T_1-1} r_n.$$

From the proofs of Lemmas 1 and 2, we have $\lim_{n \rightarrow \infty} \frac{\sum_{s=1}^n 1/s}{\sum_{s=1}^n r_s} = a$. Thus $\lim_{T_1 \rightarrow \infty} \sum_{n=T}^{T_1} r_n = \infty$, which induces a contradiction. As a consequence, we have $s_n = o(1)$. \square

B.5 Proof of Lemmas 4 and 5

Proof. (Proof of Lemma 4)

From the update rule and the linearity of \mathcal{P}_{A^\perp} , we have

$$\begin{aligned} \mathbb{E}\|\mathbf{u}_{n+1} - \mathbf{x}^*\|^2 &= \mathbb{E}\|\mathcal{P}_{A^\perp}(\mathbf{x}_n - \eta_n \nabla f(\mathbf{x}_n) + \eta_n \xi_n) - \mathbf{x}^*\|^2 \\ &= \mathbb{E}\|\mathbf{u}_n - \mathbf{x}^* - \eta_n \mathcal{P}_{A^\perp}(\nabla f(\mathbf{x}_n) - \nabla f(\mathbf{x}^*)) + \eta_n \mathcal{P}_{A^\perp} \xi_n\|^2 \\ &= \mathbb{E}\|\mathbf{u}_n - \mathbf{x}^*\|^2 + \eta_n^2 \mathbb{E}\|\mathcal{P}_{A^\perp}(\nabla f(\mathbf{x}_n) - \nabla f(\mathbf{x}^*))\|^2 \\ &\quad - 2\eta_n \mathbb{E}\langle \mathbf{u}_n - \mathbf{x}^*, \mathcal{P}_{A^\perp}(\nabla f(\mathbf{x}_n) - \nabla f(\mathbf{x}^*)) \rangle + \eta_n^2 \Sigma_n^{(1)}, \end{aligned} \quad (28)$$

where the last equality is due to that $\{\xi_n\}$ is a m.d.s. and $\Sigma_n^{(1)} := \mathbb{E}\|\mathcal{P}_{\mathbf{A}^\perp}\xi_n\|^2$.

For the second term of (28), we have

$$\begin{aligned}\|\mathcal{P}_{\mathbf{A}^\perp}(\nabla f(\mathbf{x}_n) - \nabla f(\mathbf{x}^*))\|^2 &= \|\mathcal{P}_{\mathbf{A}^\perp}(\nabla f(\mathbf{x}_n) - \nabla f(\mathbf{u}_n)) + \mathcal{P}_{\mathbf{A}^\perp}(\nabla f(\mathbf{u}_n) - \nabla f(\mathbf{x}^*))\|^2 \\ &\stackrel{(a)}{\leq} 2\|\mathcal{P}_{\mathbf{A}^\perp}(\nabla f(\mathbf{x}_n) - \nabla f(\mathbf{u}_n))\|^2 + 2\|\mathcal{P}_{\mathbf{A}^\perp}(\nabla f(\mathbf{u}_n) - \nabla f(\mathbf{x}^*))\|^2 \\ &\stackrel{(b)}{\leq} 2L^2\|\mathbf{v}_n\|^2 + 2L^2\|\mathbf{u}_n - \mathbf{x}^*\|^2,\end{aligned}$$

where (a) is by Proposition 3 and (b) is due to non-expansiveness of $\mathcal{P}_{\mathbf{A}^\perp}$ and smoothness of f . For the third term of (28), we have

$$\begin{aligned}& -\langle \mathbf{u}_n - \mathbf{x}^*, \mathcal{P}_{\mathbf{A}^\perp}(\nabla f(\mathbf{x}_n) - \nabla f(\mathbf{x}^*)) \rangle \\ & \stackrel{(a)}{=} -\langle \mathbf{u}_n - \mathbf{x}^*, \nabla f(\mathbf{x}_n) - \nabla f(\mathbf{x}^*) \rangle \\ & = -\langle \mathbf{u}_n - \mathbf{x}^*, \nabla f(\mathbf{x}_n) - \nabla f(\mathbf{u}_n) \rangle - \langle \mathbf{u}_n - \mathbf{x}^*, \nabla f(\mathbf{u}_n) - \nabla f(\mathbf{x}^*) \rangle \\ & \stackrel{(b)}{\leq} \frac{\mu}{4}\|\mathbf{u}_n - \mathbf{x}^*\|^2 + \frac{1}{\mu}\|\nabla f(\mathbf{x}_n) - \nabla f(\mathbf{u}_n)\|^2 - \mu\|\mathbf{u}_n - \mathbf{x}^*\|^2 \\ & \stackrel{(c)}{\leq} -\frac{3\mu}{4}\|\mathbf{u}_n - \mathbf{x}^*\|^2 + \frac{L^2}{\mu}\|\mathbf{v}_n\|^2,\end{aligned}$$

where (a) follows from the orthogonality between $\mathcal{P}_{\mathbf{A}}$ and $\mathcal{P}_{\mathbf{A}^\perp}$, (b) is by Propositions 2 and 3 and (c) is due to the smoothness of f . For the last term of (28), we first show that $|\Sigma_n^{(1)} - \Sigma_\star^{(1)}| \leq dL\mathbb{E}\|\mathbf{x}_n - \mathbf{x}^*\|$. From the definition of $\Sigma_n^{(1)}$ and $\Sigma_\star^{(1)}$, we have

$$\begin{aligned}|\Sigma_n^{(1)} - \Sigma_\star^{(1)}| &= |\mathbb{E}\text{trace}(\mathcal{P}_{\mathbf{A}^\perp}(\xi_n\xi_n^\top - \xi_\star(\xi_\star)^\top)\mathcal{P}_{\mathbf{A}^\perp})| \\ &= |\text{trace}(\mathcal{P}_{\mathbf{A}^\perp}(\mathbb{E}\xi_n\xi_n^\top - \mathbb{E}\xi_\star(\xi_\star)^\top)\mathcal{P}_{\mathbf{A}^\perp})| \\ &\leq d\|\mathcal{P}_{\mathbf{A}^\perp}\mathbb{E}(\Sigma(\mathbf{x}_n) - \Sigma(\mathbf{x}^*))\mathcal{P}_{\mathbf{A}^\perp}\| \\ &\leq dL\mathbb{E}\|\mathbf{x}_n - \mathbf{x}^*\|,\end{aligned}$$

where the last inequality is due to the non-expansiveness of $\mathcal{P}_{\mathbf{A}^\perp}$ and Assumption 3. It follows that

$$\begin{aligned}\Sigma_n^{(1)} &\leq \Sigma_\star^{(1)} + |\Sigma_n^{(1)} - \Sigma_\star^{(1)}| \\ &\leq \Sigma_\star^{(1)} + dL\mathbb{E}\|\mathbf{x}_n - \mathbf{x}^*\| \\ &\leq \Sigma_\star^{(1)} + dL\mathbb{E}(\|\mathbf{u}_n - \mathbf{x}^*\| + \|\mathbf{v}_n\|) \\ &\stackrel{(a)}{\leq} \Sigma_\star^{(1)} + dL\left[\frac{\Sigma_\star^{(1)}}{dL} + \frac{dL}{2\Sigma_\star^{(1)}}\mathbb{E}(\|\mathbf{u}_n - \mathbf{x}^*\|^2 + \|\mathbf{v}_n\|^2)\right] \\ &= 2\Sigma_\star^{(1)} + \frac{d^2L^2}{2\Sigma_\star^{(1)}}\mathbb{E}\|\mathbf{u}_n - \mathbf{x}^*\|^2 + \frac{d^2L^2}{2\Sigma_\star^{(1)}}\|\mathbf{v}_n\|^2,\end{aligned}$$

where (a) follows from Proposition 3.

By substituting these inequalities, we obtain

$$\begin{aligned}\mathbb{E}\|\mathbf{u}_{n+1} - \mathbf{x}^*\|^2 &\leq \left(1 - \frac{3\mu}{2}\eta_n + 2L^2\eta_n^2 + \frac{d^2L^2}{2\Sigma_\star^{(1)}}\eta_n^2\right)\mathbb{E}\|\mathbf{u}_n - \mathbf{x}^*\|^2 \\ &\quad + \left(\frac{2L^2}{\mu}\eta_n + 2L^2\eta_n^2 + \frac{d^2L^2}{2\Sigma_\star^{(1)}}\eta_n^2\right)\mathbb{E}\|\mathbf{v}_n\|^2 + 2\eta_n^2\Sigma_n^{(1)} \\ &\stackrel{(a)}{\leq} (1 - \mu\eta_n)\mathbb{E}\|\mathbf{u}_n - \mathbf{x}^*\|^2 + \frac{4L^2}{\mu}\eta_n\mathbb{E}\|\mathbf{v}_n\|^2 + 2\eta_n^2\Sigma_n^{(1)},\end{aligned}$$

where (a) holds if n is large enough. \square

Proof. (Proof of Lemma 5)

From the update rule and the linearity of \mathcal{P}_A , we have

$$\begin{aligned}
\mathbb{E} \|\mathbf{v}_{n+1}\|^2 &= (1-p_n) \mathbb{E} \|\mathcal{P}_A(\mathbf{x}_n - \eta_n \nabla f(\mathbf{x}_n) \eta_n \xi_n)\|^2 \\
&= (1-p_n) \mathbb{E} \|\mathbf{v}_n - \eta_n \mathcal{P}_A \nabla f(\mathbf{x}_n) + \eta_n \mathcal{P}_A \xi_n\|^2 \\
&= (1-p_n) \mathbb{E} \|\mathbf{v}_n\|^2 + (1-p_n) \eta_n^2 \mathbb{E} \|\mathcal{P}_A \nabla f(\mathbf{x}_n)\|^2 \\
&\quad - 2(1-p_n) \eta_n \mathbb{E} \langle \mathbf{v}_n, \mathcal{P}_A \nabla f(\mathbf{x}_n) \rangle + (1-p_n) \eta_n^2 \Sigma_n^{(2)},
\end{aligned} \tag{29}$$

where the last equality is due to that $\{\xi_n\}$ is a m.d.s. and $\Sigma_n^{(2)} := \mathbb{E} \|\mathcal{P}_A \xi_n\|^2$.

For the second term of (29), we have

$$\begin{aligned}
\|\mathcal{P}_A \nabla f(\mathbf{x}_n)\|^2 &= \|\mathcal{P}_A(\nabla f(\mathbf{x}_n) - \nabla f(\mathbf{u}_n) + \nabla f(\mathbf{u}_n) - \nabla f(\mathbf{x}^*) + \nabla f(\mathbf{x}^*))\|^2 \\
&\stackrel{(a)}{\leq} 3 \|\mathcal{P}_A(\nabla f(\mathbf{x}_n) - \nabla f(\mathbf{u}_n))\|^2 + 3 \|\mathcal{P}_A(\nabla f(\mathbf{u}_n) - \nabla f(\mathbf{x}^*))\|^2 + 3 \|\mathcal{P}_A \nabla f(\mathbf{x}^*)\|^2 \\
&\stackrel{(b)}{\leq} 3L^2 \|\mathbf{v}_n\|^2 + 3L^2 \|\mathbf{u}_n - \mathbf{x}^*\|^2 + 3 \|\nabla f(\mathbf{x}^*)\|^2,
\end{aligned}$$

where (a) is by Proposition 3 and (b) follows from non-expansiveness of \mathcal{P}_A and smoothness of f .

For the third term of (29), we have

$$\begin{aligned}
& - \langle \mathbf{v}_n, \mathcal{P}_A \nabla f(\mathbf{x}_n) \rangle \\
&\stackrel{(a)}{=} - \langle \mathbf{v}_n, \nabla f(\mathbf{x}_n) \rangle \\
&= - \langle \mathbf{v}_n, \nabla f(\mathbf{x}_n) - \nabla f(\mathbf{u}_n) \rangle - \langle \mathbf{v}_n, \nabla f(\mathbf{u}_n) - \nabla f(\mathbf{x}^*) \rangle - \langle \mathbf{v}_n, \nabla f(\mathbf{x}^*) \rangle \\
&\stackrel{(b)}{\leq} -\mu \|\mathbf{v}_n\|^2 + \frac{p_n}{8\eta_n} \|\mathbf{v}_n\|^2 + \frac{2\eta_n}{p_n} \|\nabla f(\mathbf{u}_n) - \nabla f(\mathbf{x}^*)\|^2 + \frac{p_n}{8\eta_n} \|\mathbf{v}_n\|^2 + \frac{2\eta_n}{p_n} \|\nabla f(\mathbf{x}^*)\|^2 \\
&\stackrel{(c)}{\leq} -\mu \|\mathbf{v}_n\|^2 + \frac{p_n}{4\eta_n} \|\mathbf{v}_n\|^2 + \frac{2L^2\eta_n}{p_n} \|\mathbf{u}_n - \mathbf{x}^*\|^2 + \frac{2\eta_n}{p_n} \|\nabla f(\mathbf{x}^*)\|^2,
\end{aligned}$$

where (a) follows from the orthogonality between \mathcal{P}_A and \mathcal{P}_{A^\perp} , (b) is by Propositions 2 and 3 and (c) is due to the smoothness of f . For the last term of (29), we can obtain

$$\Sigma_n^{(2)} \leq 2\Sigma_\star^{(2)} + \frac{d^2 L^2}{2\Sigma_\star^{(2)}} \mathbb{E} \|\mathbf{u}_n - \mathbf{x}^*\|^2 + \frac{d^2 L^2}{2\Sigma_\star^{(2)}} \|\mathbf{v}_n\|^2$$

by following similar procedure in the proof of Lemma 4. By substituting these inequalities, we obtain

$$\begin{aligned}
\mathbb{E} \|\mathbf{v}_{n+1}\|^2 &\leq (1-p_n) \left(1 - 2\mu\eta_n + 3L^2\eta_n^2 + \frac{p_n}{2} + \frac{d^2 L^2}{2\Sigma_\star^{(2)}} \eta_n^2 \right) \mathbb{E} \|\mathbf{v}_n\|^2 \\
&\quad + \left(\frac{4L^2\eta_n^2}{p_n} + 3L^2\eta_n^2 + \frac{d^2 L^2}{2\Sigma_\star^{(2)}} \eta_n^2 \right) \mathbb{E} \|\mathbf{u}_n - \mathbf{x}^*\|^2 \\
&\quad + \left(\frac{4\eta_n^2}{p_n} + 3\eta_n^2 \right) \|\nabla f(\mathbf{x}^*)\|^2 + 2\eta_n^2 \Sigma_n^{(2)} \\
&\stackrel{(a)}{\leq} \left(1 - \frac{p_n}{2} \right) \mathbb{E} \|\mathbf{v}_n\|^2 + \frac{7L^2\eta_n^2}{p_n} \mathbb{E} \|\mathbf{u}_n - \mathbf{x}^*\|^2 + \frac{7\eta_n^2}{p_n} \|\nabla f(\mathbf{x}^*)\|^2 + 2\eta_n^2 \Sigma_n^{(2)},
\end{aligned}$$

where (a) holds if n is large enough. \square

C Proof of Section 3.2

C.1 Proof of Case 1

We can deduce the recursive relationship of $\tilde{\mathbf{u}}_n$ by the definition of \mathbf{u}_n and the update rule (2).

$$\begin{aligned}
\tilde{\mathbf{u}}_{n+1} &= \mathcal{P}_{\mathbf{A}^\perp} \frac{\mathbf{x}_{n+\frac{1}{2}} - \mathbf{x}^*}{\sqrt{\eta_n}} \\
&= \mathcal{P}_{\mathbf{A}^\perp} \frac{1}{\sqrt{\eta_n}} (\mathbf{x}_n - \eta_n \nabla f(\mathbf{x}_n) + \eta_n \xi_n - \mathbf{x}^*) \\
&= \frac{\sqrt{\eta_{n-1}}}{\sqrt{\eta_n}} \tilde{\mathbf{u}}_n - \sqrt{\eta_n} \mathcal{P}_{\mathbf{A}^\perp} \{ (\nabla f(\mathbf{x}_n) - \nabla f(\mathbf{u}_n)) + (\nabla f(\mathbf{u}_n) - \nabla f(\mathbf{x}^*)) \} + \sqrt{\eta_n} \mathcal{P}_{\mathbf{A}^\perp} \xi_n \\
&= \frac{\sqrt{\eta_{n-1}}}{\sqrt{\eta_n}} \tilde{\mathbf{u}}_n - \sqrt{\eta_n \eta_{n-1}} \mathcal{P}_{\mathbf{A}^\perp} \left\{ \int_0^1 \nabla^2 f(t\mathbf{x}^* + (1-t)\mathbf{u}_n) dt \right\} \tilde{\mathbf{u}}_n + \mathcal{R}_n^{(1)} + \sqrt{\eta_n} \mathcal{P}_{\mathbf{A}^\perp} \xi_n \\
&= \tilde{\mathbf{u}}_n - \eta_n \mathcal{P}_{\mathbf{A}^\perp} \left(\nabla^2 f(\mathbf{x}^*) - \frac{1}{2\eta_0} \mathbb{1}_{\{\alpha=1\}} \mathbf{I} \right) \tilde{\mathbf{u}}_n + \mathcal{R}_n^{(1)} + \mathcal{R}_n^{(2)} + \mathcal{R}_n^{(3)} + \sqrt{\eta_n} \xi_n^{(1)}
\end{aligned} \tag{30}$$

Where $\mathcal{R}_n^{(i)}$, $i = 1, 2, 3$ are higher order term with respect to η_n with the form:

$$\begin{aligned}
\mathcal{R}_n^{(1)} &= -\sqrt{\eta_n} \mathcal{P}_{\mathbf{A}^\perp} (\nabla f(\mathbf{x}_n) - \nabla f(\mathbf{u}_n)) \\
\mathcal{R}_n^{(2)} &= - \left(1 - \sqrt{\frac{\eta_{n-1}}{\eta_n}} + \frac{\eta_n}{2\eta_0} \mathbb{1}_{\{\alpha=1\}} \right) \tilde{\mathbf{u}}_n + (\eta_n - \sqrt{\eta_n \eta_{n-1}}) \mathcal{P}_{\mathbf{A}^\perp} \nabla^2 f(\mathbf{x}^*) \tilde{\mathbf{u}}_n \\
\mathcal{R}_n^{(3)} &= \sqrt{\eta_n \eta_{n-1}} \mathcal{P}_{\mathbf{A}^\perp} \left(\nabla^2 f(\mathbf{x}^*) - \int_0^1 \nabla^2 f(t\mathbf{x}^* + (1-t)\mathbf{u}_n) dt \right) \tilde{\mathbf{u}}_n
\end{aligned} \tag{31}$$

Where θ_n is an entry-wise linear interpolation point from \mathbf{u}_n to \mathbf{x}^* and Lemma 6 shows that $\frac{1}{\eta_n} \mathcal{R}_n^{(i)}$ are $o(1)$ in some sense.

Lemma 6. *When Assumptions 1, 2 and 4 hold, and let $p_t = \eta_t^\beta$ where $\beta \in [0, 1/2)$, then for any $i \in \{1, 2\}$, $\mathbb{E} \|\mathcal{R}_n^{(i)}\|^2 = o(\eta_n^2)$. For $\mathcal{R}_n^{(3)}$, we have $\mathbb{E} \|\mathcal{R}_n^{(3)}\|^2 = \mathcal{O}(\eta_n^2)$ and $\mathbb{E} \|\mathcal{R}_n^{(3)}\| = o(\eta_n)$.*

We first show the tightness of the rescaling sequence we built. Actually, we make use of a classical criterion (Theorem 7.3 in [3]) to prove this property of $\bar{\mathbf{u}}_t^{(n)}$.

Proposition 6. *The sequence $\bar{\mathbf{u}}^{(n)}$ is tight if these two conditions hold*

1. *For each positive η , there exists an a and an n_0 such that*

$$\mathbb{P}(\|\tilde{\mathbf{u}}_n\| \geq a) \leq \eta \quad \forall n \geq n_0 \tag{32}$$

2. *For any $T > 0$, for any positive ϵ, η , a δ exists and an integer n_0 exists such that:*

$$\mathbb{P} \left(\sup_{s \in [t, t+\delta]} \left\| \bar{\mathbf{u}}_s^{(n)} - \bar{\mathbf{u}}_t^{(n)} \right\| \geq \epsilon \right) \leq \eta \delta; \quad \forall t \in [0, T] \quad \forall n \geq n_0 \tag{33}$$

Proof. (Proof of Lemma 6) When $\alpha < 1$,

$$\begin{aligned}
\mathbb{E}\|\mathcal{R}_n^{(1)}\|^2 &\leq \eta_n \mathbb{E}\|\nabla f(\mathbf{x}_n) - \nabla f(\mathbf{u}_n)\|^2 \leq \eta_n L^2 \mathbb{E}\|\mathbf{v}_n\|^2 \lesssim L^2 \eta_n \times \eta_n^{2-2\beta} = o(\eta_n^2) \\
\mathbb{E}\|\mathcal{R}_n^{(2)}\|^2 &\lesssim \left(1 - \sqrt{\frac{\eta_{n-1}}{\eta_n}}\right)^2 + (\eta_n - \sqrt{\eta_n \eta_{n-1}})^2 = \left(\frac{1}{\eta_n} + \eta_n\right) (\sqrt{\eta_n} - \sqrt{\eta_{n-1}})^2 \\
&\lesssim \frac{(\eta_n - \eta_{n-1})^2}{\eta_n^2} = [1 - (1 + o(\eta_n))]^2 = o(\eta_n^2) \\
\mathbb{E}\|\mathcal{R}_n^{(3)}\|^2 &\lesssim \eta_n^2 \mathbb{E}\left\|\left\{\int_0^1 \nabla^2 f(t\mathbf{x}^* + (1-t)\mathbf{u}_n) dt - \nabla^2 f(\mathbf{x}^*)\right\} \check{\mathbf{u}}_n\right\|^2 \\
&\lesssim \eta_n^2 \mathbb{E}\|\check{\mathbf{u}}_n\|^2 = \mathcal{O}(\eta_n^2) \\
\mathbb{E}\|\mathcal{R}_n^{(3)}\| &\lesssim \eta_n \mathbb{E}\left\|\int_0^1 \nabla^2 f(t\mathbf{x}^* + (1-t)\mathbf{u}_n) dt - \nabla^2 f(\mathbf{x}^*)\right\| \cdot \|\check{\mathbf{u}}_n\| \\
&\lesssim \eta_n \mathbb{E}\|\check{\mathbf{u}}_n\| \int_0^1 \|\nabla^2 f(t\mathbf{x}^* - (1-t)\mathbf{u}_n) - \nabla^2 f(\mathbf{x}^*)\| dt \\
&\lesssim \eta_n \mathbb{E}\|\check{\mathbf{u}}_n\| \int_0^1 (1-t) \|\mathbf{u}_n - \mathbf{x}^*\| dt \lesssim \eta_n^{3/2} \mathbb{E}\|\check{\mathbf{u}}_n\|^2 = o(\eta_n).
\end{aligned} \tag{34}$$

And when $\alpha = 1$

$$\mathbb{E}\|\mathcal{R}_n^{(2)}\|^2 \lesssim \left(1 - \sqrt{1 + \frac{1}{n-1} + \frac{1}{2n}}\right)^2 + \frac{1}{n} \left(\frac{1}{\sqrt{n}} - \frac{1}{\sqrt{n-1}}\right)^2 = o\left(\frac{1}{n^2}\right).$$

□

Lemma 7 (Tightness of $\bar{\mathbf{u}}^{(n)}$). *Suppose that Assumptions 1, 2 and 4 holds, and assume that there exists a positive number $p > 2$ such that $\sup_{n \geq 0} \mathbb{E}\|\xi_n\|^p < \infty$. Then the sequence of random processes*

$\{\bar{\mathbf{u}}^{(n)}\}$ is tight under the Skorokhod topology in finite interval.

Proof. (Proof of Lemma 7)

From the construction of $\bar{\mathbf{u}}_t^{(n)}$ we know it is a continuous process. What remains we have to do is to verify two conditions (32) and (33).

For the first condition about initialization of the process, it is easy to check by the convergence rate result for $\mathbf{u}_n - \mathbf{x}^*$.

For the condition (33), note that we have

$$\begin{aligned}
\bar{\mathbf{u}}_s^{(n)} - \bar{\mathbf{u}}_t^{(n)} &= \left\{ \sum_{k=N(n,t,\eta)}^{N(n,s,\eta)-1} \eta_k \mathbf{b}_k - [(t - \underline{t}_n(\eta)) \mathbf{b}_{N(n,t,\eta)} - (s - \underline{s}_n(\eta)) \mathbf{b}_{N(n,s,\eta)}] \right\} \\
&\quad + \left\{ \sum_{k=N(n,t,\eta)}^{N(n,s,\eta)-1} \sqrt{\eta_k} \xi_k - \sqrt{t - \underline{t}_n(\eta)} \xi_{N(n,t,\eta)} + \sqrt{s - \underline{s}_n(\eta)} \xi_{N(n,s,\eta)} \right\} \\
&=: \mathbf{B} + \mathbf{\Xi}
\end{aligned} \tag{35}$$

From the discussion following Lemma 6, we can see that $\mathbb{E}\|\mathbf{b}_n\|^2$ is uniformly bounded. So

$$\begin{aligned}
\mathbb{P}\left(\sup_{s \in [t, t+\delta]} \|\mathbf{B}\| \geq \frac{\epsilon}{2}\right) &\leq \mathbb{P}\left(\sum_{k=N(n,t,\eta)}^{N(n,s,\eta)} \eta_k \|\mathbf{b}_k\| \geq \frac{\epsilon}{2}\right) \\
&\leq \frac{4}{\epsilon^2} \mathbb{E}\left(\sum_{k=N(n,t,\eta)}^{N(n,s,\eta)} \eta_k \|\mathbf{b}_k\|\right)^2 \\
&\leq \frac{4}{\epsilon^2} \left(\sum_{k=N(n,t,\eta)}^{N(n,s,\eta)} \eta_k\right) \mathbb{E}\left(\sum_{k=N(n,t,\eta)}^{N(n,s,\eta)} \eta_k \|\mathbf{b}_k\|^2\right) \\
&\leq \frac{4}{\epsilon^2} \sup_k \mathbb{E}\|\mathbf{b}_k\|^2 \left(\sum_{k=N(n,t,\eta)}^{N(n,s,\eta)} \eta_k\right) \\
&\leq \mathcal{C} \frac{(\delta + \eta_n)^2}{\epsilon^2} \stackrel{(a)}{\leq} \frac{\eta(\delta + \eta_n)}{4} \stackrel{(b)}{\leq} \frac{\eta\delta}{2}
\end{aligned} \tag{36}$$

Where (a) and (b) holds when we take $\delta + \eta_n < \frac{\eta\epsilon^2}{4\mathcal{C}}$ and $\eta_{n_0} < \delta$.

On the other hand, thanks to the property of monotone interpolation, we have

$$\|\Xi\| \leq \max_{j \in \{0,1\}} \left\| \sum_{k=N(n,t,\eta)}^{N(n,s,\eta)-j} \sqrt{\eta_k} \xi_k - \sqrt{t - \underline{t}_n(\eta)} \xi_{N(n,t,\eta)} \right\|. \tag{37}$$

By leveraging the Doob's inequality and the assumption of bounded p-th moment of ξ_k , we can get

$$\begin{aligned}
\mathbb{P}\left(\sup_{s \in [t, t+\delta]} \|\Xi\| \geq \frac{\epsilon}{2}\right) &\leq \mathbb{P}\left(\max_{j \leq N(n,s,\eta)} \left\| \sum_{k=N(n,t,\eta)}^j \sqrt{\eta_k} \xi_k - \sqrt{t - \underline{t}_n(\eta)} \xi_{N(n,t,\eta)} \right\| \geq \frac{\epsilon}{2}\right) \\
&\leq \frac{2^p}{\epsilon^p} \mathbb{E} \left\| \sum_{k=N(n,t,\eta)}^{N(n,s,\eta)} \sqrt{\eta_k} \xi_k - \sqrt{t - \underline{t}_n(\eta)} \xi_{N(n,t,\eta)} \right\|^p \\
&\stackrel{(a)}{\leq} \frac{\mathcal{C}_p 2^p}{\epsilon^p} \sum_{k=N(n,t,\eta)}^{N(n,s,\eta)} \eta_n^{p/2} \mathbb{E}\|\xi_k\|^p \\
&\leq \frac{\mathcal{C}}{\epsilon^p} \eta_n^{\frac{p}{2}-1} \sum_{k=N(n,t,\eta)}^{N(n,s,\eta)} \eta_k \\
&\stackrel{(b)}{\leq} \frac{\mathcal{C}}{\epsilon^p} \eta_n^{\frac{p}{2}-1} (\delta + \eta_n) \stackrel{(c)}{\leq} \frac{\eta(\delta + \eta_n)}{4} \leq \frac{\eta\delta}{2}
\end{aligned} \tag{38}$$

Where (a) holds by the Burkholder's inequality and (b), (c) hold when we choose $\eta_n^{\frac{p}{2}-1} \leq \frac{\epsilon^p \eta}{4\mathcal{C}}$ and $\eta_{n_0} \leq \delta$.

Combine (36) and (38), finally we can derive that

$$\begin{aligned}
\mathbb{P}\left(\sup_{s \in [t, t+\delta]} \left\| \bar{\mathbf{u}}_s^{(n)} - \bar{\mathbf{u}}_t^{(n)} \right\| \geq \epsilon\right) &\leq \mathbb{P}\left(\sup_{s \in [t, t+\delta]} \|\mathbf{B}\| \geq \frac{\epsilon}{2}\right) + \mathbb{P}\left(\sup_{s \in [t, t+\delta]} \|\Xi\| \geq \frac{\epsilon}{2}\right) \\
&\leq \frac{\eta\delta}{2} + \frac{\eta\delta}{2} = \eta\delta
\end{aligned} \tag{39}$$

So far, we conclude the proof of Lemma 7. \square

Lemma 8. *Suppose Assumptions 1, 1 and 4 holds, and assume that there exists a positive number $p > 2$ such that $\sup_{n \geq 0} \mathbb{E} \|\xi_n\|^p < \infty$. And suppose*

$$\mathbb{E}[\xi_t \xi_t^\top | \mathcal{F}_t] \xrightarrow{n \rightarrow \infty} \Sigma \text{ in probability} \quad (40)$$

Where Σ is a positive definite $d \times d$ -matrix. Then for any C^2 function $g : \mathbb{R}^d \rightarrow \mathbb{R}$, compactly supported with Lipschitz continuous second derivatives, we have

$$\mathbb{E}[g(\check{\mathbf{u}}_{n+1}) - g(\check{\mathbf{u}}_n) | \mathcal{F}_n] = \eta_n \mathcal{L}g(\check{\mathbf{u}}_n) + \mathcal{R}_n^g \quad (41)$$

Where $\frac{1}{\eta_n} \mathcal{R}_n^g \rightarrow 0$ in L_1 and \mathcal{L} is the infinitesimal generator defined by

$$\forall \phi \in \mathcal{C}^2(\mathbb{R}^p) \quad \mathcal{L}\phi(\mathbf{x}) = \left\langle -\mathcal{P}_{\mathbf{A}^\perp} \left(\nabla^2 f(\mathbf{x}^*) - \frac{1}{2\eta_0} \mathbb{1}_{\{\alpha=1\}} \mathbf{I}_d \right) \mathcal{P}_{\mathbf{A}^\perp} \mathbf{x}, \nabla \phi \right\rangle + \frac{1}{2} \text{tr}(\nabla^2 \phi(\mathbf{x}) \Sigma) \quad (42)$$

Proof. (Proof of Lemma 8)

\mathcal{C} will represent a universal constant whose value may change from line to line, for the sake of convenience. We use a Taylor expansion between \mathbf{u}_n and \mathbf{u}_{n+1}

$$\begin{aligned} g(\check{\mathbf{u}}_{n+1}) - g(\check{\mathbf{u}}_n) &= \langle \nabla g(\check{\mathbf{u}}_n), \check{\mathbf{u}}_{n+1} - \check{\mathbf{u}}_n \rangle + \frac{1}{2} (\check{\mathbf{u}}_{n+1} - \check{\mathbf{u}}_n)^\top \nabla^2 g(\check{\mathbf{u}}_n) (\check{\mathbf{u}}_{n+1} - \check{\mathbf{u}}_n) \\ &\quad + \underbrace{\frac{1}{2} (\check{\mathbf{u}}_{n+1} - \check{\mathbf{u}}_n)^\top (\nabla^2 g(\lambda_n) - \nabla^2 g(\check{\mathbf{u}}_n)) (\check{\mathbf{u}}_{n+1} - \check{\mathbf{u}}_n)}_{\mathcal{R}_n^{(4)}} \end{aligned} \quad (43)$$

Since $\nabla^2 g$ is Lipschitz continuous and compactly supported, $\nabla^2 g$ is also ϵ -Hölder continuous for all $\epsilon \in (0, 1]$. Then combine the equation (30) we can control the order of $\mathcal{R}_n^{(4)}$.

$$\begin{aligned} \mathbb{E} \|\mathcal{R}_n^{(4)}\| &\lesssim \mathbb{E} \|\check{\mathbf{u}}_{n+1} - \check{\mathbf{u}}_n\|^{2+\epsilon} \\ &\leq \mathbb{E} \left\| \eta_n \mathcal{P}_{\mathbf{A}^\perp} \left(\nabla^2 f(\mathbf{x}^*) - \frac{1}{2\eta_0} \mathbb{1}_{\{\alpha=1\}} \mathbf{I}_d \right) \mathcal{P}_{\mathbf{A}^\perp} \check{\mathbf{u}}_n + \mathcal{R}_n^{(1)} + \mathcal{R}_n^{(2)} + \mathcal{R}_n^{(3)} + \sqrt{\eta_n} \xi_n \right\|^{2+\epsilon} \\ &\lesssim \eta_n^{1+\frac{\epsilon}{2}} \end{aligned}$$

So we deduce $\frac{1}{\eta_n} \mathcal{R}_n^{(4)} \rightarrow 0$ in L_1 . Further, we make use of the update formula (30) again

$$\begin{aligned} &\mathbb{E}[\langle \nabla g(\check{\mathbf{u}}_n), \check{\mathbf{u}}_{n+1} - \check{\mathbf{u}}_n \rangle | \mathcal{F}_n] \\ &= \mathbb{E} \left[\langle \nabla g(\check{\mathbf{u}}_n), -\eta_n \mathcal{P}_{\mathbf{A}^\perp} \left(\nabla^2 f(\mathbf{x}^*) - \frac{1}{2\eta_0} \mathbb{1}_{\{\alpha=1\}} \mathbf{I}_d \right) \mathcal{P}_{\mathbf{A}^\perp} \check{\mathbf{u}}_n + \mathcal{R}_n^{(1)} + \mathcal{R}_n^{(2)} + \mathcal{R}_n^{(3)} + \sqrt{\eta_n} \xi_n \rangle | \mathcal{F}_n \right] \\ &= -\eta_n \mathbb{E} \left[\langle \nabla g(\check{\mathbf{u}}_n), \mathcal{P}_{\mathbf{A}^\perp} \left(\nabla^2 f(\mathbf{x}^*) - \frac{1}{2\eta_0} \mathbb{1}_{\{\alpha=1\}} \mathbf{I}_d \right) \mathcal{P}_{\mathbf{A}^\perp} \check{\mathbf{u}}_n \rangle | \mathcal{F}_n \right] + \sum_{i=1}^3 \mathbb{E}[\langle \nabla g(\check{\mathbf{u}}_n), \mathcal{R}_n^{(i)} \rangle | \mathcal{F}_n] \end{aligned} \quad (44)$$

Note by Lemma 6, we have

$$\begin{aligned} &\mathbb{E} \left| \mathbb{E} \left[\left\langle \nabla g(\check{\mathbf{u}}_n), \frac{\mathcal{R}_n^{(i)}}{\eta_n} \right\rangle \middle| \mathcal{F}_n \right] \right| \leq \mathbb{E} \left| \left\langle \nabla g(\check{\mathbf{u}}_n), \frac{\mathcal{R}_n^{(i)}}{\eta_n} \right\rangle \right| \\ &\lesssim \mathbb{E} \left\| \frac{\mathcal{R}_n^{(i)}}{\eta_n} \right\| \leq \left(\mathbb{E} \left\| \frac{\mathcal{R}_n^{(i)}}{\eta_n} \right\|^2 \right)^{\frac{1}{2}} = o(1) \end{aligned} \quad (45)$$

And at last,

$$\begin{aligned}
& \frac{1}{2} \mathbb{E} [(\check{\mathbf{u}}_{n+1} - \check{\mathbf{u}}_n)^\top \nabla^2 g(\check{\mathbf{u}}_n) (\check{\mathbf{u}}_{n+1} - \check{\mathbf{u}}_n) | \mathcal{F}_n] \\
&= \frac{\eta_n}{2} \mathbb{E} [\xi_n^\top \nabla^2 g(\check{\mathbf{u}}_n) \xi_n | \mathcal{F}_n] + \frac{\eta_n^{\frac{3}{2}}}{2} \mathbb{E} \langle \mathbf{b}_n, \nabla^2 g(\check{\mathbf{u}}_n) \xi_n \rangle \\
&+ \frac{\eta_n^2}{2} \mathbb{E} \langle \mathbf{b}_n, \nabla^2 g(\check{\mathbf{u}}_n) \mathbf{b}_n \rangle
\end{aligned} \tag{46}$$

Cause g is compactly supported, the norm of $\nabla^2 g$ is bounded. And by Lemma 6, we can deduce $\mathbb{E} \|\mathbf{b}_n\|^2$ is uniformly bounded. Therefore, the last two terms of (46) are $o(\eta_n)$. Combine the above analysis, we have

$$\begin{aligned}
& \mathbb{E}[g(\check{\mathbf{u}}_{n+1}) - g(\check{\mathbf{u}}_n) | \mathcal{F}_n] \\
&= -\eta_n \left\langle \nabla g(\check{\mathbf{u}}_n), \mathcal{P}_{\mathbf{A}^\perp} \left(\nabla^2 f(\mathbf{x}^*) - \frac{1}{2\eta_0} \mathbb{1}_{\{\alpha=1\}} \mathbf{I}_d \right) \mathcal{P}_{\mathbf{A}^\perp} \check{\mathbf{u}}_n \right\rangle + \frac{\eta_n}{2} \langle \nabla^2 g(\check{\mathbf{u}}_n), \Sigma \rangle + \mathcal{R}_n^g
\end{aligned} \tag{47}$$

with $\mathbb{E} \|\mathcal{R}_n^g\| = o(\eta_n)$.

□

Proof. (Proof of Theorem 3.3) The proof of this main results is divided into two steps. At first, we prove that every weak limits of sequence of random process $\{\bar{\mathbf{u}}^{(n)}\}$ is a solution of the martingale problem $(\mathcal{L}, \mathcal{C})$, where \mathcal{C} denotes the class of \mathcal{C}^2 -functions with compact support and Lipschitz continuous second derivatives. \mathcal{L} is defined by (42). Then, from the property of Langevin dynamics, we know that (7) convergence to a unique invariant distribution π^* . Further, by proving that the limit of every weakly converged subsequence equals to π^* and combining it with the Prokhorov's theorem, we conclude $\bar{\mathbf{u}}_n$ converges to π^* weakly. Finally, repeat the first step of this proof, and we have $\{\bar{\mathbf{u}}_t^{(n)}\}$ converges to the solution of equation (7) with initial distribution π^* .

Step 1 Let g belong to \mathcal{C} and let $\mathcal{F}_t^{(n)}$ denote the natural filtration of $\bar{\mathbf{u}}_t^{(n)}$. We aim to derive the following equation, which can guarantee that every sub-limit of $\{\bar{\mathbf{u}}_t^{(n)}\}$ is a weak solution of the martingale problem $(\mathcal{L}, \mathcal{C})$.

$$\forall t \geq 0, \quad g(\bar{\mathbf{u}}_t^{(n)}) - g(\bar{\mathbf{u}}_0^{(n)}) - \int_0^t \mathcal{L}g(\bar{\mathbf{u}}_s^{(n)}) ds = \mathcal{M}_t^{(n,g)} + \mathcal{R}_t^{(n,g)} \tag{48}$$

Where $\mathcal{M}_t^{(n,g)}$ is a $\mathcal{F}_t^{(n)}$ -martingale and $\mathcal{R}_t^{(n,g)}$ converges to zero in L_1 .

In fact, we set

$$\begin{aligned}
\mathcal{M}_t^{(n,g)} &= \sum_{k=n+1}^{N(n,t,\eta)-1} \{g(\check{\mathbf{u}}_{k+1}) - g(\check{\mathbf{u}}_k) - \mathbb{E}[g(\check{\mathbf{u}}_{k+1}) - g(\check{\mathbf{u}}_k) | \mathcal{F}_k]\} \\
\mathcal{R}_t^{(n,g)} &= g(\bar{\mathbf{u}}_t^{(n)}) - g(\bar{\mathbf{u}}_{\underline{t}_n}^{(n)}) - \int_{\underline{t}_n}^t \mathcal{L}g(\bar{\mathbf{u}}_s^{(n)}) ds \\
&+ \int_0^{\underline{t}_n} (\mathcal{L}g(\bar{\mathbf{u}}_{\underline{s}_n}^{(n)}) - \mathcal{L}g(\bar{\mathbf{u}}_s^{(n)})) ds + \sum_{k=n}^{N(n,t,\eta)-1} \mathcal{R}_k^g
\end{aligned} \tag{49}$$

From the definition of $\bar{\mathbf{u}}_t^{(n)}$ (6), we can get

$$\bar{\mathbf{u}}_t^{(n)} - \bar{\mathbf{u}}_{\underline{t}_n(\eta)}^{(n)} = (t - \underline{t}_n(\eta)) \mathbf{b}_{N(n,t,\eta)} + \sqrt{t - \underline{t}_n(\eta)} \xi_{N(n,t,\eta)} \tag{50}$$

Which satisfies

$$\begin{aligned} \mathbb{E} \left\| \bar{\mathbf{u}}_t^{(n)} - \bar{\mathbf{u}}_{\underline{t}_n(\eta)}^{(n)} \right\| &\leq (t - \underline{t}_n(\eta)) \mathbb{E} \|\mathbf{b}_{N(n,t,\eta)}\| + \sqrt{t - \underline{t}_n(\eta)} \mathbb{E} \|\xi_{N(n,t,\eta)}\| \\ &\lesssim \sqrt{\eta_{N(n,t,\eta)}} \end{aligned} \quad (51)$$

Plug the above bound into the residual $\mathcal{R}_t^{(n,g)}$, and note the Lipschitz continuity and boundedness of g , ∇g and $\nabla^2 g$,

$$\begin{aligned} \mathbb{E} \left| g(\bar{\mathbf{u}}_t^{(n)}) - g(\bar{\mathbf{u}}_{\underline{t}_n(\eta)}^{(n)}) \right| &\lesssim \mathbb{E} \left\| \bar{\mathbf{u}}_t^{(n)} - \bar{\mathbf{u}}_{\underline{t}_n(\eta)}^{(n)} \right\| = o(1) \\ \mathbb{E} \left| \int_{\underline{t}_n(\eta)}^t \mathcal{L}g(\bar{\mathbf{u}}_s^{(n)}) ds \right| &\lesssim \int_{\underline{t}_n(\eta)}^t C \lesssim \eta_{N(n,t,\eta)} = o(1) \\ \mathbb{E} \left| \int_0^{\underline{t}_n(\eta)} \mathcal{L}g(\bar{\mathbf{u}}_{\underline{s}_n(\eta)}^{(n)}) - \mathcal{L}g(\bar{\mathbf{u}}_s^{(n)}) ds \right| &\lesssim \mathbb{E} \int_0^{\underline{t}_n(\eta)} \left\| \bar{\mathbf{u}}_{\underline{s}_n(\eta)}^{(n)} - \bar{\mathbf{u}}_s^{(n)} \right\| ds \\ &\lesssim \int_0^{\underline{t}_n(\eta)} \sqrt{\eta_{N(n,s,\eta)}} ds \leq \sqrt{\eta_n} = o(1) \end{aligned} \quad (52)$$

Further, attributed to Lemma 8,

$$\begin{aligned} \mathbb{E} \left| \sum_{k=n}^{N(n,t,\eta)-1} \mathcal{R}_k^g \right| &\leq \sum_{k=n}^{N(n,t,\eta)} \eta_k \mathbb{E} \left| \frac{\mathcal{R}_k^g}{\eta_k} \right| \\ &\leq \sup_{k \geq n} \mathbb{E} \left| \frac{\mathcal{R}_k^g}{\eta_k} \right| \sum_{k=n}^{N(n,t,\eta)} \eta_k \lesssim o(1)t = o(1) \end{aligned} \quad (53)$$

So far we can say that $\mathbb{E}|\mathcal{R}_t^{(n,g)}| \rightarrow 0$, $n \rightarrow \infty$.

Step 2 Now we suppose that there exists a weakly convergent subsequence $\{\check{\mathbf{u}}_{n_k}\}_{k=1}^\infty$ with limit distribution $\tilde{\pi}$. We should introduce some new notations. For $n \in \mathbb{N}$ and $t \geq 0$, we define $M(n,t,\eta) = \min \left\{ m \geq 0; \sum_{i=m}^{n-1} \eta_i \leq t \right\}$ and $\tilde{t}_n(\eta) = \Gamma_n - \Gamma_{M(n,t,\eta)}$. For the properties of step size sequence η_n , we can affirm $t - \tilde{t}_n(\eta) \rightarrow 0$ when $n \rightarrow \infty$.

By leveraging the Prokhorov's theorem, for any $T > 0$, we know that $\left\{ \bar{\mathbf{u}}_t^{(M(n_k, T, \eta))} \right\}$ has a weakly convergent subsequence. Without loss of generality, we can assume that the subsequence $\left\{ \bar{\mathbf{u}}_t^{(M(n_k, T, \eta))} \right\}$ itself converges weakly to a solution $\bar{\mathbf{u}}_t^{\tilde{\nu}^{(T)}}$ of the SDE (7) with initial distribution $\tilde{\nu}^{(T)}$. Owing to the tightness of the whole sequence $\{\bar{\mathbf{u}}^n\}$, for any given $\epsilon > 0$, there is a compact set $K_\epsilon \subset \mathbb{R}^d$ only depends on ϵ such that $\sup_n \mathbb{P}(\check{\mathbf{u}}_n \in K_\epsilon^c) \leq \epsilon$. This makes us find the following holds: $\tilde{\nu}^{(T)}(K_\epsilon) \geq 1 - \epsilon$ for any $T > 0$.

By the geometrical ergodicity of the dynamics (7), we can choose T_ϵ such that

$$\sup_{\mathbf{x} \in K_\epsilon} \sup_{g \in \mathcal{C}} |\mathcal{P}^{T_\epsilon} g(\mathbf{x}) - \langle \pi^*, g \rangle| \leq \epsilon \quad (54)$$

Where \mathcal{P} represents the Markov semigroup induced by the SDE (7). In virtue of the approximation of $(\widetilde{T_\epsilon})_n(\eta)$ to T_ϵ and the tightness of the sequence $\bar{\mathbf{u}}^{(n)}$, we are able to deduce that $\check{\mathbf{u}}_{n_k} (= \bar{\mathbf{u}}_{(\widetilde{T_\epsilon})_n(\eta)}^{M(n_k, T_\epsilon, \eta)})$ converges weakly to the limit random variable of the sequence $\bar{\mathbf{u}}_{T_\epsilon}^{M(n_k, T_\epsilon, \eta)}$ i.e., $\bar{\mathbf{u}}_{T_\epsilon}^{\tilde{\nu}^{(T_\epsilon)}}$. On the other hand, by assumption, $\check{\mathbf{u}}_{n_k}$ converges weakly to $\tilde{\pi}$. Thus $\bar{\mathbf{u}}_{T_\epsilon}^{\tilde{\nu}^{(T_\epsilon)}} \sim \tilde{\pi}$.

Given any $g \in \mathcal{C}$, it is not difficult to derive the following bounds

$$\begin{aligned}
|\langle \tilde{\pi}, g \rangle - \langle \pi^*, g \rangle| &= \left| \mathbb{E}g \left(\bar{\mathbf{u}}_{T_\epsilon}^{(T_\epsilon)} \right) - \mathbb{E}_{\pi^*}g \right| = \left| \int (\mathcal{P}^{T_\epsilon}g(\mathbf{x}) - \mathbb{E}_{\pi^*}g) d\tilde{\nu}^{(T_\epsilon)}(\mathbf{x}) \right| \\
&\leq \int |\mathcal{P}^{T_\epsilon}g(\mathbf{x}) - \mathbb{E}_{\pi^*}g| d\tilde{\nu}^{(T_\epsilon)}(\mathbf{x}) \\
&= \int_{K_\epsilon} |\mathcal{P}^{T_\epsilon}g(\mathbf{x}) - \mathbb{E}_{\pi^*}g| d\tilde{\nu}^{(T_\epsilon)}(\mathbf{x}) + \int_{K_\epsilon^c} |\mathcal{P}^{T_\epsilon}g(\mathbf{x}) - \mathbb{E}_{\pi^*}g| d\tilde{\nu}(\mathbf{x}) \quad (55) \\
&\leq \int_{K_\epsilon} |\mathcal{P}^{T_\epsilon}g(\mathbf{x}) - \mathbb{E}_{\pi^*}g| d\tilde{\nu}^{(T_\epsilon)}(\mathbf{x}) + 2\|g\|_\infty \tilde{\nu}^{(T_\epsilon)}(K_\epsilon^c) \\
&\stackrel{(a)}{\leq} \epsilon + 2\|g\|_\infty \epsilon
\end{aligned}$$

Where (a) holds for sake of $\tilde{\nu}^{(T_\epsilon)}(K_\epsilon) \geq 1 - \epsilon$ and (54). We obtain $\tilde{\pi} = \pi^*$ by taking $\epsilon \rightarrow 0$. Finally, owing to the Prokhorov's theorem, we have proved that $\bar{\mathbf{u}}_n$ converges weakly to π^* . Further, the sequence of random process $\bar{\mathbf{u}}_t^{(n)}$ converges weakly to the dynamics (7) with stationary distribution π^* as initialization. \square

C.2 Proof of Case 2

We first complete the formulation of the recurrence relation for v_n that was omitted from the main text

$$\begin{aligned}
\check{v}_{(n+1)-} &= \eta_n^{\beta-1} \mathcal{P}_A(\mathbf{x}_n - \eta_n \nabla f(\mathbf{x}_n) + \eta_n \xi_n) \\
&= \left(\frac{\eta_n}{\eta_{n-1}} \right)^{\beta-1} \check{v}_n - \eta_n^\beta \mathcal{P}_A \nabla f(\mathbf{x}_n) + \eta_n^\beta \mathcal{P}_A \xi_n \\
&= \left(\frac{\eta_n}{\eta_{n-1}} \right)^{\beta-1} \check{v}_n - \eta_n^\beta \nabla f(\mathbf{x}^*) - \eta_n^\beta \mathcal{P}_A (\nabla f(\mathbf{x}_n) - \nabla f(\mathbf{u}_n)) \quad (56) \\
&\quad - \eta_n^\beta \mathcal{P}_A (\nabla f(\mathbf{u}_n) - \nabla f(\mathbf{x}^*)) + \eta_n^\beta \mathcal{P}_A \xi_n \\
&= \check{v}_n - \eta_n^\beta \nabla f(\mathbf{x}^*) - \mathcal{S}_n^{(1)} - \mathcal{S}_n^{(2)} - \mathcal{S}_n^{(3)} + \eta_n^\beta \xi_n^{(2)} \\
&=: \check{v}_n - \eta_n^\beta \mathbf{d}_n + \eta_n^\beta \xi_n^{(2)}
\end{aligned}$$

Where $\mathbf{d}_n = \nabla f(\mathbf{x}^*) + \frac{1}{\eta_n^\beta} \mathcal{S}_n^{(1)} + \frac{1}{\eta_n^\beta} \mathcal{S}_n^{(2)} + \frac{1}{\eta_n^\beta} \mathcal{S}_n^{(3)}$ with higher order terms

$$\begin{aligned}
\mathcal{S}_n^{(1)} &= \left(1 - \frac{\eta_n^\beta}{\eta_{n-1}^\beta} \right) \check{v}_n \\
\mathcal{S}_n^{(2)} &= \eta_n^\beta \mathcal{P}_A (\nabla f(\mathbf{x}_n) - \nabla f(\mathbf{u}_n)) \\
\mathcal{S}_n^{(3)} &= \eta_n^\beta \mathcal{P}_A (\nabla f(\mathbf{u}_n) - \nabla f(\mathbf{x}^*))
\end{aligned} \quad (57)$$

We can see from the Theorem 3.1 that both $\frac{\mathcal{S}_n^{(2)}}{\eta_n^\beta}$ and $\frac{\mathcal{S}_n^{(3)}}{\eta_n^\beta}$ are of order $o(\eta_n^{1-\beta})$ in L_1 . Moreover, owing to the slow diminishing property of step size $\{\eta_n\}$, the following bound holds

$$\begin{aligned}
1 - \frac{\eta_n^\beta}{\eta_{n-1}^\beta} &= 1 - \left(1 + \frac{\eta_n - \eta_{n-1}}{\eta_{n-1}} \right)^\beta \\
&= 1 - (1 + \mathcal{O}(\eta_n))^\beta = 1 - (1 + \beta \mathcal{O}(\eta_n)) = \mathcal{O}(\eta_n).
\end{aligned} \quad (58)$$

So

$$\frac{1}{\eta_n^\beta} \mathbb{E} \left| \mathcal{S}_n^{(1)} \right| \lesssim \frac{\mathcal{O}(\eta_n)}{\eta_n^\beta} = \mathcal{O}(\eta_n^{1-\beta}). \quad (59)$$

As in the derivation process of the first case, we first need to focus our attention on the discussion of tightness of the sequence of random process $\{\bar{v}_t^{(n)}\}_{n=1}^\infty$. While the discontinuity of these processes constructed by (9) prevents the property 6 from being used to verify the tightness of $\{\bar{v}_t^{(n)}\}$. Hence, we will leverage the following more general criterion for tightness proposed in [19].

Proposition 7. Let $\{\mathbf{x}_n(t)\}$ be a sequence of \mathbb{R}^d -valued processes whose sample paths are càdlàg. Let

$$\omega(\mathbf{x}_n, \delta, T) = \inf_{\{t_i\}} \max_i \sup_{t_{i-1} \leq s < t < t_i} \|\mathbf{x}_t - \mathbf{x}_s\|. \quad (60)$$

Where $\{t_i\}$ ranges over all finite partitions of the form $0 = t_0 \leq t_1 < t_2 < \dots < t_{r-1} < T \leq t_r$ with $\min_{1 \leq i \leq r} (t_i - t_{i-1}) \geq \delta$. Then the sequence of processes $\{\mathbf{x}_n(t)\}$ is tight if and only if,

1. for every $T > 0$ and $\eta > 0$, there is a compact set K such that

$$\liminf_{n \rightarrow \infty} \mathbb{P}(\mathbf{x}_n(t) \in K; \forall t \in [0, T]) > 1 - \eta; \quad (61)$$

2. for every $\epsilon, \eta > 0$, and $T > 0$, there is a $\delta > 0$ such that

$$\limsup_{n \rightarrow \infty} \mathbb{P}(\omega(\mathbf{x}_n, \delta, T) \geq \epsilon) < \eta. \quad (62)$$

Denote $\mathcal{I}_n(T) = \{N(n, t, \eta^\beta) : t \in [0, T]\} \subset \mathbb{N}$ and $\mathcal{L}_n(T) = \{\Gamma_{n+k} - \Gamma_n : k \in \mathcal{I}_n(T)\}$. From the update rule of parametric sequence $\{\mathbf{x}_n\}$ and the construction of the rescaling process $\{\bar{\mathbf{v}}_t^{(n)}\}$, an intuitive fact is that the discontinuous points of $\bar{\mathbf{v}}_t^{(n)}$ in the interval $[0, T]$ belong to $\mathcal{L}_n(T)$. And we have the following lemma to support the proof of tightness.

Lemma 9. For the sequence of càdlàg processes $\{\bar{\mathbf{v}}^{(n)}\}$, consider the time point set $\mathcal{J}_n(T)$ such that

$$\mathcal{J}_n(T) = \left\{ N(n, t, \eta^\beta) : t \in [0, T] \text{ and } \bar{\mathbf{v}}_{t_n(\eta^\beta)}^{(n)} \neq \bar{\mathbf{v}}_{t_n(\eta^\beta)-}^{(n)} \right\} \quad (63)$$

and let

$$\Delta(\mathcal{J}_n(T)) = \min \{ |\Gamma_{n+k}(\eta^\beta) - \Gamma_{n+l}(\eta^\beta)| : k, l \in \mathcal{J}_n(T) \text{ and } k \neq l \} \quad (64)$$

Then there is a universal constant \mathcal{C} and an $n_0 \in \mathbb{N}$ subject to for any $\delta > 0$

$$\mathbb{P}(\Delta(\mathcal{J}_n(T)) < \delta) \leq \mathcal{C}\delta \quad \forall n \geq n_0. \quad (65)$$

Proof. (**Proof of Lemma 9**)

By the sub-additivity of probability and the jump scheme proposed in the Algorithm 1, we have

$$\begin{aligned} & \mathbb{P}(\Delta(\mathcal{J}_n(T)) < \delta) \\ & \leq \sum_{k \in \mathcal{I}_n(T)} \mathbb{P} \{ \exists (k \leq) l \in \mathcal{J}_n(T) \text{ s.t. } |\Gamma_{n+l}(\eta^\beta) - \Gamma_{n+k}(\eta^\beta)| < \delta; k \in \mathcal{J}_n(T) \} \\ & \leq \sum_{k \in \mathcal{I}_n(T)} \sum_{0 < \Gamma_{n+l}(\eta^\beta) - \Gamma_{n+k}(\eta^\beta) < \delta} \mathbb{P} \{ l \in \mathcal{J}_n(T); k \in \mathcal{J}_n(T) \} \\ & \leq \sum_{k \in \mathcal{I}_n(T)} p_{n+k} \left(\sum_{0 < \Gamma_{n+l}(\eta^\beta) - \Gamma_{n+k}(\eta^\beta) < \delta} p_{n+l} \right) \\ & \leq \gamma^2 \sum_{k \in \mathcal{I}_n(T)} \eta_{n+k}^\beta \left(\sum_{0 < \Gamma_{n+l}(\eta^\beta) - \Gamma_{n+k}(\eta^\beta) < \delta} \eta_{n+l}^\beta \right) \\ & \stackrel{(a)}{\leq} \gamma^2 (\delta + \eta_n^\beta) \sum_{k \in \mathcal{I}_n(T)} \eta_{n+k}^\beta \leq 2\gamma^2 T \delta. \end{aligned} \quad (66)$$

Where (a) holds when we let $\eta_{n_0}^\beta \leq \delta$. We conclude the proof by letting $\mathcal{C} = 2\gamma^2 T$. \square

Lemma 10. Suppose that Assumptions 1, 2 and 4 holds. Then the sequence of random processes $\{\bar{\mathbf{v}}^{(n)}\}$ is tight under the Skorokhod topology in finite interval.

Proof. (**Proof of Lemma 10**) What we need to do now is to verify the conditions in the Property 7 one by one.

For a given path $\bar{v}^{(n)}$, denote $t'_n = \max\{s \in \mathcal{L}_n(T) \cap [0, t]\} \cup \{0\}$. Then $\bar{v}_{t'_n}^{(n)} = 0$ whenever $t'_n > 0$. Let $R > 0$, we have the following inequalities

$$\begin{aligned}
& \mathbb{P} \left(\sup_{t \in [0, T]} \left\| \bar{v}_t^{(n)} \right\| \geq R \right) \\
& \leq \mathbb{P} \left(\sup_{t \in [0, T]} \left\{ \left\| \bar{v}_t^{(n)} - \bar{v}_{\underline{t}_n(\eta^\beta)}^{(n)} \right\| + \left\| \bar{v}_{\underline{t}_n(\eta^\beta)}^{(n)} - \bar{v}_{t'_n}^{(n)} \right\| + \left\| \bar{v}_{t'_n}^{(n)} \right\| \right\} \geq R \right) \\
& \leq \frac{2}{R} \mathbb{E} \sup_{t \in [0, T]} \left\{ (t - \underline{t}_n(\eta^\beta)) \left\| \mathbf{d}_{\underline{t}_n(\eta^\beta)} - \xi_{\underline{t}_n(\eta^\beta)}^{(2)} \right\| + \left\| \bar{v}_{\underline{t}_n(\eta^\beta)}^{(n)} - \bar{v}_{t'_n}^{(n)} \right\| \right\} + \frac{2}{R} \mathbb{E} \left\| \bar{v}_0^{(n)} \right\| \\
& \leq \frac{2}{R} \mathbb{E} \sup_{t \in \mathcal{L}_n(T)} \left\| \bar{v}_{t-}^{(n)} - \bar{v}_{(t-)'_n}^{(n)} \right\| + \frac{2}{R} \mathbb{E} \|\check{v}_n\| \\
& \leq \frac{2}{R} \mathbb{E} \sup_{k \in \mathcal{I}_n(T)} \sum_{i=n}^{n+k-1} \eta_i^\beta \left\| \mathbf{d}_i + \xi_i^{(2)} \right\| + \frac{2}{R} \mathbb{E} \|\check{v}_n\| \\
& = \frac{2}{R} \sum_{i=n}^{n+\sup \mathcal{I}_n(T)-1} \eta_i^\beta \mathbb{E} \left\| \mathbf{d}_i + \xi_i^{(2)} \right\| + \frac{2}{R} \mathbb{E} \|\check{v}_n\| \\
& \leq \frac{2}{R} (T + \eta_n) \sup_{n \in \mathbb{N}} \mathbb{E} \left\| \mathbf{d}_i + \xi_i^{(2)} \right\| + \frac{2}{R} \mathbb{E} \|\check{v}_n\| \\
& \stackrel{(a)}{\leq} \frac{\mathcal{C}(1+T)}{R} \leq \eta.
\end{aligned} \tag{67}$$

Where (a) holds for the uniform boundedness of $\mathbb{E} \|\mathbf{d}_n + \xi_n^{(2)}\| + \mathbb{E} \|\check{v}_n\|$. And the final inequality holds when we take $R > \frac{\mathcal{C}(1+T)}{\eta}$. Thus, the first condition of the Proposition 7 holds for $\bar{v}^{(n)}$.

As for the second condition, what we should do is to construct an appropriate partition that makes $\omega(\bar{v}^{(n)}, \delta, T)$ defined as (60) as small as possible.

For a given ϵ, η pair, let $\delta < \frac{\eta}{2}$, then from the Lemma 9 it can be seen $\mathbb{P}(\Delta(\mathcal{J}_n(T)) < \delta) < \frac{\eta}{2}$. Now given the event $\mathcal{E} = \{\Delta(\mathcal{J}_n(T)) \geq \delta\}$, we choose the partition points $\{\tau_k\} \in [0, T]$ recursively from the set $\mathcal{L}_n(T)$ such that the partition satisfies the following properties:

1. $\min_k \{\tau_k - \tau_{k-1}\} \in [\delta, 3\delta)$
2. $\mathcal{J}_n(T) \subset \{\tau_k\}$

Let $\tau_0 = 0$ and suppose we have constructed the partition points $\tau_0, \dots, \tau_k \in [0, T]$ with inductive assumptions:

1. $\min_{i \leq k-1} \{\tau_{i+1} - \tau_i\} \in [\delta, 3\delta)$,
2. $\mathcal{J}_n(\tau_k) \subset \{\tau_0, \tau_1, \dots, \tau_k\}$,
3. there is no discontinuous point in $(\tau_k, \tau_k + \delta)$, i.e. $\mathcal{J}_n(T) \cap (\tau_k, \tau_k + \delta) = \emptyset$.

We will use these results to find the next partition point τ_{k+1} . Define $\tilde{\tau}_{k+1} = \min\{t : t - \tau_k \geq \delta, t \in \mathcal{L}_n(T)\}$, we use the following scheme:

$$\tau_{k+1} = \begin{cases} s & \exists s \in (\tilde{\tau}_{k+1}, \tilde{\tau}_{k+1} + \delta) \cap \mathcal{J}_n(T) \\ \tilde{\tau}_{k+1} & \text{Otherwise} \end{cases} \tag{68}$$

From the property of the event \mathcal{E} we know there is at most one discontinuous point in $(\tilde{\tau}_{k+1}, \tilde{\tau}_{k+1} + \delta)$, which means the τ_{k+1} is always well-defined. Then we have $\delta \leq \tau_{k+1} - \tau_k \leq \tau_{k+1} - \tilde{\tau}_{k+1} + \tilde{\tau}_{k+1} - \tau_k \leq \delta + \eta_n + \delta \leq 3\delta$. Where the last inequality holds when we choose n_0 such that $\eta_{n_0} < \delta$. Thus τ_{k+1} satisfies the first inductive assumption.

By the third inductive assumption of τ_k , we know there is no discontinuous point in $(\tau_k, \tilde{\tau}_{k+1})$. On the other hand, if $\tau_{k+1} \in \mathcal{J}_n(T)$, then $(\tau_{k+1} - \delta, \tau_{k+1}) \cap \mathcal{J}_n(T) = \emptyset$, and especially we have $[\tilde{\tau}_{k+1}, \tau_{k+1}) \cap \mathcal{J}_n(T) = \emptyset$. Hence, the second inductive assumption of τ_{k+1} has been proved.

Finally, if $\tau_{k+1} = \tilde{\tau}_{k+1}$, then from the recursive construction scheme (68) we know $(\tau_{k+1}, \tau_{k+1} + \delta) \cap \mathcal{J}_n(T) = (\tilde{\tau}_{k+1}, \tilde{\tau}_{k+1} + \delta) \cap \mathcal{J}_n(T) = \emptyset$. Else, τ_{k+1} must belong to $\mathcal{J}_n(T)$. Combining the definition of \mathcal{E} we can make sure $(\tau_{k+1}, \tau_{k+1} + \delta) \cap \mathcal{J}_n(T) = \emptyset$. At this point, the proofs of the three inductive assumptions on τ_{k+1} are all complete.

$$\begin{aligned}
\mathbb{P}(\omega(\bar{\mathbf{v}}^{(n)}), \delta, T) \geq \epsilon) &\leq \mathbb{P}(\omega(\bar{\mathbf{v}}^{(n)}), \delta, T) \geq \epsilon; \mathcal{E}) + \mathbb{P}(\mathcal{E}^c) \\
&\leq \mathbb{P}\left(\max_k \sup_{\tau_k \leq t < s < \tau_{k+1}} \|\bar{\mathbf{v}}_t^{(n)} - \bar{\mathbf{v}}_s^{(n)}\| \geq \epsilon; \mathcal{E}\right) + \frac{\eta}{2} \\
&\leq 2\mathbb{P}\left(\sup_{t \in [0, T]} \|\check{\mathbf{v}}_t^{(n)} - \check{\mathbf{v}}_{\underline{t}_n(\eta^\beta)}^{(n)}\| \geq \frac{\epsilon}{2}\right) + \frac{\eta}{2} \\
&+ \mathbb{P}\left(\max_k \sup_{\tau_k \leq t < s < \tau_{k+1}} \|\bar{\mathbf{v}}_{\underline{t}_n(\eta^\beta)}^{(n)} - \bar{\mathbf{v}}_{\underline{s}_n(\eta^\beta)}^{(n)}\| \geq \frac{\epsilon}{2}; \mathcal{E}\right)
\end{aligned} \tag{69}$$

We will give the bound of two probabilities respectively. First,

$$\begin{aligned}
&\mathbb{P}\left(\sup_{t \in [0, T]} \|\check{\mathbf{v}}_t^{(n)} - \check{\mathbf{v}}_{\underline{t}_n(\eta^\beta)}^{(n)}\| \geq \frac{\epsilon}{2}\right) = \mathbb{P}\left(\sup_{k \in \mathcal{I}_n(T)} \|\bar{\mathbf{v}}_{(\Gamma_{k+1} - \Gamma_n)^-}^{(n)} - \bar{\mathbf{v}}_{\Gamma_k - \Gamma_n}^{(n)}\| \geq \frac{\epsilon}{2}\right) \\
&\leq \sum_{k \in \mathcal{I}_n(T)} \mathbb{P}\left(\|\check{\mathbf{v}}_{(n+k+1)^-} - \check{\mathbf{v}}_{n+k}\| \geq \frac{\epsilon}{2}\right) \leq \sum_{k \in \mathcal{I}_n(T)} \frac{4}{\epsilon^2} \mathbb{E} \|\check{\mathbf{v}}_{(n+k+1)^-} - \check{\mathbf{v}}_{n+k}\|^2 \\
&\leq \frac{4}{\epsilon^2} \sum_{k \in \mathcal{I}_n(T)} \eta_{n+k}^{2\beta} \mathbb{E} \|\mathbf{d}_{n+k} + \xi_{n+k}^{(2)}\|^2 \leq \frac{4\eta_n^\beta \sup_i \mathbb{E} \|\mathbf{d}_i + \xi_i^{(2)}\|^2}{\epsilon^2} \sum_{k \in \mathcal{I}_n(T)} \eta_{n+k}^\beta \\
&\leq \frac{\mathcal{C}(T + \eta_n^\beta)}{\epsilon^2} \eta_n^\beta < \frac{2CT}{\epsilon} \eta_n^\beta < \frac{\eta}{8}.
\end{aligned} \tag{70}$$

Where the last inequality holds when we take $\eta_{n_0}^\beta < \frac{\epsilon\eta}{16CT}$.

It is easy to see that we can use a bijection to link the elements in $\mathcal{I}_n(T)$ and that in $\mathcal{L}_n(T)$. Because the partition points $\{\tau_k\}$ are in $\mathcal{L}_n(T)$, we assume that every τ_k corresponds to an index $s_k \in \mathcal{I}_n(T)$. Then we have $s_{k+1} > s_k$. Denote $\mathfrak{S}_k = \mathcal{I}_n(T) \cap [s_k, s_{k+1})$. So far we are ready to bound the last

term in (69).

$$\begin{aligned}
& \mathbb{P} \left(\max_k \sup_{\tau_k \leq t < s < \tau_{k+1}} \left\| \bar{\mathbf{v}}_{\underline{L}_n(\eta^\beta)}^{(n)} - \bar{\mathbf{v}}_{\underline{L}_n(\eta^\beta)}^{(n)} \right\| \geq \frac{\epsilon}{2}; \mathcal{E} \right) \\
& \leq \sum_k \mathbb{P} \left(\sup_{l, h \in \mathfrak{G}_k} \|\check{\mathbf{v}}_{n+l} - \check{\mathbf{v}}_{n+h}\| \geq \frac{\epsilon}{2}; \mathcal{E} \right) \\
& \leq \sum_k \mathbb{P} \left(\sup_{l, h \in \mathfrak{G}_k} \sum_{i=l}^{h-1} \|\check{\mathbf{v}}_{n+i+1} - \check{\mathbf{v}}_{n+i}\| \geq \frac{\epsilon}{2}; \mathcal{E} \right) = \sum_k \mathbb{P} \left(\sum_{i=\varsigma_k}^{\varsigma_{k+1}-1} \|\check{\mathbf{v}}_{n+i+1} - \check{\mathbf{v}}_{n+i}\| \geq \frac{\epsilon}{2}; \mathcal{E} \right) \\
& \stackrel{(a)}{\leq} \sum_k \mathbb{P} \left(\sum_{i=\varsigma_k}^{\varsigma_{k+1}-1} \eta_{n+i}^\beta \|\mathbf{d}_{n+i} + \xi_{n+i}^{(2)}\| \geq \frac{\epsilon}{2} \right) \leq \sum_k \frac{4}{\epsilon^2} \mathbb{E} \left(\sum_{i=\varsigma_k}^{\varsigma_{k+1}-1} \eta_{n+i}^\beta \|\mathbf{d}_{n+i} + \xi_{n+i}^{(2)}\| \right)^2 \\
& \leq \frac{4}{\epsilon^2} \sum_k \left\{ \left(\sum_{i=\varsigma_k}^{\varsigma_{k+1}-1} \eta_{n+i}^\beta \right) \left(\sum_{i=\varsigma_k}^{\varsigma_{k+1}-1} \eta_{n+i}^\beta \mathbb{E} \|\mathbf{d}_{n+i} + \xi_{n+i}^{(2)}\|^2 \right) \right\} \\
& \leq \frac{4 \sup_i \mathbb{E} \|\mathbf{d}_i + \xi_i^{(2)}\|^2}{\epsilon^2} \sum_k \left(\sum_{i=\varsigma_k}^{\varsigma_{k+1}-1} \eta_{n+i}^\beta \right)^2 \leq \frac{\mathcal{C}}{\epsilon^2} \sum_k (\tau_{k+1} - \tau_k)^2 \\
& \stackrel{(b)}{\leq} \frac{3\mathcal{C}\delta}{\epsilon^2} \sum_k (\tau_{k+1} - \tau_k) \leq \frac{3\mathcal{C}T\delta}{\epsilon^2} < \frac{\eta}{4}.
\end{aligned} \tag{71}$$

Where (a) follows from the combination of the fact that the path $\bar{\mathbf{v}}^{(n)}$ is continuous in any interval $[\tau_{k+1}, \tau_k)$ when \mathcal{E} holds and the update formula (9). And (b) is true by the property of the partition $\{\tau_k\}$ listed above. The last inequality holds when we take $\delta < \frac{\eta\epsilon^2}{12\mathcal{C}T}$.

Bring (70) and (71) into (69), we have,

$$\mathbb{P}(\omega(\bar{\mathbf{v}}^{(n)}, \delta, T) \geq \epsilon) \geq 2 \cdot \frac{\eta}{8} + \frac{\eta}{2} + \frac{\eta}{4} = \eta. \tag{72}$$

At this point, we have checked the two sufficient conditions in the Property 7. Hence, the tightness of $\{\bar{\mathbf{v}}^{(n)}\}$ has been proved. \square

Lemma 11. *Suppose Assumptions 1, 1 and 4 holds, and assume that there exists a positive number $p > 2$ such that $\sup_{n \geq 0} \mathbb{E} \|\xi_n\|^p < \infty$. When $p_n = \gamma \eta_n^\beta$ with $\gamma > 0$,*

then for any C^2 function $g : \mathbb{R}^d \rightarrow \mathbb{R}$, compactly supported with Lipschitz continuous second derivatives, we have

$$\mathbb{E}[g(\check{\mathbf{v}}_{n+1}) - g(\check{\mathbf{v}}_n) | \mathcal{F}_n] = \eta_n^\beta \mathcal{J}g(\check{\mathbf{v}}_n) + \mathcal{T}_n^g \tag{73}$$

Where $\frac{1}{\eta_n^\beta} \mathcal{T}_n^g \rightarrow 0$ in L_1 and \mathcal{J} is the infinitesimal generator defined by

$$\forall \phi \in C^2(\mathbb{R}^p) \quad \mathcal{J}\phi(\mathbf{x}) = \langle -\nabla f(\mathbf{x}^*), \nabla \phi(\mathbf{x}) \rangle + \gamma(\phi(\mathbf{0}) - \phi(\mathbf{x})) \tag{74}$$

Proof. (Proof of Lemma 11) We would like to say that the overall proof framework is similar to the proof of the Lemma 8. However, since $\check{\mathbf{v}}_{n+1}$ may suddenly jump to 0, we cannot directly use Taylor expansion to get the desired result. First, by the scheme on $\check{\mathbf{v}}_{n+1}$ jumping to zero, we have

$$\mathbb{E}[g(\check{\mathbf{v}}_{n+1}) - g(\check{\mathbf{v}}_n) | \mathcal{F}_n] = p_n(g(\mathbf{0}) - g(\check{\mathbf{v}}_n)) + (1 - p_t) \mathbb{E}[g(\check{\mathbf{v}}_{(n+1)-}) - g(\check{\mathbf{v}}_n) | \mathcal{F}_n] \tag{75}$$

Then we make use of the Taylor expansion between $\check{\mathbf{v}}_{(n+1)-}$ and $\check{\mathbf{v}}_n$.

$$\begin{aligned}
g(\check{\mathbf{v}}_{(n+1)-}) - g(\check{\mathbf{v}}_n) &= \langle \nabla g(\check{\mathbf{v}}_n), \check{\mathbf{v}}_{(n+1)-} - \check{\mathbf{v}}_n \rangle \\
&+ \frac{1}{2} (\check{\mathbf{v}}_{(n+1)-} - \check{\mathbf{v}}_n)^\top \nabla^2 g(\varrho_n) (\check{\mathbf{v}}_{(n+1)-} - \check{\mathbf{v}}_n) \\
&= \eta_n^\beta \langle \nabla g(\check{\mathbf{v}}_n), \nabla f(\mathbf{x}^*) + \xi_n^{(2)} \rangle + \eta_n^\beta \left\langle \nabla g(\check{\mathbf{v}}_n), \frac{1}{\eta_n^\beta} \sum_{i=1}^3 \mathcal{S}_n^{(i)} \right\rangle \\
&+ \frac{\eta_n^{2\beta}}{2} (\mathbf{d}_n + \xi_n^{(2)})^\top \nabla^2 g(\varrho_n) (\mathbf{d}_n + \xi_n^{(2)})
\end{aligned} \tag{76}$$

Substitute this equation into the second term of the right hand of the equation (75). It follows that

$$\begin{aligned}
\mathbb{E}[g(\check{\mathbf{v}}_{n+1}) - g(\check{\mathbf{v}}_n) | \mathcal{F}_n] &= \eta_n^\beta (\gamma(g(\mathbf{0}) - g(\check{\mathbf{v}}_n)) + \langle \nabla g(\check{\mathbf{v}}_n), -\nabla f(\mathbf{x}^*) \rangle) \\
&+ \eta_n^\beta \mathbb{E} \left[\left\langle \nabla g(\check{\mathbf{v}}_n), \frac{1}{\eta_n^\beta} \sum_{i=1}^3 \mathcal{S}_n^{(i)} \right\rangle \middle| \mathcal{F}_n \right] + \frac{\eta_n^{2\beta}}{2} \mathbb{E} \left[(\mathbf{d}_n + \xi_n^{(2)})^\top \nabla^2 g(\varrho_n) (\mathbf{d}_n + \xi_n^{(2)}) \middle| \mathcal{F}_n \right] \\
&- \gamma \eta_n^{2\beta} \mathbb{E} \left[\langle \nabla g(\check{\mathbf{v}}_n), \mathbf{d}_n + \xi_n^{(2)} \rangle + \frac{\eta_n^\beta}{2} (\mathbf{d}_n + \xi_n^{(2)})^\top \nabla g(\varrho_n) (\mathbf{d}_n + \xi_n^{(2)}) \middle| \mathcal{F}_n \right] \\
&=: \eta_n^\beta \{ \gamma(g(\mathbf{0}) - g(\check{\mathbf{v}}_n)) - \langle \nabla g(\check{\mathbf{v}}_n), \nabla f(\mathbf{x}^*) \rangle \} + \underbrace{\mathcal{T}_n^{(1)} + \mathcal{T}_n^{(2)} + \mathcal{T}_n^{(3)}}_{\mathcal{T}_n^g}
\end{aligned} \tag{77}$$

From the Theorem 3.1 and the equation (59), we have $\mathbb{E}|\mathcal{T}_n^{(1)}| = o(\eta_n^\beta)$. And $\mathbb{E}|\mathcal{T}_n^{(2)}| = \mathcal{O}(\eta_n^{2\beta})$ by leveraging that $\|\nabla^2 g(\mathbf{x})\|$ is bounded for all $\mathbf{x} \in \mathbb{R}^d$ and that $\mathbb{E}\|\mathbf{d}_n + \xi_n^{(2)}\|^2$ is bounded. Similar approaches can be used to show that $\mathbb{E}|\mathcal{T}_n^{(3)}| = \mathcal{O}(\eta_n^{2\beta})$. At this point, the result has been proved. \square

From the Itô's formula for the semimartingales, we know that the infinitesimal generator \mathcal{J} defined in the Lemma 11 corresponds to the following stochastic differential equation driven by the Poisson process with intensity γ .

$$d\mathbf{Y}_t = -\nabla f(\mathbf{x}^*) dt - \mathbf{Y}_t \cdot \mathbf{N}_\gamma(dt) \tag{78}$$

Lemma 12. *There exists a unique invariant measure \mathbf{u}^* for the Lévy process (78). Further, for any initial distribution ν_0 , we have $\mathcal{W}_2(\mathcal{G}^t \nu_0, \nu^*) \rightarrow 0$; $t \rightarrow \infty$. Where \mathcal{W}_2 represents the Wasserstein-2 distance and $\{\mathcal{G}^t\}$ is the Markovian semigroup generated by the infinitesimal generator \mathcal{J} .*

Proof. (Proof of Lemma 12)

Consider the set of probability density functions $\left\{ h(\mathbf{x}) = p(t) \mathbb{1}_{\left\{ \mathbf{x} = \frac{\nabla f(\mathbf{x}^*)}{\|\nabla f(\mathbf{x}^*)\|} t \right\}} : p(t) \text{ is a p.d.f on } \mathbb{R} \right\}$ and denote it as \mathcal{M} . Then the distribution of any \mathbf{Y}_t only has mass on the line $\left\{ \frac{\nabla f(\mathbf{x}^*)}{\|\nabla f(\mathbf{x}^*)\|} t : t \in \mathbb{R} \right\}$ if we choose the initial distribution in \mathcal{M} . In this case, we can suppose $\mathbf{Y}_t = -\frac{\nabla f(\mathbf{x}^*)}{\|\nabla f(\mathbf{x}^*)\|} v_t$. Consequently, v_t satisfies the following one dimensional stochastic differential equation,

$$dv_t = \|\nabla f(\mathbf{x}^*)\| dt - v_t \mathbf{N}_\gamma(dt). \tag{79}$$

Let $\varphi_t(\lambda) = \mathbb{E}_{p^*} e^{i\lambda v_t}$ be the characteristic function of v_t with stationary initialization p^* . Then we have $\varphi_t(\lambda) = \varphi_s(\lambda)$; $\forall t \neq s$. On the other hand, consider the martingale problem corresponding to (79). It says that $e^{i\lambda v_t} - e^{i\lambda v_0} - \int_0^t (i\lambda \|\nabla f(\mathbf{x}^*)\| e^{i\lambda v_s} + \gamma(1 - e^{i\lambda v_s})) ds$ is a martingale with respect to the natural filtration generated by v_t . Take expectation we have

$$\begin{aligned}
0 &= \varphi_t(\lambda) - \varphi_0(\lambda) - \int_0^t \{i\lambda \|\nabla f(\mathbf{x}^*)\| \varphi_s(\lambda) + \gamma(1 - \varphi_s(\lambda))\} ds \\
&= - \int_0^t \{i\lambda \|\nabla f(\mathbf{x}^*)\| \varphi_s(\lambda) + \gamma(1 - \varphi_s(\lambda))\} ds
\end{aligned} \tag{80}$$

Which means that

$$i\lambda \|\nabla f(\mathbf{x}^*)\| \varphi_s(\lambda) + \gamma(1 - \varphi_s(\lambda)) = 0; \quad \forall s > 0 \tag{81}$$

i.e. $\varphi_s(\lambda) = \frac{1}{1 - i\|\nabla f(\mathbf{x}^*)\|_\lambda}$. So the invariant distribution of v_t is $\mathcal{E}\left(\frac{\|\nabla f(\mathbf{x}^*)\|}{\gamma}\right)$. As a result, the invariant distribution of \mathbf{Y}_t is $\frac{\nabla f(\mathbf{x}^*)}{\|\nabla f(\mathbf{x}^*)\|} \cdot \mathcal{E}\left(\frac{\|\nabla f(\mathbf{x}^*)\|}{\gamma}\right)$.

To show the mixing result, it is enough to prove the following fact,

$$\frac{1}{\|\mathbf{y}_0 - \mathbf{y}_1\|} \mathcal{W}_2(\mathcal{G}^t \delta_{\mathbf{y}_0}, \mathcal{G}^t \delta_{\mathbf{y}_1}) \rightarrow 0; \quad t \rightarrow \infty \quad \forall \mathbf{y}_0 \neq \mathbf{y}_1. \quad (82)$$

Where $\delta_{\mathbf{y}}$ represents the Dirac measure at the point \mathbf{y} . Let \mathbf{Y}_t^0 and \mathbf{Y}_t^1 be the stochastic process generated by (78) with initial distribution $\delta_{\mathbf{y}_0}$ and $\delta_{\mathbf{y}_1}$ respectively. To give a bound for the Wasserstein-2 distance between \mathbf{Y}_t^0 and \mathbf{Y}_t^1 , we compute the L_2 norm under the identical coupling, i.e., the two dynamics share all randomness in the Poisson process $\mathbf{N}_\gamma(s)$, $s \in [0, t]$. Owing to the property of the corresponding martingale problem of (78), we have

$$\begin{aligned} 0 &= \mathbb{E}\|\mathbf{Y}_t^0 - \mathbf{Y}_t^1\|^2 - \|\mathbf{y}_0 - \mathbf{y}_1\|^2 \\ &\quad - \int_0^t \mathbb{E} \left\{ -(\nabla f(\mathbf{x}^*)^\top, \nabla f(\mathbf{x}^*)^\top) \begin{bmatrix} \mathbf{I} & -\mathbf{I} \\ -\mathbf{I} & \mathbf{I} \end{bmatrix} \begin{bmatrix} \mathbf{Y}_s^0 \\ \mathbf{Y}_s^1 \end{bmatrix} - \gamma \|\mathbf{Y}_s^0 - \mathbf{Y}_s^1\|^2 \right\} ds \\ &= \mathbb{E}\|\mathbf{Y}_t^0 - \mathbf{Y}_t^1\|^2 - \|\mathbf{y}_0 - \mathbf{y}_1\|^2 + \gamma \int_0^t \mathbb{E}\|\mathbf{Y}_s^0 - \mathbf{Y}_s^1\|^2 ds \end{aligned} \quad (83)$$

Solving above integral equation we finally get $\mathbb{E}\|\mathbf{Y}_t^0 - \mathbf{Y}_t^1\|^2 = \|\mathbf{y}_0 - \mathbf{y}_1\|^2 e^{-\gamma t}$. Hence, the equation (82) has been proved. \square

Proof. (Proof of Theorem 3.4)

This proof is basically modeled after the proof of Theorem 3.3. Therefore, for the sake of narrative simplicity, we will omit some details that overlap with the previous proofs. All symbols follow the meaning in the proof of Theorem 3.3 without special specification. Analogously, two steps are split to complete to proof.

Step 1 Let g belongs to \mathcal{C} and let $\mathcal{D}_t^{(n)}$ denote the natural filtration of $\bar{\mathbf{v}}_t^{(n)}$. We aim to find the following martingale decomposition,

$$\forall t > 0, \quad g(\bar{\mathbf{v}}_t^{(n)}) - g(\bar{\mathbf{v}}_0^{(n)}) - \int_0^t \mathcal{J}g(\bar{\mathbf{v}}_s^{(n)}) ds = \mathcal{N}_t^{(n,g)} + \mathcal{T}_t^{(n,g)}. \quad (84)$$

Where $\mathcal{N}_t^{(n,g)}$ is a $\mathcal{D}_t^{(n)}$ -martingale and $\mathcal{T}_t^{(n,g)}$ converges to zero in L_1 . In fact, let

$$\begin{aligned} \mathcal{N}_t^{(n,g)} &= \sum_{k=n+1}^{N(n,t,\eta^\beta)} \{g(\check{\mathbf{v}}_{k+1}) - g(\check{\mathbf{v}}_k) - \mathbb{E}[g(\check{\mathbf{v}}_{k+1}) - g(\check{\mathbf{v}}_k) | \mathcal{D}_k]\} \\ \mathcal{T}_t^{(n,g)} &= g(\bar{\mathbf{v}}_t^{(n)}) - g(\bar{\mathbf{v}}_{\underline{t}_n(\eta^\beta)}^{(n)}) - \int_{\underline{t}_n(\eta^\beta)}^t \mathcal{J}g(\bar{\mathbf{v}}_s^{(n)}) ds \\ &\quad + \int_0^{\underline{t}_n(\eta^\beta)} \left(\mathcal{J}g(\bar{\mathbf{v}}_{\underline{s}_n(\eta^\beta)}^{(n)}) - \mathcal{J}g(\bar{\mathbf{v}}_s^{(n)}) \right) ds + \sum_{k=n}^{N(n,t,\eta^\beta)-1} \mathcal{T}_k^g. \end{aligned} \quad (85)$$

Using the definition formula of $\bar{\mathbf{v}}_t^{(n)}$ (9) when $t \notin \mathcal{L}_n(T)$,

$$\begin{aligned} \mathbb{E} \left\| \bar{\mathbf{v}}_t^{(n)} - \bar{\mathbf{v}}_{\underline{t}_n(\eta^\beta)}^{(n)} \right\|^2 &= (t - \underline{t}_n(\eta^\beta))^2 \mathbb{E} \|\mathbf{d}_{N(n,t,\eta^\beta)} - \xi_{N(n,t,\eta^\beta)}^{(2)}\|^2 \\ &\leq \mathcal{C} \eta_n^{2\beta}. \end{aligned} \quad (86)$$

This inequality combined with the Lipschitz continuity of g and its derivatives implies that the first three terms in the definition of $\mathcal{T}_t^{(n,g)}$ tend to 0 when $n \rightarrow \infty$. Further, by Lemma 11,

$$\begin{aligned} \mathbb{E} \left| \sum_{k=n}^{N(n,t,\eta^\beta)-1} \mathcal{T}_k^g \right| &\leq \sum_{k=n}^{N(n,t,\eta^\beta)-1} \eta_k^\beta \mathbb{E} \left| \frac{\mathcal{T}_k^g}{\eta_k^\beta} \right| \\ &\leq \sup_{k \geq n} \mathbb{E} \left| \frac{\mathcal{T}_k^g}{\eta_k^\beta} \right| (t + \eta_n^\beta) \xrightarrow{n \rightarrow \infty} 0. \end{aligned} \quad (87)$$

Step 2 Suppose that there is a weakly convergent subsequence $\{\check{\nu}_{n_k}\}_{k=1}^\infty$ with limit distribution $\check{\nu}$. The definition of $M(n, t, \eta^\beta)$ and $t_n(\eta^\beta)$ can be extended intuitively from the first paragraph in the second step of the Theorem 3.3's proof.

Owing to the Prokhorov's theorem and Lemma 10, for any $T > 0$, there is a weakly convergent subsequence in $\{\check{\nu}_t^{M(n_k, T, \eta^\beta)}\}$. By the Theorem 1 in [20], we know that the weak limit of this sequence is a solution of the stochastic differential equation (78). And WLOG, we assume the sequence itself converges weakly to a solution $\check{\nu}_t^{\tilde{\pi}^{(T)}}$ of (78) with initial distribution $\tilde{\pi}^{(T)}$ (the notations of $\check{\nu}$ and $\tilde{\pi}$ are independent with one in proof of Theorem 3.3). By Lemma 10, for any given $\epsilon > 0$, a compact set K_ϵ can be found such that $\sup_n \mathbb{P}(\check{\nu}_n \in K_\epsilon^c) \leq \epsilon$. Therefore, for all $T > 0$, $\tilde{\pi}^{(T)}(K_\epsilon) \geq 1 - \epsilon$.

Due to Lemma 12, a T_ϵ can be found such that

$$\sup_{i \in K_\epsilon} \sup_{g \in \mathcal{C}} |\mathcal{G}^{T_\epsilon} g(\mathbf{x}) - \langle \nu^*, g \rangle| \leq \epsilon. \quad (88)$$

Where \mathcal{G} is the Markov semigroup induced by the SDE (78). Because $(\widetilde{T_\epsilon})_n(\eta^\beta)$ converges to T_ϵ when $n \rightarrow \infty$, we have $\check{\nu}_{n_k} \left(= \check{\nu}_{\frac{M(n_k, T_\epsilon, \eta^\beta)}{(\widetilde{T_\epsilon})_n(\eta^\beta)}} \right)$ converges weakly to the limit random variable of the sequence $\check{\nu}_{T_\epsilon}^{M(n_k, T_\epsilon, \eta^\beta)}$, i.e., $\check{\nu}_{T_\epsilon}^{\tilde{\pi}^{(T_\epsilon)}}$. On the other hand, by assumption, $\check{\nu}_{n_k}$ converges weakly to $\check{\nu}$. Thus $\check{\nu}_{T_\epsilon}^{\tilde{\pi}^{(T_\epsilon)}} \sim \check{\nu}$. Combining all result we have obtained, the inequality corresponded to (55) can be derived. Consequently, we obtain $\check{\nu} = \nu^*$. Finally, by the Prokhorov's theorem, $\check{\nu}_n$ convergence weakly to ν^* . Further, $\{\check{\nu}_t^{(n)}\}$ converges weakly to the dynamics (78) with stationary distribution ν^* as initialization. \square

Before we start proving the Corollary 1, we need to use the following lemma.

Lemma 13. *Let $\{r_t\}$ be the sequence defined in Lemma 1. If a positive sequence $\{x_t\}$ satisfies:*

$$x_{t+1} \leq (1 - r_t)x_t + o(r_t), \quad (89)$$

then $\lim_{t \rightarrow \infty} x_t \rightarrow 0$.

Proof. (Proof of Lemma 13) By the recursive inequality (89), for any given $\epsilon > 0$ there is a t_0 such that $\forall t > t_0$, $o(r_t) < \epsilon r_t$. Iterate the relation (89) and combine Lemma 1. Consequently, we have,

$$x_t \leq \prod_{k=t_0}^t (1 - r_k)x_{t_0} + \sum_{k=t_0+1}^t \epsilon r_k \prod_{s=k+1}^t (1 - r_s) \rightarrow 0 + \epsilon; \quad t \rightarrow \infty. \quad (90)$$

Because ϵ can be chosen arbitrarily, the final limit of x_t is zero. \square

Proof. (Proof of Corollary 1)

We prove the target conclusion in two steps. First we show that the mean of $\hat{\mathbf{u}}_n$ converges to a constant non-zero vector. Next, we will see that the asymptotic variance of $\{\hat{\mathbf{u}}_n\}$ is zero for $\beta \in (\frac{1}{2}, 1)$.

Step 1 The first thing we need to do is to derive the recurrence relation for $\hat{\mathbf{u}}_n$,

$$\begin{aligned}
\hat{\mathbf{u}}_{n+1} &= \mathcal{P}_{\mathbf{A}^\perp} \frac{\mathbf{x}_{(n+1)-} - \mathbf{x}^*}{\eta_n^{1-\beta}} = \frac{\mathcal{P}_{\mathbf{A}^\perp}(\mathbf{x}_n - \mathbf{x}^* - \eta_n \nabla f(\mathbf{x}_n) + \eta_n \xi_n)}{\eta_n^{1-\beta}} \\
&= \left(\frac{\eta_{n-1}}{\eta_n} \right)^{1-\beta} \hat{\mathbf{u}}_n - \eta_n^\beta \mathcal{P}_{\mathbf{A}^\perp} \nabla f(\mathbf{x}_n) + \eta_n^\beta \xi_n^{(1)} \\
&= \hat{\mathbf{u}}_n - \eta_n^\beta \mathcal{P}_{\mathbf{A}^\perp} \{ \nabla^2 f(\mathbf{x}^*)(\mathbf{x}_n - \mathbf{u}_n) + [\nabla^2 f(\vartheta_n^v) - \nabla^2 f(\mathbf{x}^*)](\mathbf{x}_n - \mathbf{u}_n) \} \\
&\quad + \left(\left(\frac{\eta_{n-1}}{\eta_n} \right)^{1-\beta} - 1 \right) \hat{\mathbf{u}}_n + \eta_n^\beta \xi_n^{(1)} \\
&\quad - \eta_n^\beta \mathcal{P}_{\mathbf{A}^\perp} \{ \nabla^2 f(\mathbf{x}^*)(\mathbf{u}_n - \mathbf{x}^*) + [\nabla^2 f(\vartheta_n^u) - \nabla^2 f(\mathbf{x}^*)](\mathbf{u}_n - \mathbf{x}^*) \} \\
&= (\mathbf{I} - \eta_n \mathcal{P}_{\mathbf{A}^\perp} \nabla^2 f(\mathbf{x}^*) \mathcal{P}_{\mathbf{A}^\perp}) \hat{\mathbf{u}}_n - \eta_n \mathcal{P}_{\mathbf{A}^\perp} \nabla^2 f(\mathbf{x}^*) \check{\mathbf{v}}_n + \eta_n^\beta \xi_n^{(1)} \\
&\quad + (\eta_n - \eta_n^\beta \eta_{n-1}^{1-\beta}) \mathcal{P}_{\mathbf{A}^\perp} \nabla^2 f(\mathbf{x}^*) \hat{\mathbf{u}}_n + (\eta_n - \eta_n^\beta \eta_{n-1}^{1-\beta}) \mathcal{P}_{\mathbf{A}^\perp} \nabla^2 f(\mathbf{x}^*) \check{\mathbf{v}}_n \\
&\quad - \{ \eta_n^\beta \mathcal{P}_{\mathbf{A}^\perp} (\nabla^2 f(\vartheta_n^v) - \nabla^2 f(\mathbf{x}^*)) (\mathbf{x}_n - \mathbf{u}_n) \} \\
&\quad - \{ \eta_n^\beta \mathcal{P}_{\mathbf{A}^\perp} [\nabla^2 f(\vartheta_n^u) - \nabla^2 f(\mathbf{x}^*)](\mathbf{u}_n - \mathbf{x}^*) \} \\
&\quad + \left(\left(\frac{\eta_{n-1}}{\eta_n} \right)^{1-\beta} - 1 \right) \hat{\mathbf{u}}_n \\
&=: \left(\mathbf{I} - \eta_n \mathcal{P}_{\mathbf{A}^\perp} \left(\nabla^2 f(\mathbf{x}^*) - \frac{1-\beta}{\eta_0} \mathbb{1}_{\{\alpha=1\}} \mathbf{I}_d \right) \mathcal{P}_{\mathbf{A}^\perp} \right) \hat{\mathbf{u}}_n \\
&\quad - \eta_n \mathcal{P}_{\mathbf{A}^\perp} \nabla^2 f(\mathbf{x}^*) \check{\mathbf{v}}_n + \eta_n^\beta \xi_n^{(1)} + \eta_n \mathcal{R}_n^{\mathbf{u}}
\end{aligned} \tag{91}$$

Where ϑ_n^u and ϑ_n^v are two entrywise interpolation point between \mathbf{u}_n and \mathbf{x}_n ; \mathbf{u}_n and \mathbf{x}^* respectively. And,

$$\begin{aligned}
\mathcal{R}_n^{\mathbf{u}} &= \left(1 - \left(\frac{\eta_{n-1}}{\eta_n} \right)^{1-\beta} \right) \mathcal{P}_{\mathbf{A}^\perp} \nabla^2 f(\mathbf{x}^*) (\hat{\mathbf{u}}_n + \check{\mathbf{v}}_n) + \frac{1}{\eta_n} \left(\left(\frac{\eta_{n-1}}{\eta_n} \right)^{1-\beta} - 1 - \frac{1-\beta}{n} \mathbb{1}_{\{\alpha=1\}} \right) \hat{\mathbf{u}}_n \\
&\quad - \left(\frac{\eta_{n-1}}{\eta_n} \right)^{1-\beta} \mathcal{P}_{\mathbf{A}^\perp} \{ (\nabla^2 f(\vartheta_n^v) - \nabla^2 f(\mathbf{x}^*)) \check{\mathbf{v}}_n + (\nabla^2 f(\vartheta_n^u) - \nabla^2 f(\mathbf{x}^*)) \hat{\mathbf{u}}_n \}
\end{aligned} \tag{92}$$

The properties of the step size sequence $\{\eta_n\}$ tell us that, when $\alpha < 1$,

$$\begin{aligned}
1 - \left(\frac{\eta_{n-1}}{\eta_n} \right)^{1-\beta} &= 1 - \left(1 + \frac{\eta_{n-1} - \eta_n}{\eta_n} \right)^{1-\beta} \\
&= 1 - (1 + o(\eta_n))^{1-\beta} = (1-\beta)o(\eta_n) = o(1)\eta_n.
\end{aligned} \tag{93}$$

And when $\alpha = 1$,

$$1 + \frac{1-\beta}{n} - \left(\frac{n}{n-1} \right)^{1-\beta} = 1 + \frac{1-\beta}{n} - \left(1 + \frac{1-\beta}{n} + \mathcal{O}(n^{-2}) \right) = o(\eta_n)$$

The result can be used to guarantee the first line of (92) being $o(1)$ in L_2 . By the assumption 3 and 1, $\nabla^2 f(\cdot)$ is Lipschitz continuous and uniformly bounded. Then for any $\delta \in (0, 1)$, $\nabla^2 f(\cdot)$ is δ -Hölder continuous. Similar to the proof of the Lemmas 4 and 5, by leveraging the Taylor expansion for $\|\cdot\|^p$, $3 > p > 2$, we can deduce the following analogous bounds,

$$\begin{aligned}
\mathbb{E} \|\mathbf{u}_n - \mathbf{x}^*\|^p &\lesssim \eta_n^{p(1-\beta)}; \\
\mathbb{E} \|\mathbf{v}_n\|^p &\lesssim \eta_n^{p(1-\beta)}
\end{aligned} \tag{94}$$

when $\beta \in [\frac{1}{2}, 1)$. Based on these preparations, take $\delta = p/2 - 1$ and use the Young's inequality,

$$\begin{aligned}
\mathbb{E} \left\| (\nabla^2 f(\vartheta_n^v) - \nabla^2 f(\mathbf{x}^*)) \check{\mathbf{v}}_n \right\|^2 &\lesssim \mathbb{E} \|\vartheta_n^u - \mathbf{x}^*\|^{2\delta} \|\check{\mathbf{v}}_n\|^2 \\
&\lesssim \mathbb{E} \left(\|\mathbf{v}_n\|^{2\delta} + \|\mathbf{u}_n - \mathbf{x}^*\|^{2\delta} \right) \|\check{\mathbf{v}}_n\|^2 \\
&= \frac{1}{\eta_{n-1}^{2(1-\beta)}} \mathbb{E} \|\mathbf{v}_n\|^p + \frac{1}{\eta_{n-1}^{2(1-\beta)}} \mathbb{E} \|\mathbf{u}_n - \mathbf{x}^*\|^{2\delta} \|\mathbf{v}_n\|^2 \\
&\lesssim \frac{1}{\eta_{n-1}^{2(1-\beta)}} (\mathbb{E} \|\mathbf{v}_n\|^p + \mathbb{E} \|\mathbf{u}_n - \mathbf{x}^*\|^p) \lesssim \eta_n^{(p-2)(1-\beta)}.
\end{aligned} \tag{95}$$

The same bound can be derived for $(\nabla^2 f(\vartheta_n^u) - \nabla^2 f(\mathbf{x}^*)) \check{\mathbf{u}}_n$. These two results enable the second line of (92) to be $o(1)$ in L_2 . To simplify our writing, we denote $\boldsymbol{\nu} = -\frac{1}{\gamma} \nabla f(\mathbf{x}^*)$ and

$\boldsymbol{\mu} = \frac{1}{\gamma} \left(\mathcal{P}_{\mathbf{A}^\perp} \left(\nabla^2 f(\mathbf{x}^*) - \frac{1-\beta}{\eta_0} \mathbb{1}_{\{\alpha=1\}} \mathbf{I}_d \right) \mathcal{P}_{\mathbf{A}^\perp} \right)^\dagger \mathcal{P}_{\mathbf{A}^\perp} \nabla^2 f(\mathbf{x}^*) \nabla f(\mathbf{x}^*)$. Taking the expectation on both sides of (91) yields

$$\begin{aligned}
\mathbb{E} \hat{\mathbf{u}}_{n+1} &= \left(\mathbf{I} - \eta_n \left(\mathcal{P}_{\mathbf{A}^\perp} \nabla^2 f(\mathbf{x}^*) - \frac{1-\beta}{\eta_0} \mathbb{1}_{\{\alpha=1\}} \mathbf{I}_d \right) \mathcal{P}_{\mathbf{A}^\perp} \right) \mathbb{E} \hat{\mathbf{u}}_n \\
&\quad - \eta_n \mathcal{P}_{\mathbf{A}^\perp} \nabla^2 f(\mathbf{x}^*) \mathbb{E} \check{\mathbf{v}}_n + \eta_n \mathbb{E} \mathcal{R}_n^u
\end{aligned} \tag{96}$$

Subtract $\mathcal{P}_{\mathbf{A}^\perp} \nabla^2 f(\mathbf{x}^*) \boldsymbol{\nu}$ from both sides of (96) and we have,

$$\begin{aligned}
\mathbb{E} \hat{\mathbf{u}}_{n+1} - \boldsymbol{\mu} &= \left(\mathbf{I} - \eta_n \mathcal{P}_{\mathbf{A}^\perp} \left(\nabla^2 f(\mathbf{x}^*) - \frac{1-\beta}{\eta_0} \mathbb{1}_{\{\alpha=1\}} \mathbf{I}_d \right) \mathcal{P}_{\mathbf{A}^\perp} \right) (\mathbb{E} \hat{\mathbf{u}}_n - \boldsymbol{\mu}) \\
&\quad - \eta_n \left(\mathcal{P}_{\mathbf{A}^\perp} \nabla^2 f(\mathbf{x}^*) (\mathbb{E} \check{\mathbf{v}}_n - \boldsymbol{\nu}) + \mathbb{E} \mathcal{R}_n^u \right)
\end{aligned} \tag{97}$$

According to Theorem 3.4 we know $\|\mathbb{E} \check{\mathbf{v}}_n - \boldsymbol{\nu}\| = o(1)$. As a result of this and $\|\mathbb{E} \mathcal{R}_n^u\| \leq \mathbb{E} \|\mathcal{R}_n^u\| = o(1)$, the last term in the right hand of (97) is $o(\eta_n)$. Therefore, using Lemma 13, it holds that $\|\mathbb{E} \hat{\mathbf{u}}_n - \boldsymbol{\mu}\| = o(1)$, which means $\mathbb{E} \hat{\mathbf{u}}_n \xrightarrow{n \rightarrow \infty} \boldsymbol{\mu}$.

Step 2 Before we calculate the asymptotic variance of $\hat{\mathbf{u}}_n$, consider the inner product $|\mathbb{E} \langle \hat{\mathbf{u}}_n - \mathbb{E} \hat{\mathbf{u}}_n, \nabla^2 f(\mathbf{x}^*) (\check{\mathbf{v}}_n - \mathbb{E} \check{\mathbf{v}}_n) \rangle|$,

$$\begin{aligned}
&|\mathbb{E} \langle \hat{\mathbf{u}}_{n+1} - \mathbb{E} \hat{\mathbf{u}}_{n+1}, \nabla^2 f(\mathbf{x}^*) (\check{\mathbf{v}}_{n+1} - \mathbb{E} \check{\mathbf{v}}_{n+1}) \rangle| \\
&= (1 - \gamma \eta_n^\beta) |\mathbb{E} \langle \hat{\mathbf{u}}_{n+1} - \mathbb{E} \hat{\mathbf{u}}_{n+1}, \nabla^2 f(\mathbf{x}^*) (\check{\mathbf{v}}_{(n+1)-} - \mathbb{E} \check{\mathbf{v}}_{(n+1)}) \rangle| + \gamma \eta_n^\beta |\mathbb{E} \langle \hat{\mathbf{u}}_{n+1} - \mathbb{E} \hat{\mathbf{u}}_{n+1}, \nabla^2 f(\mathbf{x}^*) \mathbb{E} \check{\mathbf{v}}_{n+1} \rangle| \\
&= (1 - \gamma \eta_n^\beta) |\mathbb{E} \langle \hat{\mathbf{u}}_{n+1} - \mathbb{E} \hat{\mathbf{u}}_{n+1}, \nabla^2 f(\mathbf{x}^*) (\check{\mathbf{v}}_{(n+1)-} - \mathbb{E} \check{\mathbf{v}}_{(n+1)}) \rangle| \\
&= (1 - \gamma \eta_n^\beta) \left| \mathbb{E} \left\langle \left(\mathbf{I} - \eta_n \mathcal{P}_{\mathbf{A}^\perp} \left(\nabla^2 f(\mathbf{x}^*) - \frac{1-\beta}{\eta_0} \mathbb{1}_{\{\alpha=1\}} \mathbf{I}_d \right) \mathcal{P}_{\mathbf{A}^\perp} \right) (\hat{\mathbf{u}}_n - \mathbb{E} \hat{\mathbf{u}}_n) - \eta_n \mathcal{P}_{\mathbf{A}^\perp} \nabla^2 f(\mathbf{x}^*) (\check{\mathbf{v}}_n - \mathbb{E} \check{\mathbf{v}}_n) \right. \right. \\
&\quad \left. \left. + \eta_n^\beta \xi_n^{(1)} + \eta_n (\mathcal{R}_n^u - \mathbb{E} \mathcal{R}_n^u), \nabla^2 f(\mathbf{x}^*) \left\{ (\check{\mathbf{v}}_n - \mathbb{E} \check{\mathbf{v}}_n) + \eta_n^\beta \xi_n^{(2)} + \eta_n^\beta (\mathcal{R}_n^v - \mathbb{E} \mathcal{R}_n^v) \right\} \right\rangle \right| \\
&\leq (1 - \gamma \eta_n^\beta) |\mathbb{E} \langle \hat{\mathbf{u}}_n - \mathbb{E} \hat{\mathbf{u}}_n, \nabla^2 f(\mathbf{x}^*) (\check{\mathbf{v}}_n - \mathbb{E} \check{\mathbf{v}}_n) \rangle| + \eta_n^\beta |\mathbb{E} \langle \hat{\mathbf{u}}_n - \mathbb{E} \hat{\mathbf{u}}_n, \nabla^2 f(\mathbf{x}^*) (\mathcal{R}_n^v - \mathbb{E} \mathcal{R}_n^v) \rangle| + \mathcal{O}(\eta_n)
\end{aligned} \tag{98}$$

From the fact $\mathbb{E} \|\mathcal{R}_n^v\|^2 = o(1)$, we have

$$|\mathbb{E} \langle \hat{\mathbf{u}}_{n+1} - \mathbb{E} \hat{\mathbf{u}}_{n+1}, \nabla^2 f(\mathbf{x}^*) (\check{\mathbf{v}}_{n+1} - \mathbb{E} \check{\mathbf{v}}_{n+1}) \rangle| \leq (1 - \gamma \eta_n^\beta) |\mathbb{E} \langle \hat{\mathbf{u}}_n - \mathbb{E} \hat{\mathbf{u}}_n, \nabla^2 f(\mathbf{x}^*) (\check{\mathbf{v}}_n - \mathbb{E} \check{\mathbf{v}}_n) \rangle| + o(\eta_n^\beta) \tag{99}$$

We can obtain from Lemma 13 that $|\mathbb{E} \langle \hat{\mathbf{u}}_n - \mathbb{E} \hat{\mathbf{u}}_n, \nabla^2 f(\mathbf{x}^*) (\check{\mathbf{v}}_n - \mathbb{E} \check{\mathbf{v}}_n) \rangle| \xrightarrow{n \rightarrow \infty} 0$.

Back to the main result's proof, we can write down the recursive rule for the variance of $\hat{\mathbf{u}}_n$,

$$\begin{aligned}
&\mathbb{E} \|\hat{\mathbf{u}}_{n+1} - \mathbb{E} \hat{\mathbf{u}}_{n+1}\|^2 \\
&= \mathbb{E} \left\| \left(\mathbf{I} - \eta_n \mathcal{P}_{\mathbf{A}^\perp} \left(\nabla^2 f(\mathbf{x}^*) - \frac{1-\beta}{\eta_0} \mathbb{1}_{\{\alpha=1\}} \mathbf{I}_d \right) \mathcal{P}_{\mathbf{A}^\perp} \right) (\hat{\mathbf{u}}_n - \mathbb{E} \hat{\mathbf{u}}_n) \right. \\
&\quad \left. - \eta_n \mathcal{P}_{\mathbf{A}^\perp} \nabla^2 f(\mathbf{x}^*) (\check{\mathbf{v}}_n - \mathbb{E} \check{\mathbf{v}}_n) + \eta_n^\beta \xi_n^{(1)} + \eta_n (\mathcal{R}_n^u - \mathbb{E} \mathcal{R}_n^u) \right\|^2 \\
&\leq (1 - \mu \eta_n) \mathbb{E} \|\hat{\mathbf{u}}_n - \mathbb{E} \hat{\mathbf{u}}_n\|^2 - \eta_n \mathbb{E} \langle \hat{\mathbf{u}}_n - \mathbb{E} \hat{\mathbf{u}}_n, \nabla^2 f(\mathbf{x}^*) (\check{\mathbf{v}}_n - \mathbb{E} \check{\mathbf{v}}_n) \rangle + \eta_n^{2\beta} \mathbb{E} \langle \xi_n^{(1)}, \xi_n^{(2)} \rangle + o(\eta_n) \\
&\leq (1 - \mu \eta_n) \mathbb{E} \|\hat{\mathbf{u}}_n - \mathbb{E} \hat{\mathbf{u}}_n\|^2 + o(\eta_n).
\end{aligned} \tag{100}$$

Where the last equation follows from the diminish correlation we derived just now and the pre-condition $\beta > \frac{1}{2}$. Finally, the Lemma is completed from Lemma 13 and the fact $\mathbb{E} \|\hat{\mathbf{u}}_n - \boldsymbol{\mu}\|^2 = \mathbb{E} \|\hat{\mathbf{u}}_n - \mathbb{E}\hat{\mathbf{u}}_n\|^2 + \|\mathbb{E}\hat{\mathbf{u}}_n - \boldsymbol{\mu}\|^2 \rightarrow 0$. \square

D Experimental Details

In this section, we present the experimental details and the complete results on three different datasets.

D.1 Datasets

We have introduced two datasets in Section 4 in the FL setting. We will restate them and add a new dataset for the general linearly constrained problem.

IID There are K clients and the sample (\mathbf{x}_k, z_k) on the k -th client is modeled as $\mathbf{x}_k \sim \mathcal{N}(\nu_k, \Lambda)$ and $z_k = \operatorname{argmax}(\operatorname{softmax}(\mathbf{W}_k \mathbf{x}_k + \mathbf{b}_k))$ where $\Lambda \in \mathbb{R}^{d \times d}$ is diagonal with the entry (j, j) equal to $j^{-1.2}$, all the clients share the same $\mathbf{W}_k \in \mathbb{R}^{C \times d}$ and $\mathbf{b}_k \in \mathbb{R}^C$ and their entries are modeled as $\mathcal{N}(0, 1)$. We set $K = 100$, $d = 60$ and $C = 10$. For this dataset, there is no heterogeneity between the optimal local parameters. The heterogeneity is all from the diversity of the distributions of \mathbf{x}_k . For each client, the sample size is around 100.

Synthetic (a, b) There are K clients and the sample (\mathbf{x}_k, z_k) on the k -th client is modeled as $\mathbf{x}_k \sim \mathcal{N}(\nu_k, \Lambda)$ and $z_k = \operatorname{argmax}(\operatorname{softmax}(\mathbf{W}_k \mathbf{x}_k + \mathbf{b}_k))$ where $\Lambda \in \mathbb{R}^{d \times d}$ is diagonal with the entry (j, j) equal to $j^{-1.2}$, each entry of \mathbf{W}_k and \mathbf{b}_k is modeled as $\mathcal{N}(\mu_k, 1)$ with $\mu_k \sim \mathcal{N}(0, a)$ and $\nu_k \sim \mathcal{N}(\zeta_k, \mathbf{I})$ with $\zeta_k \sim \mathcal{N}(\mathbf{0}, b\mathbf{I}_d)$. We set $K = 20$, $d = 10$ and $C = 5$. a controls how many local models differ from each other and b controls how much the local data for each client differs from that of other clients. They are the two sources of heterogeneity. For each client, the sample size is around 50. In this paper, we let $a = b = 1$.

The last dataset aims to solve the general linearly constrained problem (1).

Lincons The data are generated by the same way in IID. Since in IID, all the clients share the same \mathbf{W}_k and \mathbf{b}_k , we can combine all the samples and obtain the dataset `Lincons`. Then we generate the matrix $\mathbf{A} \in \mathbb{R}^{610 \times 400}$ whose entries are independent and modeled as $\mathcal{N}(0, 1)$.

For all the three datasets, the loss function is defined as the sum of cross entropy loss and ℓ_2^2 regularization.

D.2 Parameters

For all the datasets, the mini-batch size is 4. As for the probability p_n , we reparameterize it as $p_0 n^{-\alpha\beta}$ with $p_0 < 1$. The value of α is from $\{1, 0.8, 0.6\}$ and the value of β is from $\{0, 0.2, 0.4, 0.6, 0.8\}$. For $\beta = 0$, we set $p_0 = 0.2$; for $\beta > 0$, we set $p_0 = 0.5$. And we run gradient descent 1000 steps to obtain the value of \mathbf{x}^* .

IID The parameter of ℓ_2^2 regularization is 0.005. For $\alpha = 1$, we set $\eta_0 = 200$; for $\alpha = 0.8$, we set $\eta_0 = 40$ in Appendices D.3 and D.4 and set $\eta_0 = 200$ in Appendices D.5 and D.6; for $\alpha = 0.6$, we set $\eta_0 = 20$.

Synthetic $(1, 1)$ The parameter of ℓ_2^2 regularization is 0.5. For $\alpha = 1$, we set $\eta_0 = 1$; for $\alpha = 0.8$, we set $\eta_0 = 0.3$; for $\alpha = 0.6$, we set $\eta_0 = 0.1$.

Lincons The parameter of ℓ_2^2 regularization is 0.05. For $\alpha = 1$, we set $\eta_0 = 8$; for $\alpha = 0.8$, we set $\eta_0 = 2$; for $\alpha = 0.6$, we set $\eta_0 = 0.8$.

D.3 Convergence Rates

We plot the log-log scale graphs of averaged MSEs over 5 repetitions on IID vs iterations in Figure 1 and the log-log scale graphs of averaged MSEs over 10 repetitions on IID and `Lincons` vs

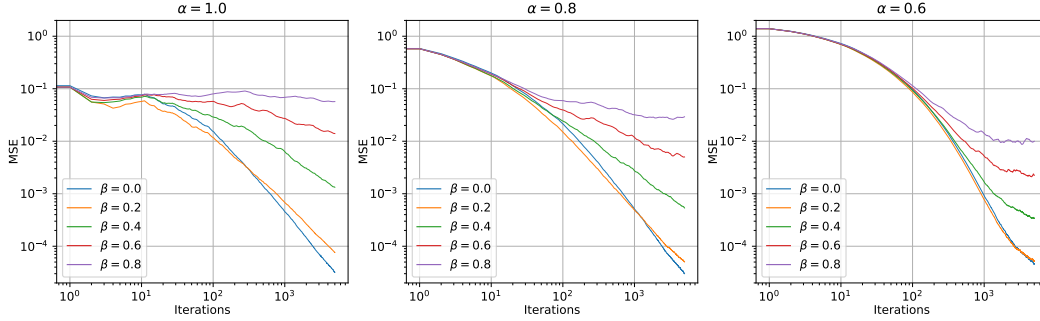


Figure 4: The log-log scale graphs of averaged MSE on Synthetic (1, 1) over 10 repetitions vs iterations.

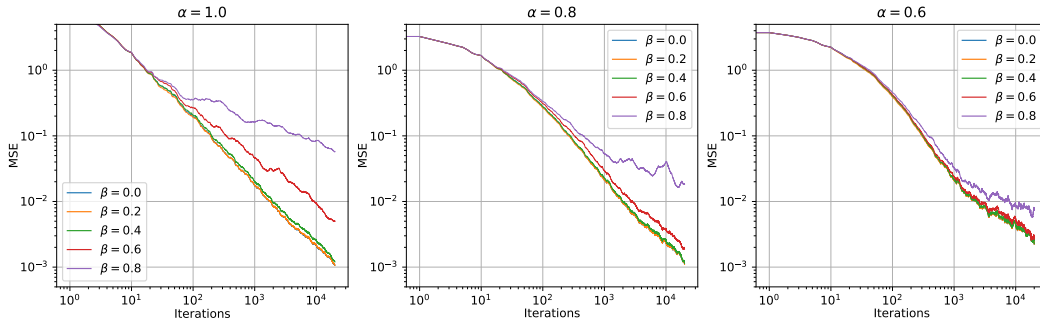


Figure 5: The log-log scale graphs of averaged MSE on Lincons over 10 repetitions vs iterations.

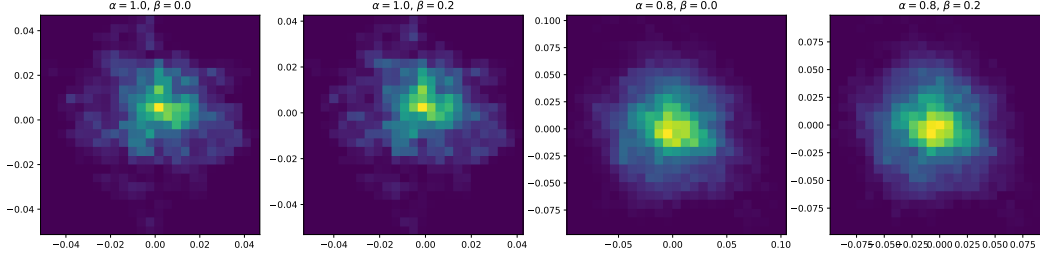


Figure 6: The heatmaps of \check{u}_n across two orthogonal directions over 100 repetition on IID.

iterations in Figures 4 and 5. When $\beta < 1/2$, the value of β hardly affects the convergence rate; when $\beta > 1/2$, both larger β and smaller α lead to a slower convergence rate. This is consistent to the result of Theorem 3.1.

D.4 Heatmaps

We plot the heatmaps for $\alpha = 1, 0.8$ and $\beta = 0, 0.2$. The results for the three datasets are shown in Figures 6, 7 and 8. For IID, we run 2000 steps of LPSA over 100 repetitions and pick up the last 200 iterates. For Synthetic (1, 1), we run 3000 steps of LPSA over 100 repetitions for $\alpha = 1$ and 4000 steps for $\alpha = 0.8$. Then we pick up the last 800 iterates to plot the heatmap. For Lincons, we run 2000 steps of LPSA over 100 repetitions and pick up the last 800 iterates. All the heatmaps show that the cells near the origin have lighter colors, which agrees with Theorem 3.3.

D.5 Trajectories

For $\alpha = 1, 0.8$ and $\beta = 0.6, 0.8$, we plot the trajectories of \check{v}_n along two random directions e_1 and e_2 vs accumulation of η_n in Figures 9, 10 and 11. Note that the directions vectors e_1 and e_2 are distinct

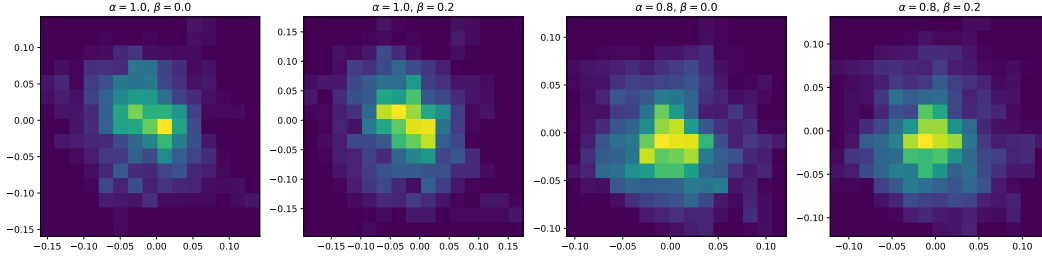


Figure 7: The heatmaps of \tilde{u}_n across two orthogonal directions over 100 repetition on Synthetic (1, 1).

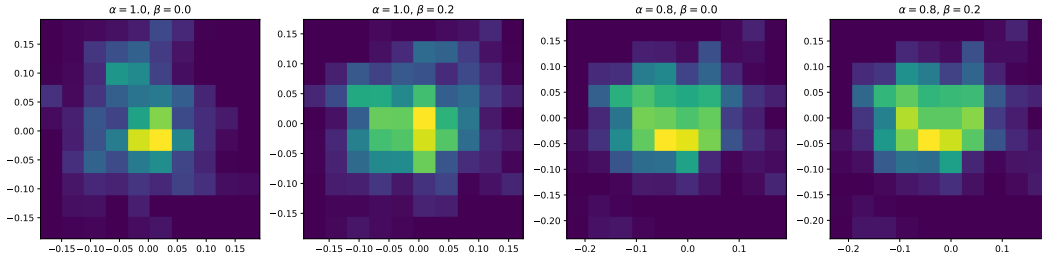


Figure 8: The heatmaps of \tilde{u}_n across two orthogonal directions over 100 repetition on Lincons.

for different datasets. The value of the horizontal coordinate is $\sum_{i=s}^n \eta_i^\beta$, where s is the start point of the trajectory that aims to eliminate the irregular behavior in the early stage of the optimization process. In Figure 9, we run 20000 steps of LPSA and set $s = 2000$; in Figure 10, we run 50000 steps of LPSA and set $s = 1000$; in Figure 11, we run 5000 steps of LPSA and set $s = 2000$.

We take Figure 10 as an example. Observe that the trajectories in Figure 10 come in a jagged manner and the peak value does not vanish or explode. This is because we have chosen a suitable rescaled version \tilde{v}_n of v_n and such a behavior can be captured by Theorem 3.4. The same discussion also applies for Figure 11. As for Figure 9, where the dimension of v_n is 61000, the rate of the weak convergence mentioned in Theorem 3.4 is much slower than the low-dimensional counterparts depicted in Figures 10 and 11, where the dimension of v_n is of hundreds or around 1000. When the number of iterations is not so large, the influence of gradient noise can not be ignored. As a result, the trajectories in Figure 9 keep fluctuating a lot and are not so smooth as those in Figures 10 and 11.

D.6 Bias

For $\alpha = 1, 0.8$ and $\beta = 0.6, 0.8$, we plot the trajectories of \hat{u}_n along two random directions e_1 and e_2 (or e_3) for three datasets in Figures 12, 13 and 14 to show the asymptotic biased of \hat{u}_n . Note that the directions vectors e_1 and e_2 are distinct for different datasets. The scale of coordinate axis in Figure 13 is different from that in Figure 3. This is due to that we omit the influence of η_0 in Figure 3, whose value does not affect the shape of the trajectories. Moreover, we choose a different direction e_3 in Figure 13 instead of e_2 in Figure 3 for a better illustration. We observe that although some trajectories have not converged yet, they stay away from the blue horizontal dashed line, which denotes the value 0. This verifies the result of Corollary 1.

D.7 Convergence Rates in terms of the Number of Projections

Recall that in Section 3.1 and Appendix D.3, we establish the convergence rates in terms of the number of iterations and provide the log-log scale graphs of averages MSEs vs. the number of iterations. To better capture the influence of projections, in this subsection, we consider the convergence rates in terms of the number of projections and plot the the log-log scale graphs of averages MSEs vs. the number of projections.

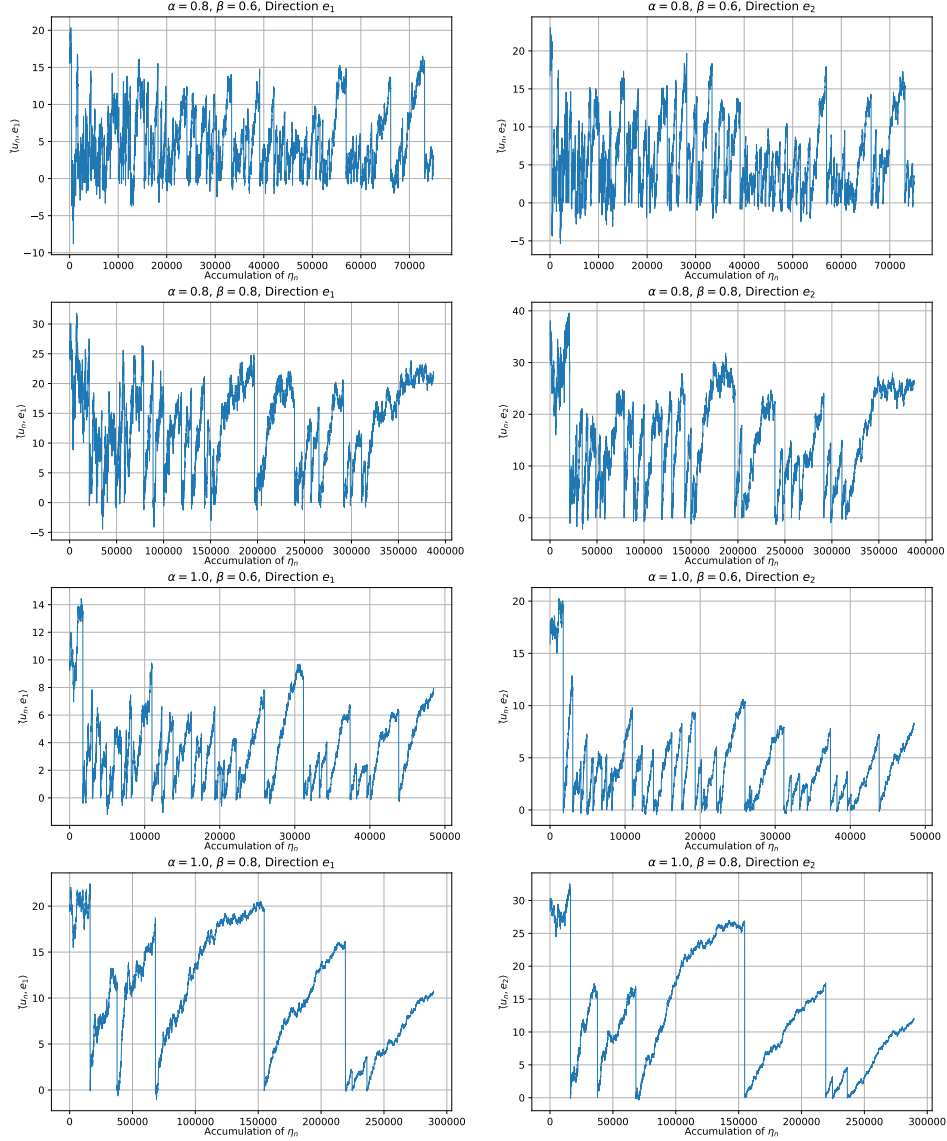


Figure 9: Trajectories of \check{v}_n along two random directions vs accumulation of η_n on IID.

In our method, at the n -th iteration, the projection probability is $p_n = \min\{\eta_n^\beta, 1\} = \Theta(n^{-\alpha\beta})$. As a result, after n steps of iterations, the number of projections m should be of the order $\Theta(n^{1-\alpha\beta})$. Suppose that after m steps of projections, we obtain the variable \mathbf{x}_m and $\mathbf{u}_m = \mathcal{P}_{\mathbf{A}^\perp}(\mathbf{x}_m)$. By Theorem 3.1, we have $\mathbb{E} \|\mathbf{u}_m - \mathbf{x}^*\|^2 = \mathcal{O}\left(m^{-\frac{\alpha \min\{1, 2-2\beta\}}{1-\alpha\beta}}\right)$. For $0 \leq \beta < 0.5$, the rate is of the order $\mathcal{O}\left(m^{-\frac{\alpha}{1-\alpha\beta}}\right)$ and a larger β leads to a faster rate. For $0.5 \leq \beta < 1$, the rate is of the order $\mathcal{O}\left(m^{-\frac{2\alpha(1-\beta)}{1-\alpha\beta}}\right) = \mathcal{O}\left(m^{-2\left(1-\frac{1-\alpha}{1-\alpha\beta}\right)}\right)$ and a larger β leads to a slower rate.

To conclude, if we only focus on the complexity of projection steps and ignore the cost of gradient computation, $\beta = 0.5$ is the best choice.

Then we plot the log-log scale graphs of averages MSEs vs. the number of projections on two datasets IID and Lincons over 5 repetitions in Figures 15 and 16.

For IID, the value of α is from $\{1.0, 0.8, 0.6\}$ and the value of β is from $\{0, 0.2, 0.4, 0.5, 0.6\}$. When $\beta = 0, 0.2$, we run 10000 steps pf LPSA; when $(\alpha, \beta) = (0.6, 0.4)$, we run 20000 steps pf LPSA;

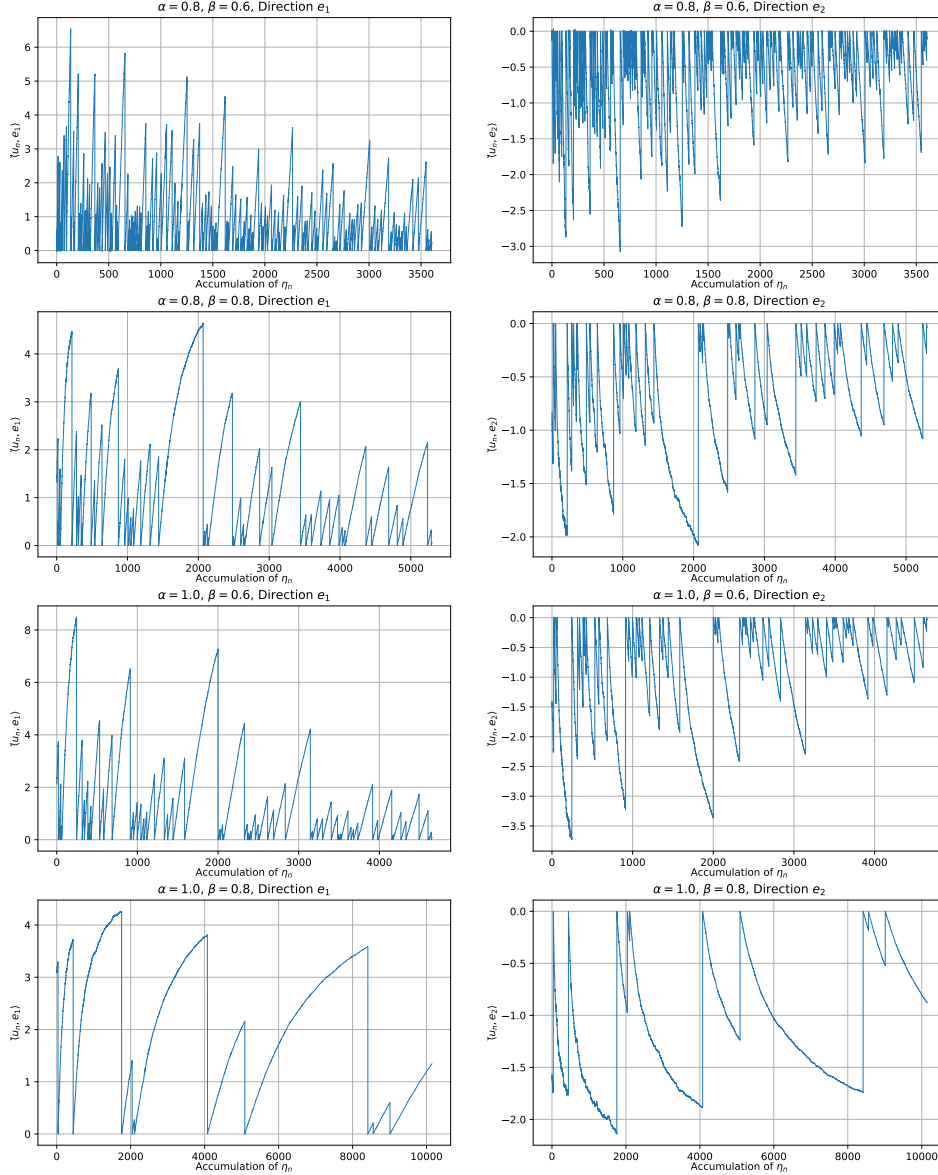


Figure 10: Trajectories of \tilde{v}_n along two random directions vs accumulation of η_n on Synthetic (1, 1).

when $(\alpha, \beta) = (0.8, 0.4)$, we run 30000 steps pf LPSA; when $\beta = 0.5, 0.6$ or $(\alpha, \beta) = (1.0, 0.4)$, we run 50000 steps pf LPSA.

For Lincons, the value of α is from $\{1.0, 0.8, 0.6\}$ and the value of β is from $\{0, 0.2, 0.4, 0.6, 0.8\}$. When $\beta = 0, 0.2$, we run 10000 steps pf LPSA; when $\beta = 0.4$ or $(\alpha, \beta) = (0.6, 0.6)$, we run 50000 steps pf LPSA; when $(\alpha, \beta) = (1.0, 0.6), (0.8, 0.6)$, we run 100000 steps pf LPSA; when $(\alpha, \beta) = (0.6, 0.8)$, we run 500000 steps pf LPSA; when $(\alpha, \beta) = (1.0, 0.8), (1.0, 0.6)$, we run 1000000 steps pf LPSA.

We find that in both Figures 15 and 16, when β is closer to 0.5, the lines of convergence rates are steeper. This is consistent with our analysis above. It is worth noting that for a fixed number of iterations, a larger β implies a smaller number of projections. As a result, for β larger than 0.5, the interval between two adjacent projections is pretty large and to get a target number of projections (e.g., 1000), the number of iterations can be undesirable. To reduce the computational cost, we take a predetermined number of iterations, so the lines corresponding the larger β can be shorter than others.

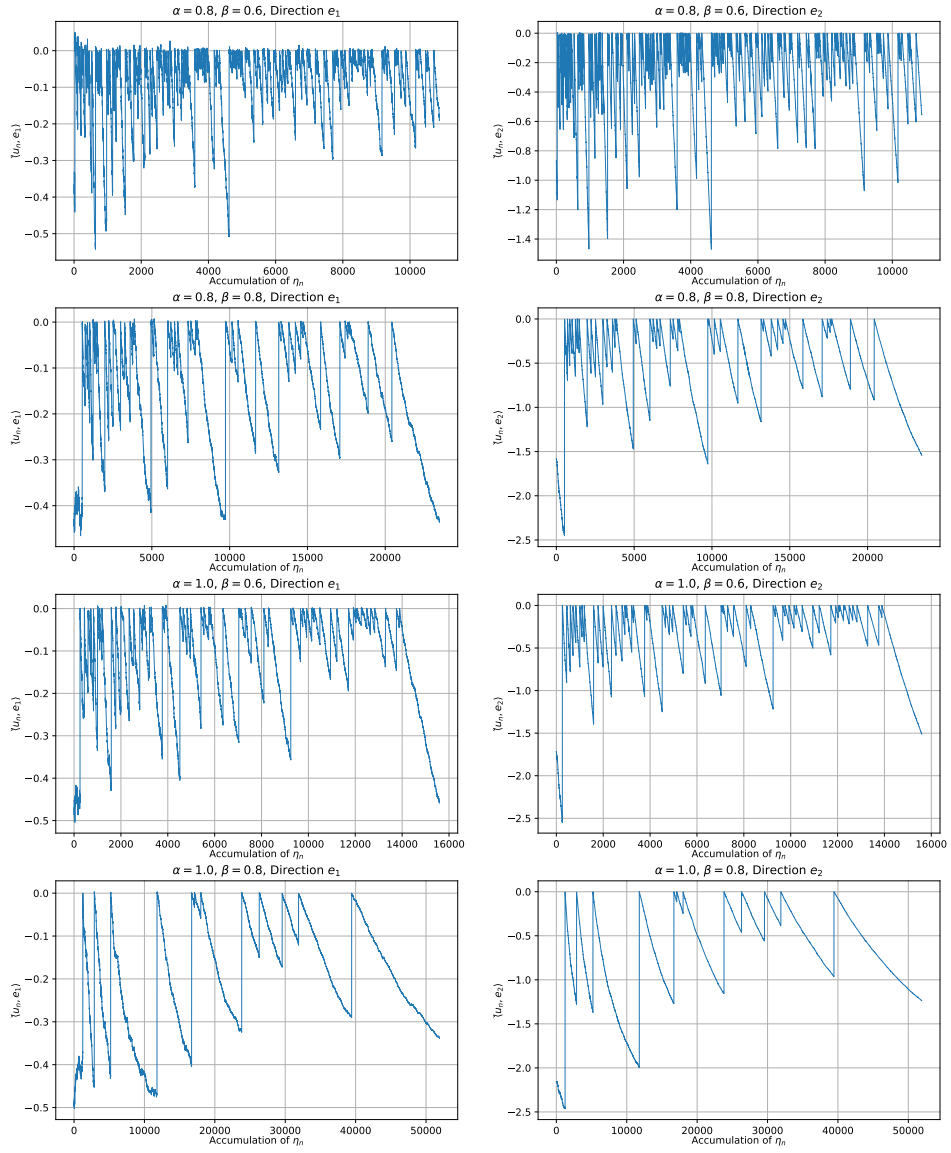


Figure 11: Trajectories of \tilde{v}_n along two random directions vs accumulation of η_n on Lincons.

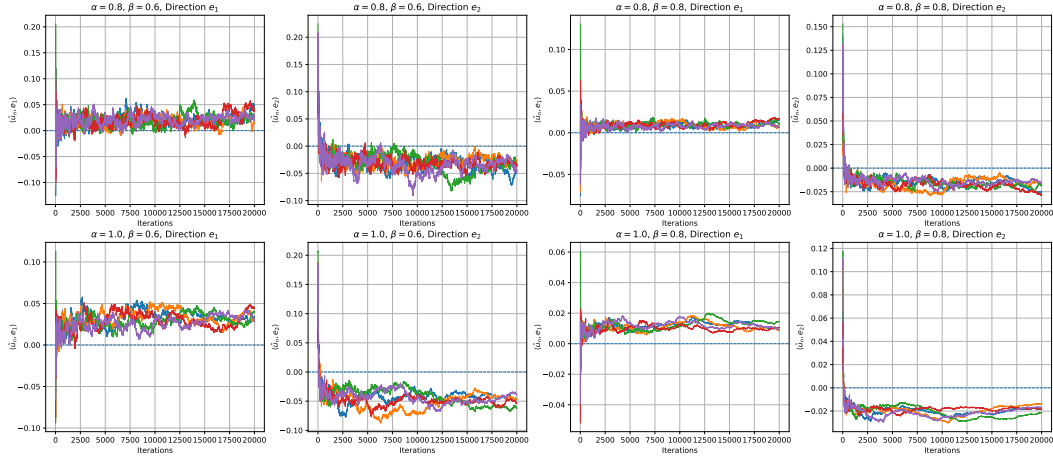


Figure 12: Trajectories of \hat{u}_n along two random directions over 5 repetitions on IID.

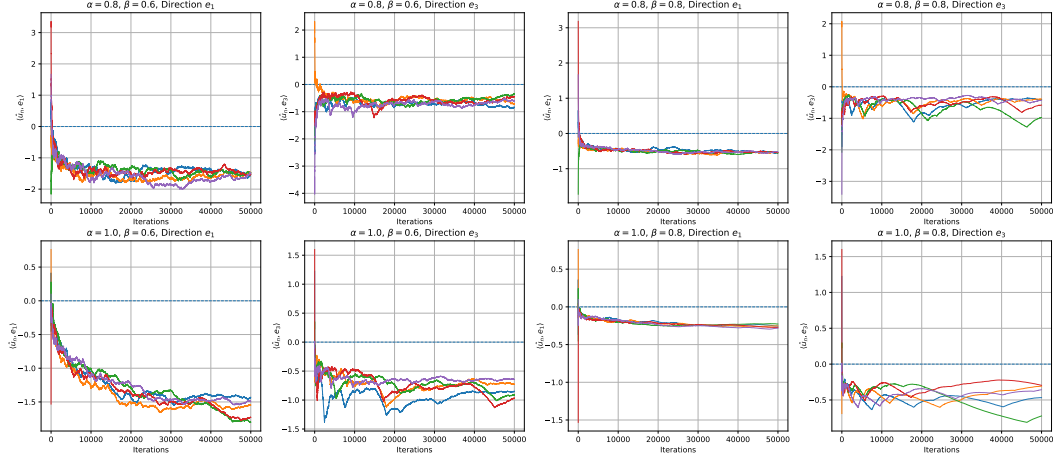


Figure 13: Trajectories of \hat{u}_n along two random directions over 5 repetitions on Synthetic (1, 1).

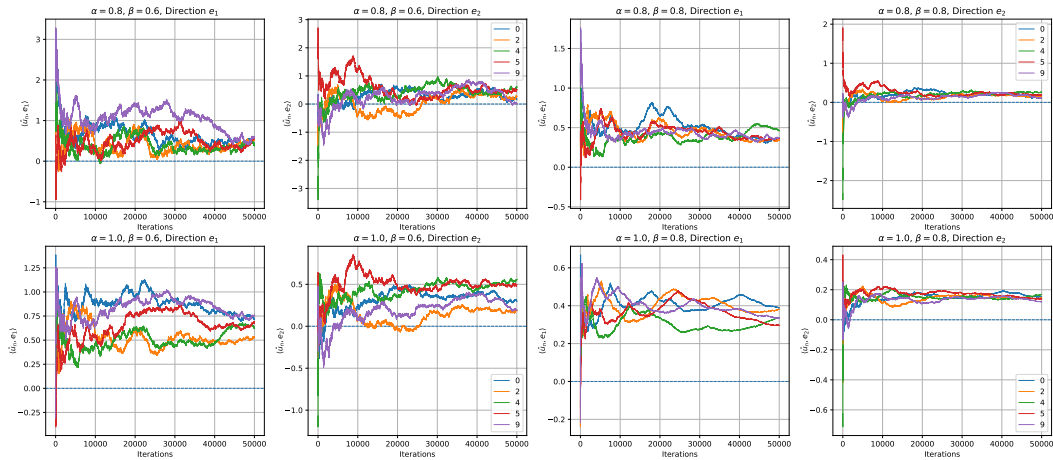


Figure 14: Trajectories of \hat{u}_n along two random directions over 5 repetitions on Lincons.

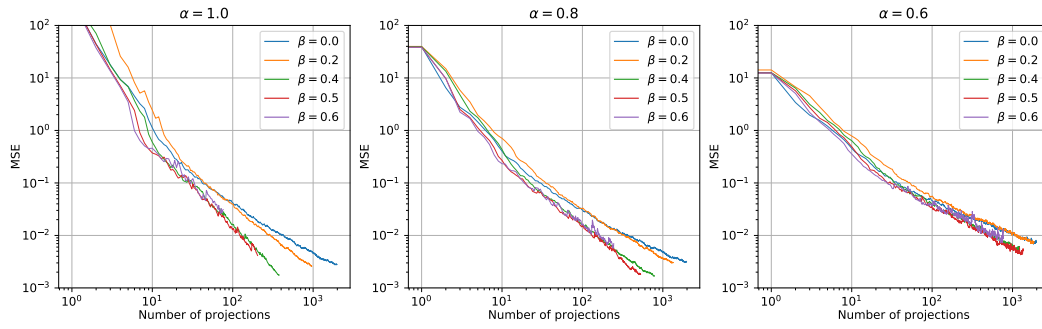


Figure 15: The log-log scale graphs of averaged MSE over 5 repetitions on IID vs. the number of projections.

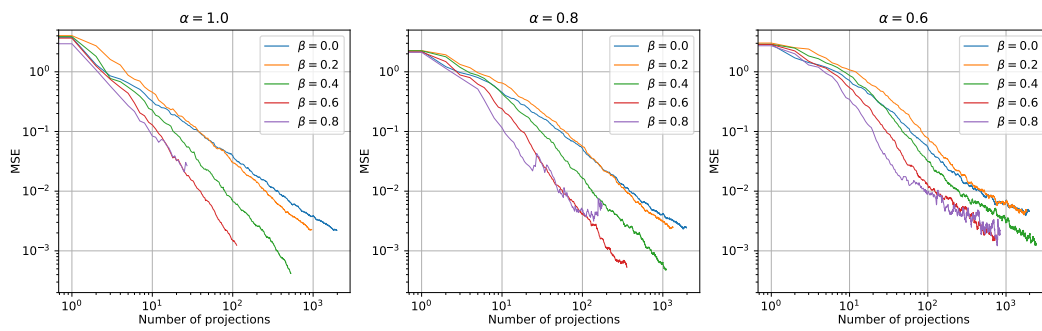


Figure 16: The log-log scale graphs of averaged MSE over 5 repetitions on Lincons vs. the number of projections.